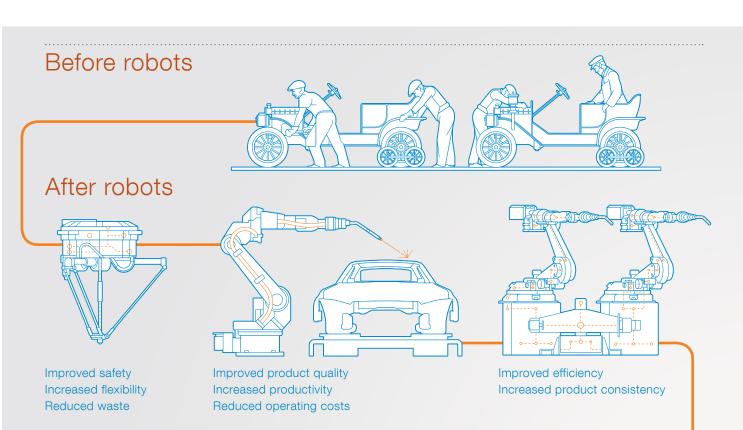
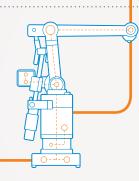


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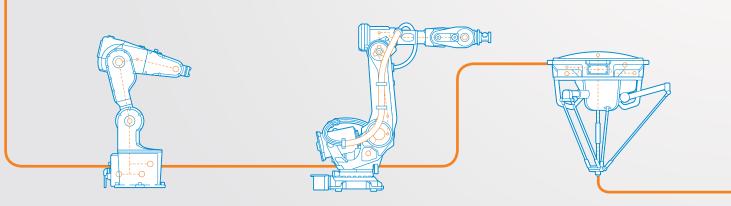


In 1974, the IRB 6 was the start of it all: The world's first microprocessor controlled, electrically-driven industrial robot became commercially available.



Becoming more useful

Over time, we have developed robots for more and more industries and purposes, bringing the benefits of robots to anyone who needs them.



Small robots

For the delicate, fast and flexible tasks

Palletizing robots

For when you have to load a pallet as quickly and accurately as possible

Large heavy duty robots

For those applications that require the ultimate in strength and reach

Welding robots

For reaching those hard to reach spaces and delivering a quality weld every time.

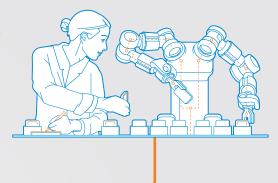
IRB 360 Flexpicker™

For high speed picking and packing

Now - becoming collaborative

YuMi® is the world's first truly collaborative robot, and represents the ultimate in what collaborative robots stand for.

- Inherent safety makes it possible to operate without safety fencing
- Human proportioned, for natural co-working with people and the ability to fit into existing human-sized spaces
- Meant for small parts assembly



Becoming smarter

With advances in hardware, we have delivered technology that can sense its surroundings and work more efficiently.

Integrated Vision

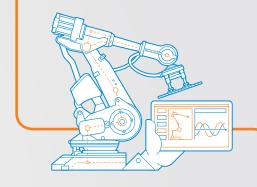
The gift of sight is just as good for a robot

Integrated Force Control

Know where the workpiece is and how hard to push for the perfect finish

Superior motion control

Getting from point A to point B efficiently and quickly makes all the difference



RobotWare

The underlying brains of the robot for easy optimization and high flexibility

Becoming easier

Making smart robots for many uses is only half the story, the rest comes down to making implementation as easy as possible.

Function packages

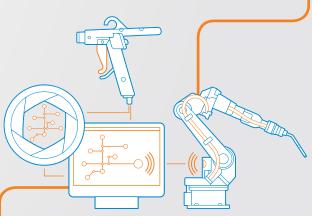
Standardized components and design make for quick startup and reduced costs.

RobotStudio®

Powerful PC-based programming makes it easier than ever to program complex robotic operations.

PowerPacs

Plug-ins for RobotStudio that make programming for specific industries a matter of plug-and-play.



Simplified Robot Programming

A revolution in turning manual motions into robotic paint programs.

Customer Service Securing your productivity. Anytime. Anywhere.

ABB Robotics' global service presence is unmatched with more than 100 service locations spread across 53 countries. More than 1,300 dedicated specialists are on hand to provide service and support for you and your robots 24 hours a day, seven days a week, 365 days a year. Anytime and anywhere you need us. ABB will be there.



Service agreements

We have built in full flexibility into our service agreements, where you make your own choices from a variety of available services. With increased availability and better performance from your installation, you can be sure to keep your operations well within budget.

With a service agreement from ABB, unplanned stops are reduced to a minimum, and when they do happen, ABB can deliver a response within minutes, via our optional Remote Service solution. We take care of your robots, so you can take care of your business.

Installation and commissioning

Installation and commissioning of ABB products and systems is one of our core competencies. Our simulation tool, RobotStudio®, helps reduce installation, commissioning and start-up time. With the help of RobotStudio we provide high-performance programs that deliver benefits throughout the entire robot life cycle.

We offer commissioning engineers with extensive experience in robots and robot systems. Their know-how, backed by the expertise of our design team, makes commissioning fast and smooth and lays the foundation for reliable and efficient operation.



Replacements

Replacing existing equipment with a new ABB robot arm or controller is an alternative to a completely new installation. ABB provides fast and reliable solutions when your robot controller or robot arm needs to be replaced, or when you prefer to harmonize your installed systems. Replacements are provided with proper preparation, pre-programming and program simulation.

ABB has developed unique and innovative new technologies for backward compatibility, such as stand-alone control systems to run previous robot model generations. Replacement can also be performed on process equipment like welding guns and atomizers.

Spares and consumables

As your global supplier of original high-quality new, exchange, repair and spare parts kits, we are by your side ready to deliver the right part, at the right time, in the right place.

All deliveries are possible, whether you need economy, express or emergency shipment. If you need spare parts in-house, we can provide package deals and support to recommend which parts to have locally based on your needs. We maintain parts availability 8–10 years after the end of robot series production. Through our robot database, we keep track of each part installed – enabling fast part identification and delivery.

Extensions, upgrades and retrofits

An ABB robot's life cycle not seldom exceeds 20 years. Life cycles can be prolonged through upgrades and retrofits. Product upgrades are designed to improve performance and extend both the functionality and the lifetime of the product, thereby providing the best possible return on investment by phased migration to the latest technology. It is an attractive alternative to keeping other parameters of the production unit versus making additional investments.

Robot equipment that is at the end of its life cycle can be replaced by retrofits, leading to improvements in reliability, safety and ultimately performance.

Training

To use your robots in a safe way and to their full potential it is important to keep your personnel up-to-date on the latest technology developments. We offer your employees specialized training at more than 50 locations worldwide – training that helps reduce production costs and exploit the full potential of your robot systems.

Our training courses include standard robot training modules, process and applications courses and systems training. Customized training can also be provided to students on site, in an external training facility, or through e-learnings and webinars.

Maintenance

Scheduled preventive maintenance reduces the likelihood of a failure or component deterioration. Maintenance is carried out regularly or based on the condition of the robot. Preventive maintenance consists of regular inspections and maintenance plus predefined component replacements.

Monitoring robot health with ABB's wireless Remote Service increases robot uptime and productivity while reducing the cost of ownership. We offer appropriate maintenance paths to upgrade equipment reliability based on a service assessment performed by our service experts on-site.

Repairs

ABB technical support is there for you, answering anything from a quick technical question up to advanced product and application support, or to request services via telephone, e-mail or via web inquiry. With ABB's patented wireless Remote Service troubleshooting tools we can provide a dedicated expert, virtually on site within 5 minutes for remote support in the event of a specific problem or failure.

ABB robot specialists are on call worldwide to assist you in a matter of hours, avoiding costly production losses. ABB supports different maintenance strategies. In case you opt to focus on corrective repairs, rather than preventive, ABB is there for you to restore your robot.

IRB 120

IRB 120 and IRB 120T



Main applications		
Assembly	Load (kg)	3
Machine Tending	Reach (m)	0.58
Material Handling	Protection available	Std: IP30. Option: Cleanroom class 5, certified by IPA
Packing/Dispensing	Mounting	Floor, wall, inverted and any tilted angle
	Position repeatability (RP)(mm)	0.01



Certified by IPA

IRB 1200

IRB 1200-5/0.9 and IRB 1200-7/0.7



)./				
	Main applications		IRB 1200-5/0.9	IRB 1200-7/0.7
	Machine Tending	Load (kg)	5	7
	Material Handling	Reach (m)	0.90	0.70
		Protection available	Std: IP40. Option: IP67	IP40. Option: IP67
		Mounting	Any angle	Any angle
		Position repeatability (RP)(mm)	0.025	0.02



IRB 140 and IRB 140T



Main applications		
Arc Welding	Load (kg)	6
Assembly	Reach (m)	0.81
Cleaning/Spraying	Protection available	Std: IP67. Option: Cleanroom class 6, certified by IPA,
Deburring		Foundry Plus, SteamWash
Machine Tending	Mounting	Floor, wall, inverted and any tilted angle
Material Handling	Position repeatability (RP)(mm)	0.03
Packing		



Certified by IPA

IRB 1410

IRB 1410



Main applications		
Arc Welding	Load (kg)	5
	Reach (m)	1.44
	Protection available	-
	Mounting	Floor
	Position repeatability (RP)(mm)	0.02



