

ABB ROBOTICS, DECEMBER 2015

IRB 910SC

SCARA Overview



IRB 910 SC

Agenda

- 1. Differentiated value proposition
- 2. Overview and vision
- 3. Main features
- 4. Payload
- 5. Working range
- 6. Performance and accuracy
- 7. Main dimensions
- 8. Outline manipulator
- 9. Degree of protection
- 10. Easy integration
- 11. Controller
- 12. Customer benefits
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Overview

Differentiated value proposition



"fast, cost-effective and, because it's from ABB, accurate"





Original vision

 To fill the gap in our small robot portfolio with a competitive 4 axis robot which could be used in high speed accurate small part assembly, machine tending and general pick and place solutions which would require a compact fast accurate robot



Primary target markets







3C

- Assembly and test of custom chips, Automated board testing, Aerospace electronic components assembly
- Inspections of PC boards, Automated cleaning of circuit board components

Food packaging

- Meat Packaging, snack packaging, Box cutting and taping, Plastic component packaging
- Meat/ snack handling operations, Vegetable picking & cutting, Produce packaging

Medical/ Pharmaceutical

- Ideal for lab automation & drug manufacturing operations
- Custom prescription filling, Tablet packaging



Target main applications





- Screw driving
- Inserting
- Assembly/ disassembly
- Mounting



Material Handling

- Picking and placing
- Parts transfer
- Parts handling
- Sorting



Inspection

- Product inspection
- Testing
- Quality control



IRB 910SC vs. IRB 120





IRB 910SC offers unmatched four axis performance while still having the power of ABB's rapid and IRC-5 platform

It has been designed to be lightweight and portable, boasts a small footprint with superior speed and accuracy



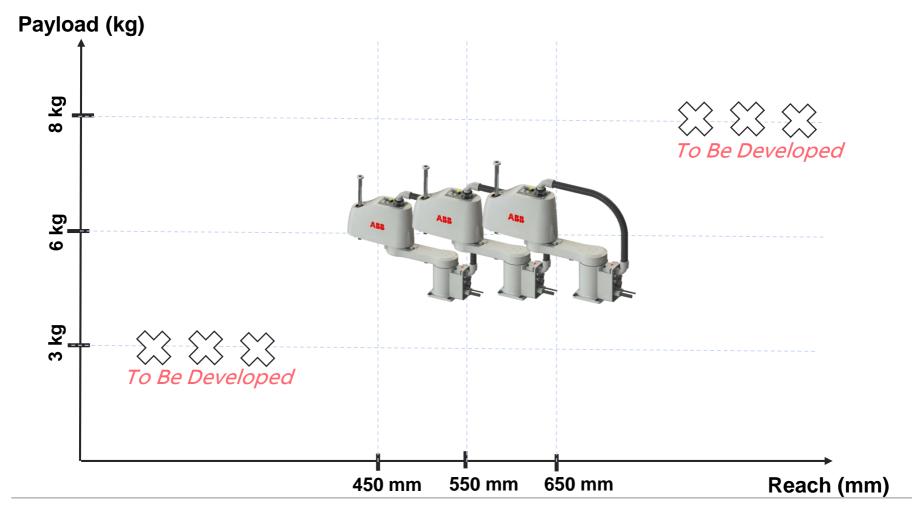
IRB 120

IRB 120 offers all the functionality and expertise of the ABB range in a much smaller packaging

Its reduced weight of only 25kg and compact design enables it to be mounted virtually anywhere on the production line, with superior control and path accuracy



SCARA portfolio





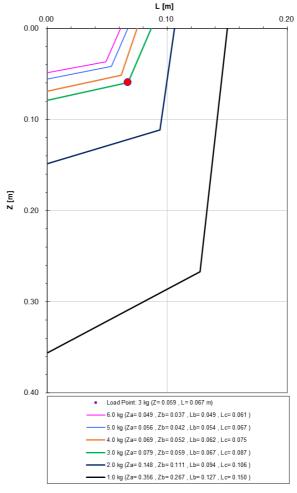
Main features

	IRB 910SC - 3/ 0.45	IRB 910SC - 3/ 0.55	IRB 910SC - 3/ 0.65	
Payload	Maximum 6kg			
Reach	450 mm 550 mm 650 mm			
Weight	24.5 kg	25 kg	25.5 kg	
Footprint	160mmx160mm			
Shaft Diameter	20 mm			
Degree of Protection	IP20			
Mounting Position	Table top			
Controller	IRC 5 Compact			
Supply Voltage	200-600 V, 50/60Hz			
Power Consumption	200 W			



