

# ROBOTICS

# **FlexTTH** Flexible Table Top Hemming



ABB's Table Top Hemming provides a flexible and modular solution to improve hemming quality and increase body-in-white production speed, this can reduce traditional hemming cycle time by up to 50 percent.

# High quality output with 50% shorter cycle time

ABB's Table Top Hemming provides a flexible and modular table top hemming solution and it is able to perform optimized motions with a short cycle time and high accuracy. This solution improves hemming quality and increases Body-in-White production cycle speed with a total lower cost of ownership. ABB's novel kinematic hemming motion reduces hemming cycle time and consumes less energy, with reductions of up to 50% of traditional hemming cycle time. This solution is particularly suitable for high-volume production.

#### Flexible and precise process control

Optimized kinematic itinerary makes it possible to hem up to 105° open angle in only two steps. The reinforced Gripper structure together with the proven docking design, assures a stable and effective downholder pressure. As well as being quick to configure to allow the engineer to focus on the design of blades and die. Class-A surface assembly and any quality requirement on hemming thickness and roll-in are all being considered by design simulations and maintained by a dedicated and experienced team of experts.

## Robot based technology

The Table Top Hemming uses the same IRC5 robot based technology as other ABB Robots. This means that no special software or training is required. Robot programmers and maintenance personal can immediately begin to use the product with the same interface they are used to.

## Offline programming in RobotStudio®

The hemming path can be quickly programmed offline in the ABB virtual simulation software, RobotStudio<sup>®</sup>. It can program the servo unit like a robot, and allows robot programming to be done on a PC in the office without shutting down production.

#### Advantages

- Table Top Hemming process is fast and accurate
- Space needed is less than Press Hemming
- Multiple materials can be hemmed together eg. Sheet metal + plastic.
- Optimum panel quality guaranteed through the hemming principle of the closed ring

## Features:

- Flexible and precise process control;
- Excellent hemming quality
- Quick & easy system design and setup
- Low effort trial and commission
- Short cycle time
- Integration of additional operations possible
- Minimal maintenance
- Low noise operations

#### Specifications

- Maximum weight of hemming blade 25 kg per hemming unit
- Pre hemming force up to 38KN / stroke 27mm
- Final hemming force up to 100KN / stroke 100mm
- Hemming flange angle up to 105° (tested on 110°)
- Hemming time 4 seconds
- Cycle time (Hemming + docking + undocking)
  14 seconds

01 Technical illustration

02 Technical illustration

03 Standard

Hemming Unit

04 Window Channel Hemming Unit

## Specification

	Typical Dimensions (X Y Z)	Weight
Complete Station	3.3m X 3m X 3.8m	7,000 kg
Elevator		1,584 kg
Hemming Unit		338 kg
Window Channel Unit		510 kg

# Performance

Max Blade Weight

Pre Hemming Force

Pre Hemming Stroke

Final Hemming Force

Final Hemming Stroke

Window Channel Hemming Unit

Hemming Time

Hemming Time

Elevator Stroke

Time

Pre Hemming Stroke

Final Hemming Force

Final Hemming Stroke

Angle

Hemming Flange

Hemming Station	
Cycle time	14 seconds (Docking + Hemming + UnDocking)
Standard Hemmi	ng Unit

25 kg

38 kN

27 mm

100 kN

100 mm

4 seconds

hemming.

8 seconds

20 mm

90 kN

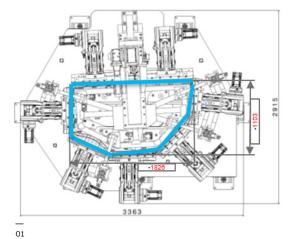
30 mm

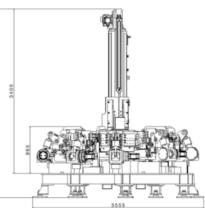
1200 mm

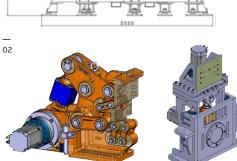
4 seconds

Up to 105 degree for two step hemming.

Up to 124 degree for three step







04

03

898

ABB AB Robotics Hydrovägen 10 SE-721 36 Västerås, Sweden Phone: +46 21325000

ABB Engineering (Shanghai) Ltd. No. 4528, Kangxin Highway, Pudong New District, Shanghai, 201319, China Phone: +86 21 6105 6666

We reserve the right to make technical changes or modify the contents of this document without prior notice. With regard to purchase orders, the agreed particulars shall prevail. ABB does not accept any responsibility whatsoever for potential errors or possible lack of information in this document.

We reserve all rights in this document and in the subject matter and illustrations contained therein. Any reproduction, disclosure to third parties or utilization of its contents - in whole or in parts - is forbidden without prior written consent of ABB. Copyright© 2017 ABB All rights reserved