IRB 1500

IRB 1500ID



Main applications		
Arc Welding	Load (kg)	4
	Reach (m)	1.50
	Protection available	Std. IP40
	Mounting	Floor, inverted
	Position repeatability (RP)(mm)	0.05



IRB 1600

IRB 1600-6/1.2 and IRB 1600-10/1.2



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Main applications		IRB 1600-6/1.2	IRB 1600-10/1.2
Arc Welding	Load (kg)	6	10
Assembly	Reach (m)	1.20	1.20
Cleaning/Spraying	Protection available	Std: IP54. Option: IP67 wit	h Foundry Plus 2
Extraction	Mounting	Floor, wall, tilted, inverted,	shelf
Machine Tending	Position repeatability (RP)(mm)	0.02	0.02
Material Handling			
Packing			

IRB 1600

IRB 1600-6/1.45 and IRB 1600-10/1.45



1.45	4	3	
Main applications		IRB 1600-6/1.45	IRB 1600-10/1.45
Arc Welding	Load (kg)	6	10
Assembly	Reach (m)	1.45	1.45
Cleaning/Spraying	Protection available	Std: IP54. Option: IP67	with Foundry Plus 2
Cutting	Mounting	Floor, wall, tilted, invert	ed, shelf
Extraction	Position repeatability (RP)(mm)	0.02	0.05
Machine Tending			
Material Handling			
Packing			

IRB 1600

IRB 1600ID



Main applications		
Arc Welding	Load (kg)	4
	Reach (m)	1.50
	Protection available	Std: IP40
	Mounting	Floor, inverted, tilted
	Position repeatability (RP)(mm)	0.02

IRB 2400

IRB 2400-10/16



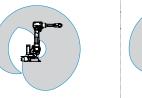
Main applications		
Cutting/Deburring	Load (kg)	12/20
Grinding/Polishing	Reach (m)	1.55
	Protection available	Std: IP54. Option: IP67 with Foundry Plus 2
	Mounting	Floor, inverted
	Position repeatability (RP)(mm)	0.03

IRB 2600

IRB 2600-12/1.65 and IRB 2600-20/1.65



71.00			
Main applications		IRB 2600-12/1.65	IRB 2600-20/1.65
Arc Welding	Load (kg)	12	20
Assembly	Reach (m)	1.65	1.65
Cutting	Protection available	Standard: IP67. Option:	Foundry Plus 2
Dispensing	Mounting	Floor, wall, tilted, inverte	ed, shelf
Machine Tending	Position repeatability (RP)(mm)	0.04	0.04
Material Handling			
Material Handling			





IRB 2600

IRB 2600-12/1.85



Main applications		
Arc Welding	Load (kg)	12
Assembly	Reach (m)	1.85
Cutting	Protection available	Standard: IP67. Option: Foundry Plus 2
Dispensing	Mounting	Floor, wall, tilted, inverted, shelf
Machine Tending	Position repeatability (RP)(mm)	0.04
Material Handling		

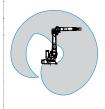


IRB 2600

IRB 2600ID-8/2.00



Main applications		
Arc Welding	Load (kg)	8
Dispensing	Reach (m)	2.00
Machine Tending	Protection available	Standard: IP67 (base, lower arm, wrist), IP54 (axis 4)
Material Handling	Mounting	Floor, wall, tilted, inverted, shelf
	Position repeatability (RP)(mm)	0.02

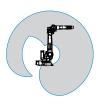


IRB 2600

IRB 2600-15/1.85



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Main applications		
Arc Welding	Load (kg)	15
Assembly	Reach (m)	1.85
Dispensing	Protection available	Std: IP67 (base, lower arm and wrist), IP54 (axis 4)
Machine Tending	Mounting	Floor, wall, tilted, inverted, shelf
Material Handling	Position repeatability (RP)(mm)	0.03

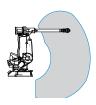


IRB 4400

IRB 4400/L10



	Main applications		
	Cutting/Deburring	Load (kg)	10
	Die Spraying	Reach (m)	2.55
	Dispensing	Protection available	Std: IP54. option: IP67, Foundry Plus
	Grinding/Polishing	Mounting	Floor
		Position repeatability (RP)(mm)	0.05

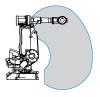


IRB 4400

IRB 4400/60



Main applications		
Cutting/Deburring	Load (kg)	60
Dispensing	Reach (m)	1.96
Grinding/Polishing	Protection available	Std: IP54. Option: IP67, steam washable - Foundry Plus
	Mounting	Floor
	Position repeatability (RP)(mm)	0.19



IRB 4600

IRB 4600-20/2.50



Main applications		
Arc Welding	Load (kg)	20
Assembly	Reach (m)	2.50
Dispensing	Protection available	Std: IP67. Option: Foundry Plus 2
Laser Welding	Mounting	Floor, tilted, inverted, shelf
Machine Tending	Position repeatability (RP)(mm)	0.05
Material Handling		
Measuring		
Packing/Palletizing		(Steers)
Press brake tending		

IRB 4600

IRB 4600-40/2.55



Main applications		
Assembly	Load (kg)	40
Dispensing	Reach (m)	2.55
Extraction	Protection available	Std: IP67. Option: Foundry Plus 2
Laser Welding	Mounting	Floor, tilted, inverted, shelf
Machine Tending	Position repeatability (RP)(mm)	0.06
Material Handling		
Measuring		
Packing/Palletizing		

IRB 4600

IRB 4600-45/2.05 and IRB 4600-60/2.05



Main applications		4600-45/2.05	4600-60/2.05	
Assembly	Load (kg)	45	60	
Deburring	Reach (m)	2.05	2.05	
Dispensing	Protection available	Std: IP67. Option: Foundry I	Plus 2, Foundry Prime 2	
Extraction		(valid for 60 kg variant)		
Machine Tending	Mounting	Floor, tilted, inverted, shelf	Floor, tilted, inverted, shelf	
Material Handling	Position repeatability (RP)(mm)	0.05	0.06	
Measuring				
Packing/Palletizing				

IRB 6620

IRB 6620



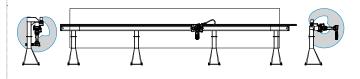
Main applications		
Assembly	Load (kg)	150
Cleaning/Spraying	Reach (m)	2.20
Cutting/Deburring	Protection available	IP54, IP67, Foundry Plus 2 High preassure steam washable
Dispensing	Mounting	Floor, tilted, inverted
Grinding/Polishing	Position repeatability (RP)(mm)	0.03
Machine Tending		
Material Handling	under	
Packing/Palletizing		
Press Brake Tending		
Spot Welding	•	

IRB 6620

IRB 6620LX



Main applications		
Machine Tending	Load (kg)	150
Material Handling	Reach (m)	1.90
Powertrain Assembly	Protection available	5-axis robot arm: Std IP54. Option: Foundry Plus 2 IP67
Grinding/Polishing		Std: IP66 (linear axis).
	Mounting	Wall, inverted
	Position repeatability (RP)(mm)	0.05

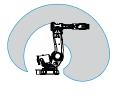


IRB 6640

IRB 6640-235/2.55



Main applications		
Cutting/Deburring	Load (kg)	235
Grinding/Polishing	Reach (m)	2.55
Machine Tending	Protection available	Std: Option: Foundry Prime 2
Material Handling	Mounting	Floor
	Position repeatability (RP)(mm)	0.05

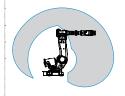


IRB 6640

IRB 6640-185/2.8



···	·	Ā
Main applications		
Cutting/Deburring	Load (kg)	185
Grinding/Polishing	Reach (m)	2.80
Machine Tending	Protection available	Std: Option: Foundry Prime 2
Material Handling	Mounting	Floor
Spot Welding	Position repeatability (RP)(mm)	0.05



IRB 6650

IRB 6650S-90/3.9, IRB 6650S-125/3.5 and IRB 6650S-200/3.0



Main applications		IRB 6650S-90/3.9	IRB 6650S-125/3.5	IRB 6650S-200/3.0
Assembly	Load (kg)	90	125	200
Material Handling	Reach (m)	3.90	3.50	3.00
Packing	Protection available	Std: IP67. Option: I	Foundry Plus 2,	
		High preassure stea	am washable	
Picking	Mounting	Shelf	Shelf	Shelf
	Position repeatability (RP)(mm)	n.a.	0.13	0.14

IRB 6660

IRB 6660-100/3.3 and IRB 6660-130/3.1



IRB 6660

IRB 6660-205/1.9



	Main applications		
	Cutting	Load (kg)	205
	Grinding	Reach (m)	1.90
	Machining	Protection available	Std: IP67. Option: Foundry Plus 2, incl Chip Protection
	Milling	Mounting	Floor
	Sawing	Position repeatability (RP)(mm)	0.07
	1	T	

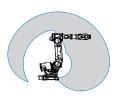


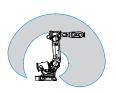
IRB 6700

IRB 6700-155/2.85 and IRB 6700-200/2.60



Main applications		IRB 6700-155/2.85	IRB 6700-200/2.60
Cutting/Deburring	Load (kg)	155	200
Grinding/Polishing	Reach (m)	2.85	2.60
Machine Tending	Protection available	Std: IP67. Option: Foundry	Plus 2
Material Handling	Mounting	Floor	Floor
Spot Welding	Position repeatability (RP)(mm)	0.10	0.10
-	<u> </u>	1.00.	1.001