Payload range

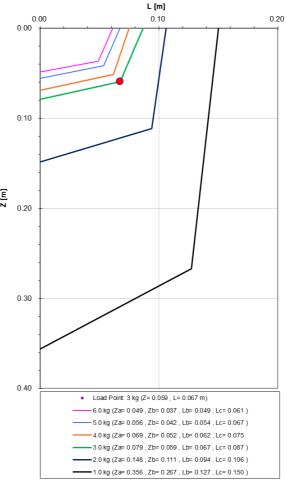






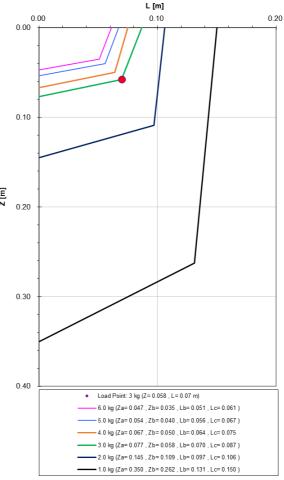
Payload range



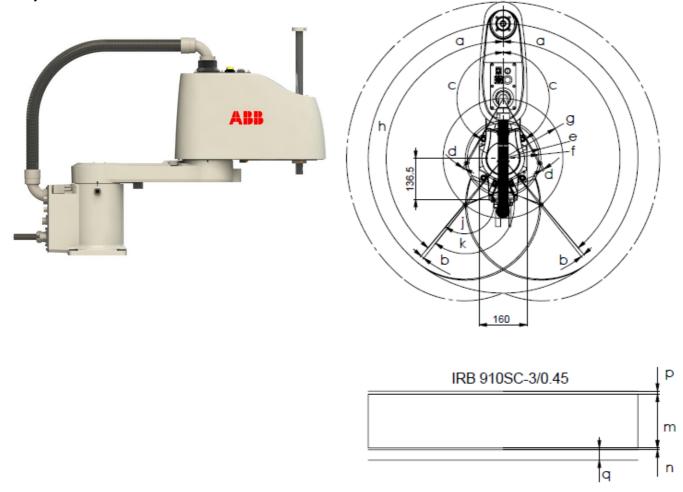


Payload range



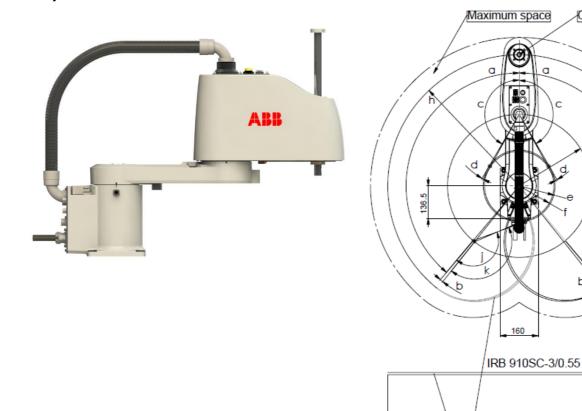








IRB 910SC - 3/ 0.55





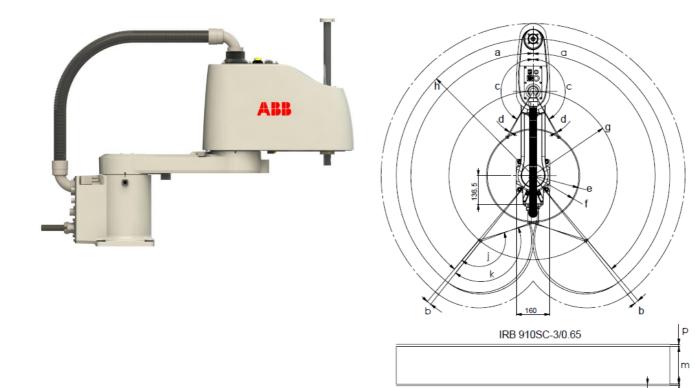
Center Joint#3

р

m

Base mounting face

^VArea limited by mechanical stop





Axis movement/ Maximum speed

Movement

	IRB 910SC-3/0.45		IRB 910SC-3/0.55		IRB 910SC-3/0.65	
Axis movement	Working range	Maximum speed	Working range	Maximum speed	Working range	Maximum speed
Axis 1 Rotation	±140 deg	415 deg/s	±140 deg	415 deg/s	±140 deg	415 deg/s
Axis 2 Rotation	±150 deg	659 deg/s	±150 deg	659 deg/s	±150 deg	659 deg/s
Axis 3 Up/ Down	180mm	1.02m/s	180mm	1.02m/s	180mm	1.02m/s
Axis 4 Rotation	±400 deg	2400 deg/s	±400 deg	2400 deg/s	±400 deg	2400 deg/s