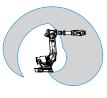
LeanID option, see page 17

IRB 6700

IRB 6700-175/3.05



Main applications		
Assembly	Load (kg)	175
Cutting/Deburring	Reach (m)	3.05
Grinding/Polishing	Protection available	Std: IP67. Option: Foundry Plus 2
Machine Tending	Mounting	Floor
Material Handling	Position repeatability (RP)(mm)	0.10
Spraying		
•	7	



LeanID option, see page 17

IRB 6700

IRB 6700-150/3.20, IRB 6700-205/2.80 and IRB 6700-235/2.65



Main applications		IRB 6700-150/3.20	IRB 6700-205/2.80	IRB 6700-235/2.65
Cutting/Deburring	Load (kg)	150	205	235
Grinding/Polishing	Reach (m)	3.20	2.80	2.65
Machine Tending	Protection available	Std: IP67. Option:	Foundry Plus 2	
Material Handling	Mounting	Floor	Floor	Floor
Spot Welding	Position repeatability (RP)(mm)	0.10	0.10	0.10
			•	





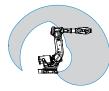


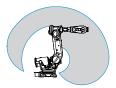
IRB 6700

IRB 6700-245/3.00 and IRB 6700-300/2.70



J	00/2.70			
	Main applicationss		IRB 6700-245/3.00	IRB 6700-300/2.70
	Assembly	Load (kg)	245	300
	Cutting/Deburring	Reach (m)	3.00	2.70
	Grinding/Polishing	Protection available	Std: IP67. Option: Foundry	Plus 2
	Machine Tending	Mounting	Floor	Floor
	Material Handling	Position repeatability (RP)(mm)	0.10	0.10





IRB 6700

IRB 6700 LeanID



LeanID is a special option for IRB 6700 with the DressPack partly integrated into the robot's upper arm. LeanID is intended for production with many complex wrist movements and where the need for flexibility in changing products is high. For LeanID payload decreases. See production specification for more details.

IRB 7600

IRB 7600-325/3.1, IRB 7600-340/2.8



Ö	A		
Main applications		IRB 7600-325/3.1	IRB 7600-340/2.8
Assembly	Load (kg)	325	340
Cutting/Deburring	Reach (m)	3.10	2.80
Grinding/Polishing	Protection available	Std: IP67. Option: Foun	dry Plus 2
Machine Tending	Mounting	Floor	Floor
Material Handling	Position repeatability (RP)(mm)	0.10	0.27
Press Brake Tending			
Spot Welding			Territoria de la constanta de





IRB 7600

IRB 7600-400/2.55 and IRB 7600-500/2.55



Assembly Load (kg) 400 500 Cutting/Deburring Reach (m) 2.55 2.55 Grinding/Polishing Protection available Std: IP67. Option: Foundry Plus 2 Machine Tending Mounting Floor Floor Material Handling Position repeatability (RP)(mm) 0.19 0.08 Press Brake Tending Spot Welding	00/2.55			
Cutting/Deburring Reach (m) 2.55 2.55 Grinding/Polishing Protection available Std: IP67. Option: Foundry Plus 2 Machine Tending Mounting Floor Floor Material Handling Position repeatability (RP)(mm) 0.19 0.08 Press Brake Tending	Main applications		IRB 7600-400/2.55	IRB 7600-500/2.55
Grinding/Polishing Protection available Std: IP67. Option: Foundry Plus 2 Machine Tending Mounting Floor Floor Material Handling Position repeatability (RP)(mm) 0.19 0.08 Press Brake Tending	Assembly	Load (kg)	400	500
Machine Tending Mounting Floor Floor Material Handling Position repeatability (RP)(mm) 0.19 0.08 Press Brake Tending 0.08	Cutting/Deburring	Reach (m)	2.55	2.55
Material Handling Position repeatability (RP)(mm) 0.19 0.08 Press Brake Tending	Grinding/Polishing	Protection available	Std: IP67. Option: Foun	dry Plus 2
Press Brake Tending	Machine Tending	Mounting	Floor	Floor
	Material Handling	Position repeatability (RP)(mm)	0.19	0.08
Spot Welding	Press Brake Tending			
	Spot Welding			





IRB 7600

IRB 7600-150/3.50



Main applications		
Assembly	Load (kg)	150
Cutting/Deburring	Reach (m)	3.50
Grinding/Polishing	Protection available	Std: IP67. Option: Foundry Plus 2
Machine Tending	Mounting	Floor
Material Handling	Position repeatability (RP)(mm)	0.19
Press Brake Tending		



IRB 260

IRB 260-30/1.5



Main applications		
Packing	Load (kg)	30
	Reach (m)	1.53
	Protection available	Std: IP67
	Mounting	Floor
	Position repeatability (RP)(mm)	0.03

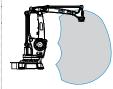


IRB 460

IRB 460-110/2.4



Main applications		
Depalletizing	Load (kg)	110
Material Handling	Reach (m)	2.40
Palletizing	Protection available	Std: IP67
	Mounting	Floor
	Position repeatability (RP)(mm)	0.20



IRB 660

IRB 660-180/3.15 and IRB 660-250/3.15



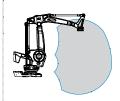
/3.15		·	
Main applications			
Material Handling	Load (kg)	180	250
Palletizing	Reach (m)	3.15	3.15
	Protection available	Std: IP67	Std: IP67
	Mounting	Floor	Floor
	Position repeatability (RP)(mm)	0.05	0.05

IRB 760

IRB 760-450/3.2



Main applications		
Depalletizing	Load (kg)	450
Full Layer Palletizing	Reach (m)	3.18
Material Handling	Protection available	Std: IP67
Palletizing	Mounting	Floor
	Position repeatability (RP)(mm)	0.05



IRB 360

IRB 360-1/1130 and IRB 360-3/1130



, ,			
Main applications		IRB 360-1/1130	IRB 360-3/1600
Assembly	Load (kg)	1	3
Material Handling	Reach (m)	1.13	1.13
Packing	Protection available	Std: IP54/67/IP69K. Option: Wash down, Stainless Clea	
	distribution of the control of the c	ISO class 5-7, IRB 360-1	/1130 certified by IPA
Picking	Position repeatability (RP)(mm)	0.10	0.10

IRB 360-1/1130 certified by IPA

IRB 360

IRB 360-8/1130, IRB 360-1/1600 and IRB 360-6/1600



Main applications		IRB 360-8/1130	IRB 360-1/1600	IRB 360-6/1600
Assembly	Load (kg)	8	1	6
Material Handling	Reach (m)	1.13	1.60	1.60
Packing	Protection available	Std: IP54.	•	
	Annual Control of the	Option: Clean roor	n ISO class 5-7 (for	IRB 360-1/1600)
Picking	Position repeatability (RP)(mm)	0.10	0.10	0.10

Protection levels IRB 360-8/1130

IP classification

ABB uses IP classification to ensure that you select the right robot for the job. A clearly defined standard helps users ensure work place safety, correct assessment of life expectancy and high productivity when investing in a robot. Robots are often asked to work in harsh environments, putting greater demand on their ability to withstand harmful substances from penetrating the mechanics.

IP stands for Ingress Protection and is combined with a numerical code that shows how well the electrical compartments of a machine are protected against ingress of solid particles/dust or water from the surrounding environment. The first figure of the two digit code specifies the level of protection against solid particles/dust, and the second, the ingress of water. The higher the figure the greater the protection.

Further protection classifications:

For specific applications, ABB uses other classifications of protection targeting the specific environment and conditions which the robot is exposed to.

Foundry Plus 2 – for harsh environments and exposure to spray of coolants, lubricants and metal spits. Typical applications are part extraction of die casting machines and cast cleaning.

Foundry Prime 2 – for very harsh environments and exposure to solvent-based detergents and indirect spray from jet pressure. Typical for washing applications such as water jet cleaning of castings and machined parts.

Chip protection – for applications such as Deburring, Sawing and Milling. It ensures that metal chips created during operation do not collect on the robot.

Clean room – international standard to ensure that robot components do not contaminate the sensitive products being handled inside the clean room.

Wash-down and stainless wash-down – robots that are designed for industrial cleaning including hip IP protection level and cavity free design with smooth surfaces that allows water and detergents to rinse off easily.