Disclaimer: The numbers contained herein are provisional and subject to change



Performance and accuracy

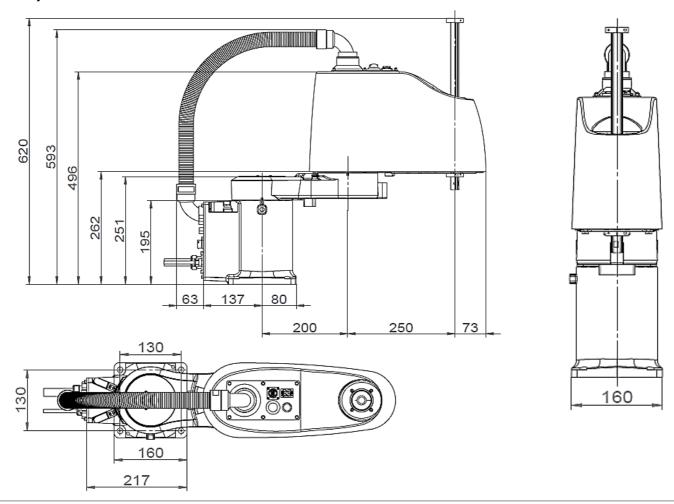
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Performance	IRB 910SC - 3/ 0.45	IRB 910SC - 3/ 0.55	IRB 910SC - 3/ 0.65	
1 kg Picking Cycle	0.370 s	0.380 s	0.385 s	
Max TCP Velocity	6.2 m/s	6.9 m/s	7.6 m/s	
Max TCP Acceleration	65 m/s^2	60 m/s^2	55 m/s^2	
Acceleration Time 0-1m/s	0.04 s	0.05 s	0.06 s	
Axis 3 (Z stroke) Down				
Force	250 N	250 N	250 N	
Maximum Speed				
Axis 1+ Axis 2	6.13 m/s	6.86 m/s	7.58 m/s	
Axis 3	1.02 m/s	1.02 m/s	1.02 m/s	
Axis 4	2400 deg/s	2400 deg/s	2400 deg/s	
Position Repeatability				
Axis 1+ Axis 2	<i>Axis 1+ Axis 2</i> ±0.015 mm		±0.015 mm	
Axis 3	Axis 3 ±0.01 mm		±0.01 mm	
Axis 4	±0.005 deg	±0.005 deg	±0.005 deg	