 $1. \ Servo \ hand \ and \ one \ pneumatic, \ with \ camera \ | \ 2. \ Servo \ hand \ and \ two \ pneumatics \ with \ status \ lights$

YuMi®

IRB 14000-0.5/0.5



Main applications		
Small parts material	Load (kg)	0.5
handling	Reach (m)	0.50
Small parts assembly	Protection available	Std: IP30
	Mounting	Table, bench
	Position repeatability (RP)(mm)	0.02
	Functional saftey	PL b Cat B



Small parts storage, feeding and presentation

FlexFeeder™



Main applications		FlexFeeder-Single	FlexFeeder-Double
Small parts	Max. Feature Dimension	< 25	< 30
presentation 3D to 2D	Min. Feature Dimension	> 0.50	> 0.50
Storage and	Product Weight	<= 0.1	<= 0.1
handling of parts	Feeder Weight	27	40
For intergation with	Feeder Dimension (mm)	754x737x125	754x737x230
2D vision	Illumination area	90x160	200x160
	dimension (mm)		

Grippers

Small Parts Modular servo gripper



Main applications		
Small parts assembly	Weight (g)	215 – 280 depending on configuration
Options	Load (g)	Up to 285
Five possible	Finger stroke (mm)	50
configurations	Protection	Std: IP30
using function modules	Mounting	YuMi toolflange
Function modules	Position repeatability	0.05
Servo gripper (default)	(servo gripper) (mm)	
1-2 pneumatic	Vacuum spec. (bar)	Input max 6, Vacuum max 0.050
units (option)		
Integrated Vision		
(option) via		
1.3 MP camera		

Controllers

IRC5 Single cabinet controller and Drive module



	Single cabinet	Drive module
Size H x W x D (mm)	970 x 725 x 710	720 x 725 x 710
Electrical connections	200–600 V, 50–60 Hz	200–600 V, 50–60 Hz
Protection	Std: IP54 (IP33 in rear compartment)	Std. IP54 (IP33 in rear compartment)
IRB Support	All robots	All robots

Based on advanced dynamic modelling, the IRC5 optimizes the performance of the robot for the physically shortest possible cycle time (QuickMove™) and precise path accuracy (TrueMove™). What you program is what you get.

IRC5 Compact controller



Size H x W x D (mm)	310 x 449 x 442
Electrical connections	220-230 V, 50-60 Hz, single phase
Protection	Std: IP20
IRB Support	IRB 120, IRB 140, IRB 260, IRB 360, IRB 1200, IRB 1410, IRB 1600

IRC5 Panel mounted controller



Control module	Drive module small	Drive module large	
375 x 498 x 271	375 x 498 x 299	658 x 498 x 425	
200–600 V, 50–60 Hz	200–600 V, 50–60 Hz	200–600 V, 50–60 Hz	
Std: IP20	Std: IP20	Std: IP20	
IRB 140, IRB 260, IRB 360, IRB 1200, IRB 1600 (small drive unit),			
IRB 2400, IRB 2600, IRB 4400, IRB 4600, IRB 6620, IRB 6640,		3 6640,	
IRB 6650S, IRB 7600, IRB	460, IRB 660, IRB 760 (large	drive unit)	
	-	-	
	375 x 498 x 271 200–600 V, 50–60 Hz Std: IP20 IRB 140, IRB 260, IRB 360 IRB 2400, IRB 2600, IRB 4	375 x 498 x 271 375 x 498 x 299 200–600 V, 50–60 Hz 200–600 V, 50–60 Hz Std: IP20 Std: IP20 IRB 140, IRB 260, IRB 360, IRB 1200, IRB 1600 (small d	

Process module



Size H x W x D (mm)	Small 720 x 725 x 710 mm, Large 970 x 725 x 710
Electrical connections	Empty cabinet
Protection	Std: IP54

Toronto.	Size H x W x D	1450 x 725 x 710 mm
	Electrical connections	200-600 V, 50-60 Hz
	Protection	Std: IP54 (IP33 in rear compartment)
	IRB Support	Paint robots
A		

FlexPendant		
	Size	6.5" color touch screen / 1.0 kg
	Protection	Std: IP54
	IRB Support	Non-paint robots

FlexPaint Pendant		
	Protection	Std: IP54, EX protected
	IRB Support	Paint robots

Track Motions

RTT RTT Robot model IRB 1600 Max Speed (m/s) 1.06 IRB 2400 Protection available Standard Mounting position Floor Travel length (m) 1.70 - 11.70 (in steps of 1m) Acc/Ret (m/s2) 1.50 Maraton-Pac, 2.50 Bobin **IRBT IRBT 4004** Robot model IRB 4400-60 Max Speed (m/s) 2.00 IRB 4600 Protection available Std: Foundry, IP65 Mounting position Travel length (m) 1.90-19.90 (in steps of 1m) Acc/Ret (m/s²) 2.50 **IRBT 6004** Robot model IRB 6620 Max Speed (m/s) 1.60 IRB 6640 Protection available Std: Foundry, IP65 IRB 6650S Mounting position Floor IRB 6700 Travel length (m) 1.70-19.70m (in steps of 1m) Acc/Ret (m/s²) 2.00 **IRBT 7004** Robot model IRB 7600 Max Speed (m/s) 1.20 Protection available Std: Foundry, IP65 Mounting position Floor Travel length (m) 1.70-19.70 (in steps of 1m) Acc/Ret (m/s2) 1.80 FlexTrack IRT501-66 and IRT501-66R Robot model IRT501-66 IRT501-66R 2 1.50 None Max Speed (m/s) 900 2000 (material handling Load track motion) Travel length 25 1-25 Track length (m) 2.10-105 2.10-105 Width (m) 0.66 0.66 2 Acc/Ret (m/s²) 1.20 IRT501-90 and IRT501-90R IRT501-90 IRT501-90R Robot model Max Speed (m/s) 1.50 1.20 (material handling Load 2000 2950 track motion) Travel length 1-25 1-25 Track length (m) 2.10-105 2.10-105 Width (m) 0.90 0.90 Acc/Ret (m/s²) 1.20 1

Positioners

FlexLifter

IRL 100 and IRL 190



	IRL 100	IRL 100
Load (kg)	1000	500
Lifting height (mm)	100	190
Speed (mm/s)	40	76
Lift time (sec)	2.50	2.50
Rotation	Optional 360° rotation	Optional 360° rotation
Mounting	Floor or FlexTrack, IRT501-66,66R,90,90R	Floor or FlexTrack, IRT501-66,66R,90,90R

FlexLifter

IRL 600



Load (kg)	600
Lifting height (mm)	600
Speed (mm/s)	200
Lift time (sec)	3
Rotation	
Mounting	Floor or FlexTrack, IRT501-66,66R

FlexPLP

IRPLP - X, Y and Z axis



3
150
30
X = 300 or 400, Y = 300 or 400, Z = 200
100

IRPLP - Z axis



Axis	1
Static load (kg)	150
Dynamic load (kg)	50
Travel length (mm)	200
Speed (mm/s)	100

IRPLP - X and Y axis



Axis	1 or 2
Static load (kg)	150
Dynamic load (kg)	50
Travel length (mm)	300 or 400
Speed (mm/s)	200

Positioners

IRBP A

IRBP A-250, IRBP A-500, IRBP A-750



	IRBP A-250	IRBP A-500	IRBP A-750
Max handling capacity (kg)	250	500	750
Max working envelope ø (mm)	1000	1450	1450
Max length (mm)	900	950	950

IRBP B

IRBP B-250, IRBP B-500 and IRBP B-750



	IRBP B-250	IRBP B-500	IRBP B-750
Max handling capacity (kg)	250 (each side)	500 (each side)	750 (each side)
Max working envelope ø (mm)	1000	1450	1450
Max length (mm)	900	1000	1000

IRBP C

IRBP C-500 and IRBP C-1000



	IRBP C-500	IRBP C-1000
Max handling capacity (kg)	500 (each side)	1000 (each side)
Max working envelope ø (mm)	-	-
Max length (mm)	-	-

IRBP D

IRBP D-300 and IRBP D-600



	IRBP D-300	IRBP D-600
Max handling capacity (kg)	300 (each side)	600 (each side)
Max working envelope ø (mm)	1000	1200
Max length (mm)	1600	2000
	Principal	

IRBP K

IRBP K-300, IRBP K-600 and IRBP K-1000



	IRBP K-300	IRBP K-600	IRBP K-1000
Max handling capacity (kg)	300 (each side)	600 (each side)	1000 (each side)
Max working envelope ø (mm)	1200	1400	1400
Max length (mm)	4000	4000	4000
			•

IRBP L

IRBP L-300, IRBP L-600 and IRBP L-1000



	IRBP L-300	IRBP L-600	IRBP L-1000
Max handling capacity (kg)	300	600	1000
Max working envelope ø (mm)	1500	1500	1500
Max length (mm)	4000	4000	4000

IRBP L

IRBP L-2000 and IRBP L-5000



	IRBP L-2000	IRBP L-5000
Max handling capacity (kg)	2000	5000
Max working envelope ø (mm)	1500	2200
Max length (mm)	4000	5000

IRBP R

IRBP R-300, IRBP R-600 and IRBP R-1000



	IRBP R-300	IRBP R-600	IRBP R-1000
Max handling capacity (kg)	300 (each side)	600 (each side)	1000 (each side)
Max working envelope ø (mm)	1000	1200	1200
Max length (mm)	1600	2000	2000
		P	7

Application equipment

Material Handling

DressPack

To support different production needs a family of DressPacks has been developed for Material Handling.

Common features

- Well documented solutions including training material, circuit diagram and CAD models.
- Easy to maintain including spare part support.
- Supports parallel signals as well as common fieldbus communication.

Material Handling

Integrated DressPack - ID and LeanID



This type of DressPack creates flexibility for a variety of production demands. It is intended for production where there are high demands on flexibility and accessibility. For operations with many complex wrist movements and where the need for flexibility in changing products is high. No individual adjustment are needed for DressPack.

Material Handling

External with retract arm function



External DressPack with a retract arm pulling the cables away from the wrist. Minor individual adjustment needed for DressPack.

Material Handling

External



External DressPack targeting production with basic needs for robot handled tool. Individual adjustment needed for DressPack.

Spot Welding

Spot Welding DressPack

To support different production needs a family of DressPacks has been developed for Spot Welding applications or when they are combined with Material Handling.

Common features:

- Well documented solutions including training material, circuit diagram and CAD models.
- Easy to maintain including spare part support.
- Supports parallel signals as well as common fieldbus communication.
- Supports pneumatic or servo welding guns.
- Supports AC or MFDC welding application.

Spot Welding

Integrated DressPack - ID and LeanID



This type of DressPack creates flexibility for a variety of production demands. It is intended for production where there are high demands on flexibility and accessibility. For operations with many complex wrist movements and where the need for flexibility in changing products is high. No individual adjustment is needed for DressPack.

Spot Welding

External with retract arm function



External DressPack with a retract arm pulling the cables away from the wrist. Minor individual adjustment needed for DressPack.

Spot Welding

Spot Welding cabinet



Dedicated controller cabinet for spot welding processes, including spot welding timer.

The cabinet supports different process needs, like:

- AC or MFDC welding technique.
- Robot handled or stationary welding guns.
- Pneumatic or servo controlled welding guns.

Application equipment

Spot Welding

Water and Air Unit



A fully integrated water and air unit for spot welding processes.

The unit supports different process needs like:

- Robot handled or stationary welding guns.
- Pneumatic or servo controlled welding guns.

Spot Welding

FlexGun IRG X-Gun



Type	X-Gun
Transformer	MFDC or AC
Max stroke (mm)	245
Max force (daN)	757 (gun body capability)
Arm length (mm)	227–600
Weight (kg)	100–150
Key feature	Same body for both X and C gun

Spot Welding

FlexGun IRG C-Gun



Туре	C-Gun
Transformer	MFDC or AC
Max stroke (mm)	245
Max force (daN)	757 (gun body capability)
Arm length (mm)	0-250
Weight (kg)	100–150
Key feature	Same body for both X and C gun

Arc Welding

Seam finder SmarTac



Search Speed (mm/s)	20-50 (depending on position accuracy required)
Search time per	2-6 (depending on workpiece complexity)
point/one dimension	
(sec)	
Accuracy (mm)	+/- 0.25 (with search speed 20 mm/sec)

Arc Welding

Seam tracker WeldGuide IV



WeldGuide IV is the most powerful robotic though-the arc joint joint tracking on the market. It is a patented technology using two sensor inputs, the welding current and the arc voltage, reading the real values from the welding arc 25,000 times per second, which is up to 25 times faster than traditional tracking methods. Combined with the outstanding ABB motion control TrueMove™ this provides for extremely quick and accurate path corrections, superior to any other available thru-the-arc joint tracking. WeldGuide IV can guide spray-arc, short-arc and pulsed-arc and provide Height sensing, Centerline tracking, MultiPass, Adaptive fill and Single side tracking. It is very easy to program and fine tune with all information at your fingertips on the powerful and interactive FlexPendant.

Arc Welding

Welding torches



We offer a wide range or welding torches from the leading brands for local installation. For delivery with the Esab AristoMig 5000i process equipment we offer the Binzel ABIROB A and ABIROB W torch packages with air and water cooling. For delivery with the RPC process equipment we offer the Binzel ABIROB A torch package (air cooling) for IRB 1520ID and the Esab PSF315 welding torch kit (air cooling) for IRB 1410.

Arc Welding

TSC Torch Service Center



Torch cleaner unit TC 96 (gas nozzle cleaning).

Tool Centre Point gauging and calibrating system.

Wire cutter (Max. wire diameter to be cut: 1.6 mm steel and aluminium).

Anti-spatter spraying unit.

Arc Welding

Bull's Eye



The Bull's Eye provides the user with a fully automated tool center point calibration giving the highest possible level of utilization, quality and productivity from your robot station.

Customised pre-defined programs enable fully automatic tool centre point calibration during production execution, reducing down time to almost zero.

Application equipment

Arc Welding

Esab AristoMig 5000i



Voltage range (V)	8–60
Current range (A)	16–500
Permissible load at MIG/MAG	60% duty cycle: 500A/40V, 100 % duty cycle: 400A/36V
Process methods MIG/MAG	Short arc, Spray arc, Rapid arc, Pulse arc

Esab AristoMig 5000i process equipment standard packages with the Esab AristoMig Integrated graphical user interface. Available for IRB 1600, IRB 1600ID, IRB 2600 and IRB 2600ID.

Arc Welding

Power Source RPC S-400



Connection voltage (V)	400 (-15% + 20%)
Output current (A)	400 80% duty cycle
Welding mode	Synergic MIG/MAG

ABB RPC S-400 process equipment standard packages with the ABB RPC S Integrated graphical user interface. Available for IRB 1410 and IRB 1520ID. Only for the Asian market.

Arc Welding

Graphical user interfaces



Available for Fronius, RPC, Esab, Lincoln and Miller power source packages.

The easy-to-use FlexPendant graphical user interface provides operators with a single point of programming, an overview of cell status and a display of important quality and production data. With just a few buttons, an intuitive and PC-like, multilingual interface, the operator can organize the welding operation with a minimum of training. By integrating the power source interface on the FlexPendant the operator can have full control over voltage, current, speed, gas flow, etc.

Machining

ForceControl



Enables easy teaching and automatic path generation of complex part surfaces and edges for machining processes like polishing, deburring, grinding. Forces are also controlled during the processing instead of the conventional position control of the robot which makes it more sensitive and increases the quality of the finished parts. Suitable function packages are available for various machining robots of ABB.

Palletizing

FlexGripper - Claw



Handled products	1
Max. weight per lift (kg)	50
Gripper weight (kg)	70
Finger pitch (mm)	75
Bag dimensions (LxWxH range) (mm)	(300-750)x(300-550)x(120-250)

Main application: Bag palletizing

FlexGripper - Clamp



Handled products	1-2	1-5
Max. weight per lift (kg)	40	60
Gripper weight (kg)	45	80
Finger pitch (mm)	1-zone	2-zone
Bag dimensions (LxWxH range) (mm)	(200-650)x(200-500)x	(200-1200)x(200-500)x
	(150-330)	(150-330)

Main application: Case palletizing

FlexGripper - Vacuum



Handled products	1-5
Max. weight per lift (kg)	40
Gripper weight (kg)	75
Finger pitch (mm)	10
Bag dimensions (LxWxH range) (mm)	Max 1200x500x300 mm, Min 240x240x100
	•

Main application: Case palletizing Handled pallet types: GMA/AUS/EUR/ISO

Motors and Gear units

Gear Units MTD / MID



							-
Product/MTD and MID	MTD 250	MTD 500	MTD 750	MTD 2000	MTD 5000	MID 500	MID 1000
Max handling	300	600	1000	2000	5000	1300	3300
capacity (kg)							
Max continous	350	650	900	3800	9000	1400	3800
torque (Nm)							
Max bend	650	3300	5000	15000	60000	5000	15000
moment (Nm)							

Motor Units MU



Product/MU	MU 100	MU 200	MU 300	MU 400		
Rated Speed (rpm)	3300	5000	4500	4700		
Max dynamic	4.30	14	35	50		
Max dynamic torque (Nm)						

Application equipment

Press Automation

IRB 6660RX (7-axis robot)



Main applications		
Press automation	Load (kg)	75/50
Machine tending	Reach (m)	3.10 + 1.3/1.45
Material handling	7th axis rotational	Offset 6th-7th axis: 1.30/1.45 m
		Height: 127 mm

Press Automation

IRB 7600RX (7-axis robot)



Load (kg)	85/80
Reach (m)	3.50 + 1.30/1.45
7th axis rotational	Offset 6th-7th axis: 1.30/1.45 m
	Height: 127 mm
<u> </u>	
	Reach (m)

Press Automation

IRB 6660FX (7-axis robot)



Main applications		
Press automation	Load (kg)	40
Machine tending	Reach (m)	3.10 + 1.40
Material handling	7th axis rotational	Stroke: ± 1.40 m
		Height: 130 mm
		Max. Speed: 5 m
		Max. Acceleration: 20 (m/s²)
	1	

Press Automation

IRB 7600FX (7-axis robot)



Main applications		
Press automation	Load (kg)	100
Machine tending	Reach (m)	3.10 + 1.75
Material handling	7th axis rotational	Stroke: ± 1.75 m
		Height: 130 mm
		Max. Speed: 5 m
		Max. Acceleration: 18 (m/s²)

Press Automation

IRB 760 Twin XB



Main applications		
Press automation	Load (kg)	150 (Crossbar, tooling and part)
Material handling	Reach (m)	3.10 + 1.75
	non-Henri	

Press Automation

Carbon Fiber tooling



	Main applications	ABB modular tooling concept combines Carbon Fiber (CF) for structural components
	Press automation	(1 & 2) with aluminum components (3) for adaption to each specific parts.
Material handling Carb		Carbon Fiber improves performance due to a dramatic reduction of deflection, vibrations
		and weight. Its design features a reduced height for optimum cycle time.
		Carbon Fiber Boom (1) is an extension of the robot arm. With a length of 1450 mm,
		it has been dimensioned to handle up to 100kg.
		The Carbon Fiber Gondola arm (2) is a common component for 6- and 7- axis robots.
		There are two length variants: 1000 and 1400 mm.

Press Automation

DDC - Dynamic Drive Chain (Press servotechnology)



DDC allows new and existing presses to take full advantage of servo technology with limited peak power, using a servo motor to open and close the press faster while performing the stamping process with the energy accumulated in the flywheel. It consists of a servo kit (gear motor plus drive) that is integrated in the same master control as the automation. The DDC line is capable of running 30% faster than common lines. Energy losses are reduced thanks to regenerative speed reduction and synchronized clutching.