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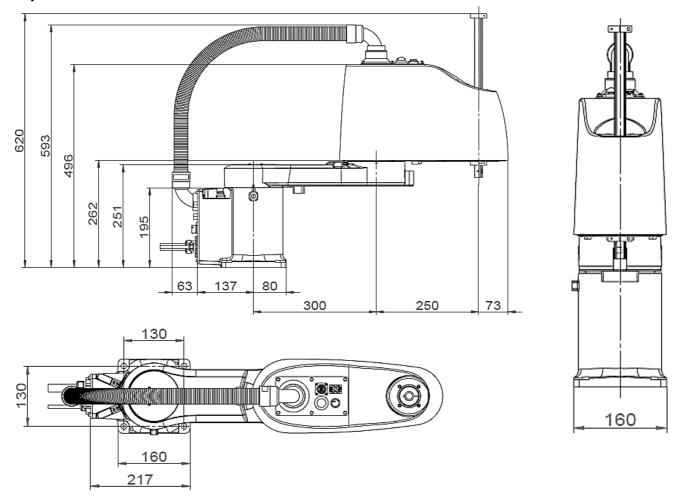


Main dimensions



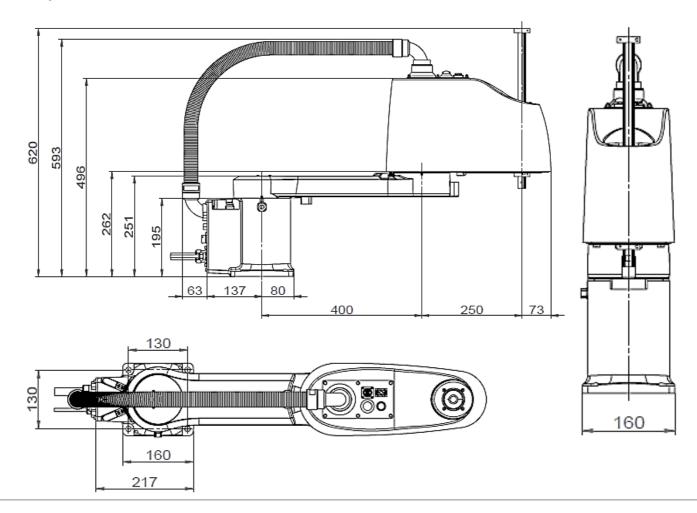


Main dimensions





Main dimensions





Outline manipulator

IRB 910SC three variances comparison







Front view

Side view

Top view



Outline manipulator

IRB 910SC - 3/ 0.55 Vs. IRB 120



Front view

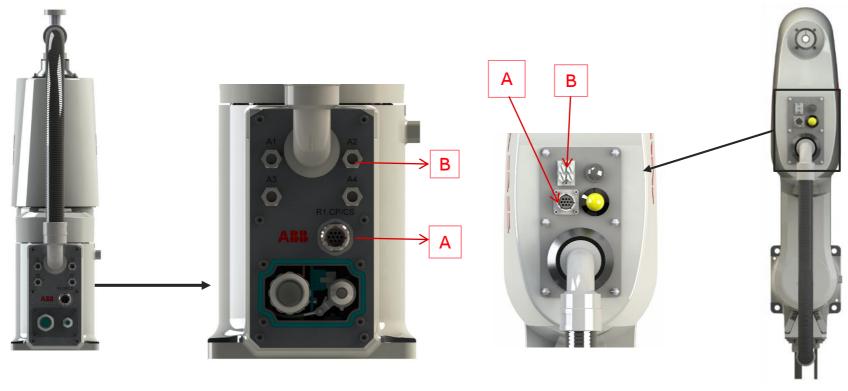
Side view

Top view



Easy integration

Customer interfaces

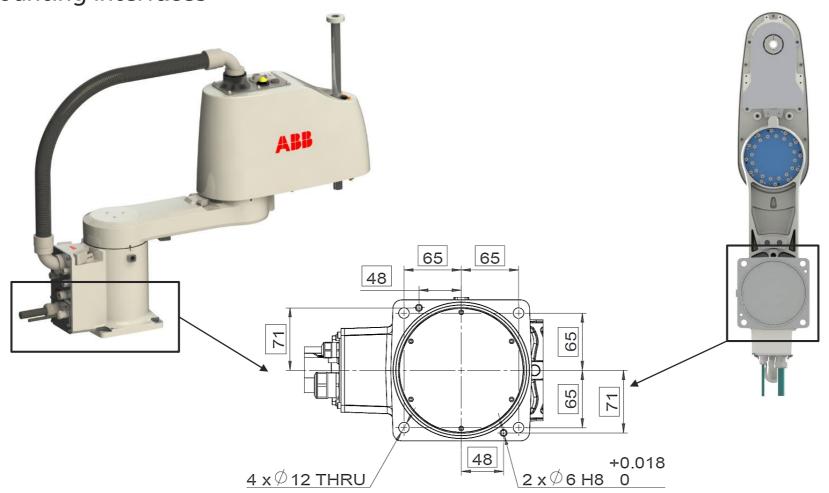


Position	Connection	Description	Number	Value
Α	(R1)R3.CP/CS	Customer power/signal	10	49√, 500mA
В	Air	Max. 5 bar	4	Inner hose diameter 4mm



Easy integration

Mounting interfaces





Easy integration

Camera mounting interfaces







Controller

IRC5 Compact