Dispensing

Doser (single or double, heated or not heated)



Gross volume (cm³)	1.20	80	155	560
Nominal flow (ml/s)	0.80	24	37.50	80
Peak flow (ml/s)	1	28	44	96
Nominal flow/ peak pressure (bar)	150 / 250	150 / 250	150 / 250	150 / 250
Dimensions* (mm)	240x40x470	170x460x950	180x470x960	200x510x1390

^{*}Max. envelope volume; not heated single doser, incl. inlet and outlet valves; no cabling.

Application equipment

Dispensing

Pump (single or double barrel, heated or not heated)



Barrel size (I)	30	50	200
Follower plate (ø) (mm)	280	355	571
Pressure ratio	65:1	65:1	65:1
Delivery volume per double stroke (cm³)	150	150	150
Dimensions* (mm)	1070x700x 2350	1070x700x 2350	1070x700x 2350
	1	Ĭ	1

^{*}Width, depth, maximum height.

Dispensing

Applicator

Gluing	SPA410 Sealing	SPA470 Sealing	Material Temperat	ure Conditioning
	1 Nozzle*	3 Nozzles	Peltier 600W**	Peltier 800W**
THE REAL PROPERTY.	The			

^{*}Optional with nozzle changer. **Air- or watercooled.

Integrated Force Control

Integrated Force Control



Conventional robotic solutions are controlled by predefined paths and speeds.

However, with ABB Integrated Force Control, the robot reacts to its surrounding and can deviate from its programmed path or speed based on feedback from the force sensor. It is possible to automate complex tasks which previously required skilled personnel and advanced fixed automation.



Main applications	Capacity	Sensor 165	Sensor 660	Sensor 2500
Grinding	Fx. Fy	165 Nm	660 N	2500 N
Milling	Fz	495 N	1980 N	6250 N
Polishing	Mx, My, Mz	15 Nm	60 Nm	400 Nm
Deburring	Dimensions	***************************************	*	
Assembly	Height (mm)	40	40	62
Product testing	Diameter (ø mm)	104	104	168
			•	

Integrated Vision

Integrated Vision



Compact smart cameras that are easily programmed in Robotstudio together with the robots makes vision guided robots viable for any user. The vision system is highly robust and proven in industrial solutions under tough conditions. The product comes complete with cables, filters, lenses, cameras and software.

Modular solutions

FlexMT®

FlexMT®



A leader in the development of automation solutions, ABB's FlexMT sets the standard in flexible machine tool tending. This robotic solution increases machine utilization by as much as 60 percent. Available in two variants, the FlexMT 20 (20kg/1.65m reach) and the FlexMT 60 (60kg/2.05m reach), the FlexMT comes complete with a robot controller inside its fully integrated control cabinet. The FlexMT is a pre-engineered, well-tested and reliable automation solution.

Machining

FlexWasher

2-in-1 process

ABB FlexWasher technology combines high pressure water de-burring (HPWD) and parts washing into one system. This system removes eyelash burrs and other foreign materials without removing parent material.

Robotic Agility

ABB FlexWashers take advantage of the robot's agility to move the part around stationary HPWD tools or the HPWD tool around the part in a fixture. The result is a uniform and unsurpassed cleanliness of parts with simple as well as complex geometries.

Green technology

ABB FlexWasher technology is differentiated by not using heated water or cleaning chemicals to remove burrs and debris. This results in significant lower energy consumption and operating costs. The patented closed loop water filtration system with best-in-class low water consumption also reduces waste handling costs.

Palletizing

PalletPack



PalletPack is a package of pre-emgineered products to make end-of-line and bag palletizing solutions more accessible and easier to use. The package includes robot, gripper and easy-to-use Wizard on Flexpendant for setting up different palletizing tasks. A PLC including safety is included for control of the complete line.

Packing

RacerPack



RacerPack is a robot function package for packing of flow wrapped products. Receiving flow wraps on a high speed in feed conveyor, RacerPack distributes the products into an indexing belt from which the IRB 360 picks up the products and pack them into boxes. The product is modular and can be ordered with full configuration or modules depending on the need.

Paint robots

IRB 52

IRB 52



Painting	a a a (1 a v)	
	Load (kg)	7
	Reach (m)	1.20-1.45
	Protection available (RP) (mm)	Std: IP67, Ex
	Specific	Floor mounted. Wall mounted and inverted are selectable
	Pose repeatability	0.15



IRB 580

IRB 580-12, 1220 mm



Main applications		
Painting	Load (kg)	10
	Reach (m)	2.20
	Protection available (RP) (mm)	Std: IP67, Ex
	Specific	Floor mounted
	Pose repeatability	0.30



IRB 580

IRB 580-12, 1620 mm



	Main applications		
	Painting	Load (kg)	10
		Reach (m)	2.60
		Protection available (RP) (mm)	Std: IP67, Ex
		Specific	Floor mounted
		Pose repeatability	0.30
- 1			



IRB 580

IRB 580-13/14, 1220-1620 mm



Main applications		
Painting	Load (kg)	10
	Reach (m)	2.20-2.60, rail travel length: 1 - 14
	Protection available (RP) (mm)	Std: IP67, Ex
	Specific	Clean wall rail, In-booth rail
	Pose repeatability	0.30

IRB 5400

IRB 5400-12 Slim arm



Main applications		
Painting	Load (kg)	25
	Reach (m)	3.10
	Protection available (RP) (mm)	Std: IP67, Ex
	Specific	Floor mounted
	Pose repeatability	0.15

IRB 5400

IRB 5400-13/14 Slim arm



Main applications		
Painting	Load (kg)	25
	Reach (m)	3.10, rail travel length: 1 - 14
	Protection available (RP) (mm)	Std: IP67, Ex
	Specific	Clean wall rail, In-booth rail
	Pose repeatability	0.15

Paint robots

IRB 5400

IRB 5400-22 Process arm



Main application	ıs	
Painting	Load (kg)	25
	Reach (m)	3.10
	Protection available (RP) (mm)	Std: IP67, Ex
	Specific	Floor mounted
	Pose repeatability	0.15



IRB 5400

IRB 5400-23/24 Process arm



Main applications		
Painting	Load (kg)	25
	Reach (m)	3.10, rail travel length: 1 - 14
	Protection available (RP) (mm)	Std: IP67, Ex
	Specific	Clean wall rail, In-booth rail
	Pose repeatability	0.15



IRB 5500

IRB 5500



Main applications		
Painting	Load (kg)	13
	Reach (m)	3
	Protection available (RP) (mm)	Std: IP67, Ex
	Specific	Wall mounted – axis 1 "horizontal"
	Internation	Wall mounted – axis 1 "vertical"
	Pose repeatability	0.15

Bending backwards possibility on axis 3 (may be limited by the hose guiding on the robot)

IRB 5350 Door Opener

5350 3-axis/4-axis



Main applications		
Door Opening	Load (kg)	5
	Reach (m)	1.35, rail length: 3 - 10
	Protection available (RP) (mm)	Std: IP66, Ex
	Specific	Floor mounted, rail mounted
	Pose repeatability	0.15

Painting equipment

Color Change Unit

Color Change Unit



ABB's color change units are specifically designed for fast color change. The internal bores of the color change unit are without "dead-ends," reducing the cleaning cycle to a minimum. Both plastic and steel versions are available, with or without recirculation. The ABB color change units are compatible with solvent based and water borne paint materials used in 1K and 2K systems.

2K Mixer Unit

2K Mixer Unit



ABB's 2K mixers are specifically designed for precise mixing of two component fluids and optimized for fast material change. The 2K mixer unit is using the same fluid valves as in the color change unit (common parts). 2K mixer unit is designed and optimized to be used in combination with ABB's gear pumps (and IPS software).

GearPump Unit

GearPump Unit



ABB's precision paint pump provides constant and consistent fluid regulation for automatic coating applications. It is specifically designed for fast color change. The ABB gear pumps can be used for paint, catalyst and clear coat and are available in sizes: 1.2 cc/rev, 3 cc/rev, 6 cc/rev and 9 cc/rev. The compact design uses light weight materials and is optimized for low material waste and color change time.

M-PAC Color Change Module & Gear Pump Module

M-PAC Color Change Module



The modular concept of the new M-PAC paint application equipment makes it easy to combine the various components to build compact and light units for integration on the robot arms. This enables for the robots to use high acceleration and the application solution to have minimum material waste. The color change module can be mounted directly on a gear pump module for maximum paint savings and minimum color change time. This complete assembly is designed to be integrated in the robot with the shortest possible supply line to the atomizer (typically less than 650 mm).

Compact CBS Unit

Compact CBS Unit and C-CBS2



The compact CBS is an optimized solution for internal charge waterborne materials. This CBS unit is used to prepare and change the paint cartridges in the CBS bell atomizer which is handled and controlled by the ABB paint robot. It is a cost effective solution, prepared for 1 or 2 filling stations with flushable cartridges. Flushable cartridges are used when the cartridges are connected to a color change unit for changing the paint material in the same cartridge. Color change waste in a flushable cartridge is slightly more than with dedicated cartridges (< 30 ml).

IRB 5320 Workpiece Positioner

IRB 5320 Workpiece Positioner



The IRB 5320 Workpiece Positioner is a manipulator that is integrated with a six-axis paint robot, simplifying the painting process. It operates with either one or three axes. The three-axis version of the IRB 5320 is used to precisely position workpieces for painting. The turntables are controlled by the fully-integrated robot servo unit alternating as the loading/unloading station and as the place where the robot paints the workpieces. This single-axis positioner is built, with precision and reliability, on the proven ABB robotics gear box and delivered in several thousand units prior to this introduction.

IRB 5330 Paint External Axis Kit

Paint External Axis Kit



ABB's pre-engineered Paint External Axis Kit is for the control and positioning of ABB paint robots on linear or vertical axes solutions. This ex-certificated servo unit is specially designed to be used, together with customized track motion systems, as an engineering building block for paint application, extending possibilities for large object painting with the use of a standardized external axis solution.

Air Control Unit

Air Control Unit



The ABB Air Control Unit (ACU) is a high performance, cost-efficient air flow controller typically used for high volume paint applications. This extremely accurate and reliable unit controls the air flow destined to a paint gun or paint bell and contains three different channels that control spray patterns, bell rotation and even paint flow for some applications.

Atomizers (RB1000-SAD, -SSD)

RB1000-SAD, -SSD



The Robobel family of internal charged bells consist of highly efficient, high performance rotary atomizers for solvent borne paint, providing high finish quality and high transfer efficiency. It includes the popular 926 atomizer, the 951 with pattern control function, and the RB1000 high performance atomizer with up to 1000cc/min paint flow capacity.

CBS Atomizers

RB1000-WSC



ABB's Cartridge Bell System (CBS) is the optimal solution for saving paint, both for water borne and solvent borne paints. Color changing is done by changing the paint cartridge, resulting in near zero paint-loss for dedicated color-cartridges. For efficient use of space and cost a flushable version is also available. Key features are: Pattern Control for high transfer efficiency, and High Flow capacity for high acceleration robots.

Painting equipment

Atomizers

RB1000-EXT



ABB's external charged bell is a highly efficient atomizer designed for waterborne paint. By utilizing the same air motor as the RB1000 series, the rotation speed performance is up to max 80,000 rpm with a paint flow of 700cc/min in primer. The atomizer is designed with an air heater-free system and has an newly designed electrodes, providing high transfer efficiency.

Atomizers

ROBOBEL031-PC



The 031-PC bell is easiest way for general industry customers to gain access to ABB's bell atomizer technology. The circle spray pattern and variable pattern control of ROBOBEL031-PC bring a lot of benefits to users that normally use spray gun. Since the 031-PC uses no high-voltage, not only both water-borne and solvent-borne but also coating materials can be used. There are widely line-up bell cup and selectable for suitable size.

Application package

Paint Application Packages (PAP)



ABB's standardized paint application packages are complete solution designed to have your system up and running very quickly. They are pre-engineered and pre-connected to enable fast installation. They require less field tuning and come documented with standardized interfaces. The packages are flexible. You can choose between gun or bell, select the number of colors, pump sizes, cable length, etc.

Application package

Paint Application Packages (PAP)



The ABB Simplfied Robot Programming solution combines modern motion tracking technology, with smart software and a teaching handle (tracing device) which resembles a traditional spray gun. Recording mode is activated from the teaching tool and records paint commands along the motion path, visually guided by a line laser to see where the trigger on points are located on the object. Speed, accuracy and fluidness of motion are fully editable in RobView once the recording has stopped.

FlexArc® Standard Arc Welding cells Complete plug n' produce solution

FlexArc cells deliver maximum performance while making optimum use of available space.

All equipment is installed on the common platform which provides for easy relocation within the production facilities.

Complete cell is tested in production including welding test, therefore, customers obtains fully functioning solution without need for additional on-site commissioning. FlexArc features the FlexPendant GUI, which not only provides operators with an overview of the status of the cell, but also important quality and production data.

Cells based on A-type positioners

FlexArc A





Robot	IRB 1520ID, IRB 1600(ID), IRB 2600(ID), IRB 4600
Number of robots	1–2
Positioners	IRBP A-250, IRBP A-500, IRBP A-750
Handling capacity	Max 750 kg
Process equipment package	Fronius, SKS, ESAB, Kemppi
Welding torch	Fronius, Dinse, Binzel, SKS
Safety equipment	Complete system of safety features—safety encing, light curtains, laser scanner, froll doors, safety locks, safety PLC

Cells based on B-type positioners

FlexArc B





Robot	IRB 1520ID, IRB 1600(ID), IRB 2600(ID),
	IRB 4600
Number of robots	1–2
Positioners	IRBP B-250, IRBP B-500, IRBP B-750
Handling capacity	Max 750 kg
Process equipment package	Fronius, SKS, ESAB, Kemppi
Welding torch	Fronius, Dinse, Binzel, SKS
Safety equipment	Complete system of safety features
	- safety fencing, light curtains, laser
	scanner, roll doors, safety locks, safety PLC

Cells based on C-type positioners

FlexArc C





Robot	IRB 1520ID, IRB 1600(ID), IRB 2600(ID), IRB 4600
Number of robots	1–2 (up to 3 on request)
Positioners	IRBP C-500, IRBP C-1000
Handling capacity	Max 1000 kg
Process equipment package	Fronius, SKS, ESAB, Kemppi
Welding torch	Fronius, Dinse, Binzel, SKS
Safety equipment	Complete system of safety features
	- safety fencing, light curtains, laser
	scanner, roll doors, safety locks, safety PLC

Cells based on D-type positioners

FlexArc D





Robot	IRB 1520ID, IRB 1600(ID), IRB 2600(ID),
	IRB 4600
Number of robots	1–2 (up to 3 on request)
Positioners	IRBP D-300, IRBP D-600
Handling capacity	Max 600 kg
Process equipment package	Fronius, SKS, ESAB, Kemppi
Welding torch	Fronius, Dinse, Binzel, SKS
Safety equipment	Complete system of safety features
	- safety fencing, light curtains, laser
	scanner, roll doors, safety locks, safety PLC

Cells based on K-type positioners

FlexArc K





Robot	IRB 1520ID, IRB 1600(ID), IRB 2600(ID),
	IRB 4600
Number of robots	1-2 (up to 4 on request)
Positioners	IRBP K-300, IRBP K-600, IRBP K-1000
Handling capacity	Max 1000 kg
Process equipment package	Fronius, SKS, ESAB, Kemppi
Welding torch	Fronius, Dinse, Binzel, SKS
Safety equipment	Complete system of safety features
	- safety fencing, light curtains, laser
	scanner, roll doors, safety locks, safety PLC

Cells based on R-type positioners

FlexArc R





y	
Robot	IRB 1520ID, IRB 1600(ID), IRB 2600(ID), IRB 4600
Number of robots	1–2 (up to 4 on request)
Positioners	IRBP R-300, IRBP R-600, IRBP R-1000
Handling capacity	Max 1000 kg
Process equipment package	Fronius, SKS, ESAB, Kemppi
Welding torch	Fronius, Dinse, Binzel, SKS
Safety equipment	Complete system of safety features
	- safety fencing, light curtains, laser
	scanner, roll doors, safety locks, safety PLC

Cells based on 2L-type positioners or fixed tables

FlexArc 2L





Robot	IRB 1520ID, IRB 1600(ID), IRB 2600(ID),
	IRB 4600
Number of robots	1
Positioners	2 IRBP L or 2 fixed tables
Handling capacity	Max 300 kg
Process equipment package	Fronius, SKS, ESAB, Kemppi
Welding torch	Fronius, Dinse, Binzel, SKS
Safety equipment	Complete system of safety features
	- safety fencing, light curtains, laser
	scanner, roll doors, safety locks, safety PLC

Cells based on 2L-type positioners

FlexArc 2L





Robot	IRB 1520ID, IRB 1600(ID), IRB 2600(ID), IRB 4600
Number of robots	1-2 (up to 3 on request)
Positioners	2 IRBP L
Handling capacity	Max 300 kg
Process equipment package	Fronius, SKS, ESAB, Kemppi
Welding torch	Fronius, Dinse, Binzel, SKS
Safety equipment	Complete system of safety features
	- safety fencing, light curtains, laser
	scanner, roll doors, safety locks, safety PLC

Software products RobotWare

To boost your productivity and decrease your total cost of owning and operating a robot-based solution, ABB has developed a family of software products to support every stage of the robot life cycle.

RobotWare is a collection of robot software, which offers in its basic design – superior motion control and enables the quick integration of additional hardware. For RobotWare there are a number of options and specific application software available.

They represent tools for robot users who need additional functionality, for example running multiple tasks, transfer information from file to robot, communicating with a PC and performing advanced motion tasks. For more information, please visit www.abb.com/robotics

RobotWare - Options

AbsAcc



Absolute Accuracy (AbsAcc) is a calibration concept which ensures a TCP absolute accuracy of better than ± 1 mm in the entire working range with some limitation for "bending backwards" robots. The user is supplied with robot calibration data (compensation parameters saved on the manipulator SMB) and a certificate that shows the performance ("birth certificate"). The difference between an ideal robot and a real robot can typically be up to 10mm, resulting from mechanical tolerances and deflection in the robot structure. The Absolute Accuracy option is integrated in the controller algorithms for compensation of this difference, and does not require external position recalculation.