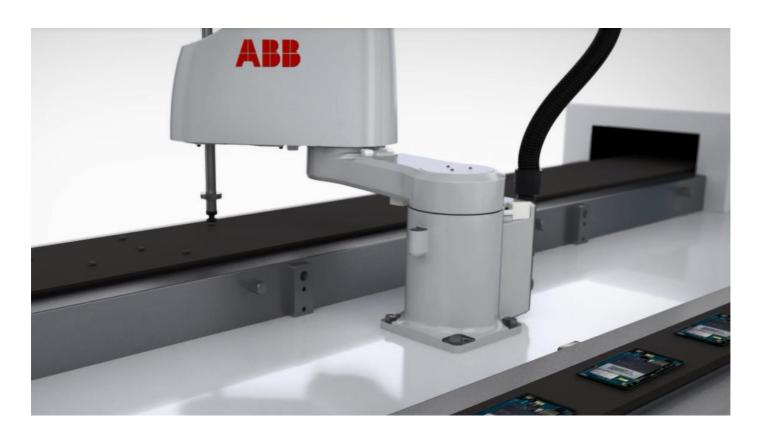


- The IRC5 Compact controller is a desktop sized robot controller designed for segments such as 3C market. The compact controller protection degree is class IP20
- Low cost
- Portable(28.5 kg)
- External connectors
- Built-in 16 in /16 out



Fast and accurate

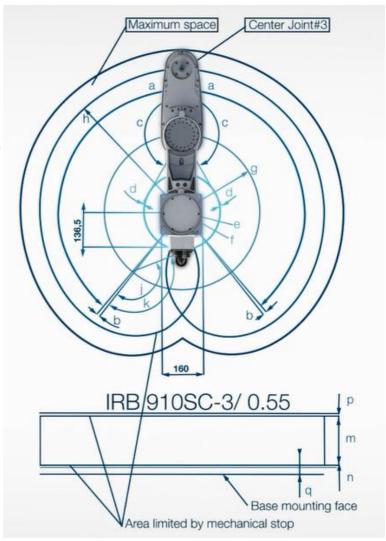
Shorter cycle time with pin point accuracy gives you a better ROI





Large working envelope

Enables the best possible use of a compact design which then enables you to handle more tasks in a defined area





Compact floor Mounting

Smaller cell design better cell layout giving a smaller footprint allowing better use of floor space





Three Variants

Common spares and platform across all models. This makes it possible to have less spares for the range