RobotWare - Options

Communications

Several optional RobotWare functions are available for communication to and from the robot such as:

- FTP Client
- NFS Client
- PC Interface
- FlexPendant Interface
- Field bus Command Interface
- Socket Messaging
- File and Serial Channel Handling
- EtherNet/IP m/s
- PROFINET SW, master/slave and slave only

RobotWare - Options

Conveyor Tracking



Conveyor Tracking (also called line tracking) is the function which makes the robot follow a work object on a moving conveyor. While tracking the conveyor, the programmed TCP speed, relative to the work object, will be maintained even when the conveyor speed is changing slowly.

RobotWare - Options

Collision Detection

Collision Detection is a software option, which reduces collision impact forces on the robot. In this way, the robot and external equipment can be protected from severe damage.

RobotWare - Options

SafeMove



SafeMove™ builds on the latest developments in robotic safety and modernization in safety regulations (ISO 10218). It performs safety classified monitoring of robot motion, covering complex position zones, speed limitation, standstill supervision, tool orientation etc. If a safety hazard is detected, SafeMove executes an emergency stop or alerts a superior PLC within fractions of a second. With SafeMove, it is possible to restrict the cell size to precisely what is needed, saving valuable floor space. It is also possible to create production concepts where robot and operator interact more closely, without compromising safety. For limited needs Electronic Position Switches is available, building on the same principles as SafeMove, but limited to monitoring of joint level zones.

RobotWare - Options

SoftMove



SoftMove is a cartesian soft servo option that allows the robot to be compliant or floating to adjust to external forces or variations in work objects. SoftMove can lower the stiffness of the robot in a pre-defined cartesian direction (in relation to either the tool or the work object) while keeping the original behavior in the other directions. The basic behavior of the softness is mainly controlled by stiffness and damping parameters. With Soft-Move, the robot is compliant in one direction only which facilitates high accuracy and reliability. The option reduces robot programming time and enables effective interaction between robot and machine, which reduces cycle time.

RobotWare - Options

QuickMove™ and TrueMove



Based on advanced dynamic modelling, the IRC5 optimizes the performance of the robot for the physically shortest possible cycle time (QuickMove) and precise path accuracy (TrueMove). Together with a speed-independent path, predictable and high-performance behavior is delivered automatically, with no tuning required by the programmer. What you program is what you get.

RobotWare - Options

MultiMove



The option MultiMove - Independent makes a robot system a MultiMove system with independent robots functionality. A MultiMove system is a system where a common controller controls up to four robots, each equipped with its own drive module. MultiMove system exists in two different modes - Independent and Coordinated. With MultiMove Independent, the robots run independently of each other, i.e. controlled by separate RAPID tasks. It is also possible to run positioners independently (controlled by separate RAPID tasks).

The option MultiMove - Coordinated makes a robot system a MultiMove system with coordinated robots functionality. A MultiMove system is a system where a common controller controls up to four robots, each equipped with its own drive module. MultiMove exists in two different modes - Independent and Coordinated. With the MultiMove Coordinated option, a MultiMove system is able to work together on a common work piece and coordinated in a common workobject. MultiMove Coordinated also includes all MultiMove Independent functionality.

Application software

ABB offers a full range of easy-to-use software tools to help you to improve your process, optimize your production, increase productivity, reduce risks and maximize the return of investment of your robot systems.

Arc Welding

RobotWare Arc



RobotWare Arc comprises a large number of dedicated arc welding functions. It is a simple yet powerful program since both the positioning of the robot and the process control and monitoring are handled in one instruction.

Spot Welding

RobotWare Spot



Dedicated software that simplifies the Spot Welding application. Advanced motion control for an electrical servo gun are built in features. RobotWare Spot is designed to be a general and flexible software platform offering both standard configurations as well as giving possibility to create customized solutions. All with the target to give easy to use function packages for different types of spot welding systems.

Cutting

RobotWare Cutting



Modern ABB robots are used for high precision laser cutting. This is possible through a combination of ABB robot features and advanced cutting software products, RobotStudio Cutting PowerPac and RobotWare Cutting, developed specifically for robotic laser cutting. Using robots for laser cutting offers substantial cost benefits compared to using laser cutting machines. Robotic laser cutting reduces capital investment by up to 35 percent* and uses less floor space.

* A ABB robot based standard function package compared to a dedicated cutting machine.

Dispensing

RobotWare Dispense



RobotWare-Dispense can be used for different types of dispensing processes. It is a software option typically used for gluing, sealing, spraying and other similar processes, but can also be useful in a wide spectrum of other applications.

Picking and Packing

PickMaster 3



PickMaster is the tool for guiding robots in the packaging process. The PC based software product uses comprehensive graphical interfaces to configure powerful applications where up to eight robots may work in a team along conveying belts. PickMaster 3 includes advanced vision technique and tightly integrated conveyor tracking capability. The integrated vision system is advanced, however PickMaster 3 is also open to communicate with any external sensor. (line scanners, color vision, 3D, etc.).

Machine Tending

RobotWare Machine Tending



An integrated set of software tools that uses ABB's extensive experience in machine tending to reduce operational expenditure and increase productivity through easy and flexible pr ogramming, straightforward configuration and trouble free operation of ABB robots.

RobotWare Machine Tending is a flexible controller software for deployment and operation of ABB robots. It provides configurable and powerful tools, including an intuitive graphical user interface, that facilitates trouble-free and safe operation for everyone.

Assembly

RobotWare Force Control



RobotWare Force Control will greatly facilitate the use of robots for tasks that needs "touch sensing", like assembly, fixturing, product testing etc. The option is based on the force control concept, i.e. a robot control strategy where the robot movements are adapted to the feedback from a force sensor. Thus the robot can automatically search for the correct location, and assemble parts using intelligent Force/Torque motion without the risk for jamming or part damage.

RobView

RobView



With RobView 5 you can manage your paint installation, whether it is one or many robots, visualize the complete paint process, and operate and supervise your paint robot cell. A basic version of RobView 5 is bundled with all IRC5P paint robots, free of charge*. It is an affordable graphical user interface for low budget installations. However, it is scalable and expandable with plug-in options for large and advanced installations.

^{*}Requires activation.

Software products RobotStudio®

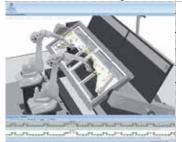
Computer-based programming is the best way to maximize return on investment for robotic systems, resulting in lower costs, faster time to market and superior end products. RobotStudio allows programming to be done on a computer without committing to construction or disturbing existing production.

The computer-based system design in RobotStudio ensures you do it right the first time, with the ability to verify tooling, cycle times, work envelopes and product throughput before any construction begins in the real world.

Achieving perfectly optimized solutions is made possible because you can quickly and easily try multiple configurations on your PC. You can be certain your system will work properly in the real world after seeing it work in the virtual world. The end result is greatly reduced risk.

RobotStudio - PowerPacs

RobotStudio ArcWelding PowerPac



ArcWelding PowerPac is an add-in to RobotStudio that makes it fast and easy to program arc-welding applications. It includes VirtualArc, an expert system that makes it possible to determine the process parameters necessary to achieve a particular welding result. Use of ArcWelding PowerPac makes it easy to make sure that the optimum tool angles are always used, resulting in higher quality welds and shorter cycle-times.

RobotStudio - PowerPacs

RobotStudio Painting PowerPac



The Painting PowerPac integrates paint programming knowledge and paint process tools into RobotStudio. It will speed up your programming and simulation of painting robots and painting equipment, and is a faster and more intuitive way to create paint programs. Paint strokes are easy to create and edit. Instructions for paint events are automatically added to your program and the event trigger axis automatically selected. Robot positions for the acceleration and deceleration distances are calculated automatically. Paint process performance parameters can be predicted off-line.

RobotStudio - PowerPacs

RobotStudio Machine Tending PowerPac



RobotStudio Machine Tending PowerPac – an add-on for RobotStudio, ABB's powerful PC-based programming tool – provides a platform for quick, easy creation and editing of machine tending robot cells in a 3D virtual environment. RobotStudio Machine Tending PowerPac is seamlessly integrated with RobotWare Machine Tending.

RobotStudio - PowerPacs

RobotStudio Machining PowerPac



Machining PowerPac reduces programming complexity by 50% and optimizes machining tool path to improve product quality. The PowerPac guides the users in creating accurate targets and paths from surfaces and edges on an imported CAD model while having control of related process parameters in the simulation. In addition the PowerPac provides the possiblity to convert CNC-Code to RAPID and customize conversion to match different machine setups. RobotStudio MachiningPowerPac not only supports the traditional position controlled processes but also supports force controlled processes and is seamlessly integrated with Robotware Machining FC.

RobotStudio - PowerPacs

RobotStudio Cutting PowerPac



RobotStudio Cutting PowerPac is an offline programming tool that allows operators to create, modify and verify cutting programs in an offline 3D simulation instead of on the factory floor. RobotStudio Cutting PowerPac is seamlessly integrated with RobotWare Cutting.

RobotStudio - PowerPacs

RobotStudio Palletizing PowerPac



RobotStudio Palletizing PowerPac makes programming robot palletizing systems easier than ever before. As no programming skills are required, RobotStudio Palletizing PowerPac software radically reduces programming times and creates fully tested simulations, and real robot system programs, in minutes.

RobotStudio - PowerPacs

RobotStudio Picking PowerPac



Picking PowerPac is an offline tool that simulates PickMaster 3 in picking applications. The PowerPac offers ease of use configuration of a picking application which can be simulated and fully optimized before being downloaded into PickMaster 3 for real production.

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