Internal Air and signals

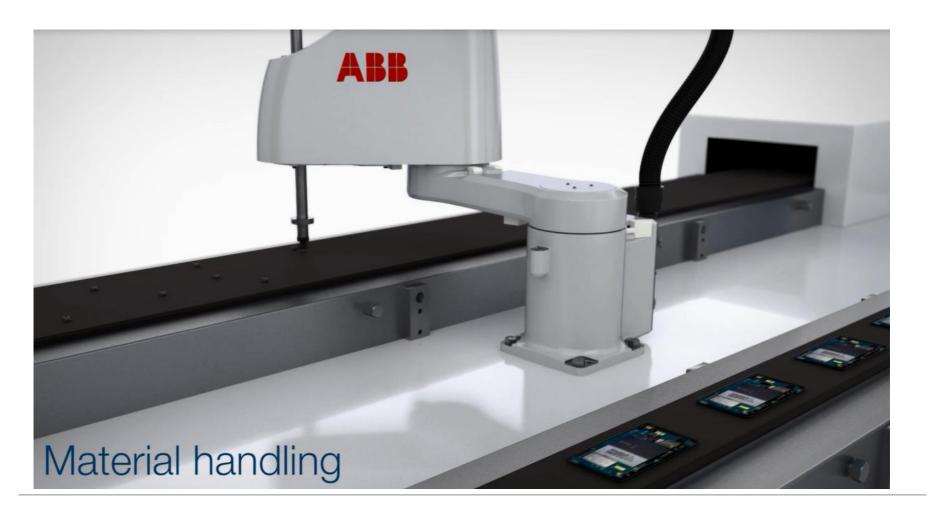
There is no need to route cables and air outside the robot, ABB has tested the solution so you don't need to worry about lifetime of the solution





Applications

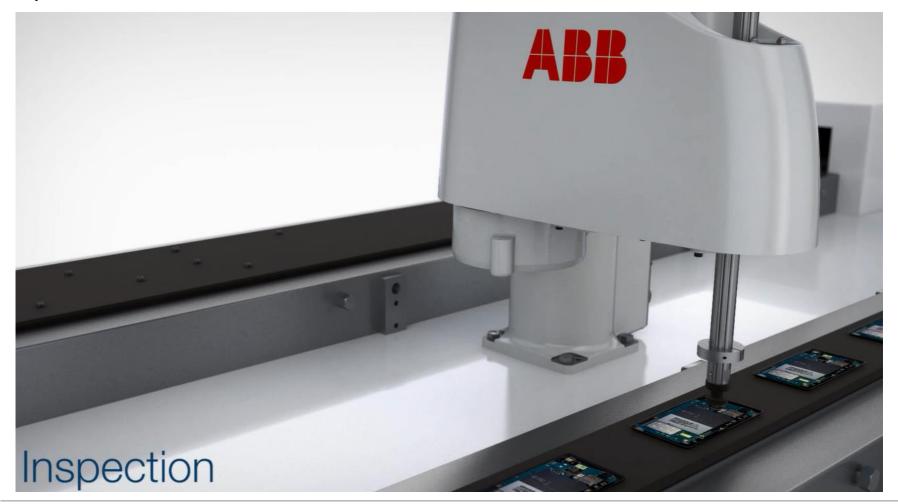
High Speed packing material handling





Applications

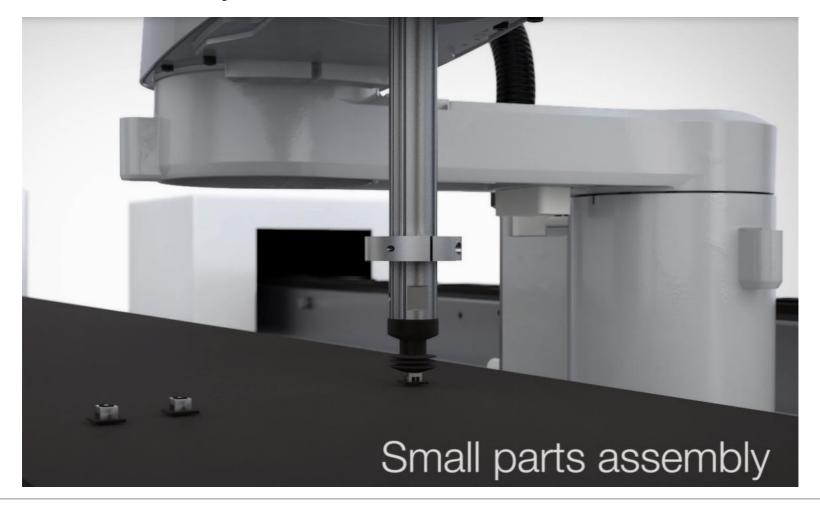
Inspection





Applications

3C Electronics assembly





Summary



 The SCARA is a product designed to be simple to integrate. Cost effective whilst providing a good return on investment.
Fast and accurate and very simple structure which makes it easer for first time robotics users

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