

DC DRIVE - PRODUCT INFORMATION Quick start-up guide PROFIBUS DP - DCT880 and FPBA-01

Connection of DCT880 via FPBA-01 with PROFIBUS DP

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General Information

After the adapter module FPBA-01 has been mechanically and electrically installed according to the instructions in chapters Mechanical installation and Electrical installation of the fieldbus adapter manual, which is used (<u>see Related documents</u>), the communication between the thyristor power controller and the module must be set-up.

The detailed procedure of activating the module for PROFIBUS DP communication with the power controller depends on the product type. The PROFIBUS parameters in the device requires setting to establish the communication to the PLC. The following manual gives DCT880 specific start-up instructions.

Once communication between the power controller and the adapter module has been established, several configuration parameters are shown to the user. These parameters are listed in chapter <u>DCT880</u> <u>configuration as fieldbus device</u> and must be checked first and adjusted where necessary. Parameters can be adjusted via the control panel or by Drive Composer.

Note: The new parameter settings take effect only when power is cycled or when the fieldbus adapter refresh parameter (51.27 or 54.27) is used.

Related documents

A list of related manuals is provided in the <u>DCT880 Thyristor power controller Manuals</u>. Additionally the FPBA-01 user manual provides further information regarding the communication profiles and parameter settings <u>FPBA-01 PROFIBUS adapter module User manual</u>.

All information regarding DCT880 and compatible fieldbus communication adapters as well as example parameter files for FPBA-01 configuration of the DCT880 can be found in <u>DCT880 fieldbus options FW 2.01</u> and later or directly be downloaded here – <u>FPBA-01 default parameter set DCT880 3ADW000834</u>.

Firmware version

2.05.0.0 and higher.

Use the "Other..." function

E. g. connect 06.13 Global status word to 50.09 FBA A SW transparent source.



DCT880 configuration as fieldbus device

Configuration of the fieldbus adapter

Parameter group 50

To configure the DCT880 as a fieldbus device, the fieldbus adapter requires parameter configuration. In a DCT880 up to two fieldbus adapters can be configured. One as fieldbus adapter A (FBA A) and the other as fieldbus adapter B (FBA B). The following settings in Parameter group 50 will enable an FBA according to the installed slot and will read the F-series adapter information to adapt the parameter groups 51 FBA A settings or 54 FBA B setting accordingly.

| Parameter | Setting |
|-------------------------------|---|
| 50.01 FBA A enable | 0: Disable; |
| | 1: Option slot1; |
| | 2: Option slot2; here selected. |
| | 3: Option slot3; |
| | |
| 50.02 FBA A comm loss func | 0: No action; 1: Fault: occurs only when the thyristor power controller is |
| | controlled from the fieldbus. |
| | 2: Warning; |
| | 3: Last speed; |
| | 4: Speed reference safe; |
| | 5: Fault always; occurs even though no control is expected from |
| | the fieldbus. |
| 50.03 FBA A comm loss timeout | 300 ms . (default) |
| Each change in paramet | er groups 50, 51, 52 and 53 must be validated using 51.27 FBA A par |
| refresh = Refresh or for | FBA B configuration 54.27 FBA B par refresh = Refresh. |

Same is applicable for the FBA B configuration:

| Parameter | Setting |
|-------------------------------|---|
| 50.31 FBA B Enable | 0: Disable; |
| | 1: Option slot1; |
| | 2: Option slot2; here selected. |
| | 3: Option slot3; |
| | |
| 50.32 FBA B comm loss func | 0 : No action; |
| | 1: Fault; occurs only when the thyristor power controller is |
| | controlled from the fieldbus. |
| | 2: Warning; |
| | 4: Speed reference safe: |
| | 5: Fault always: occurs even though no control is expected from |
| | the fieldbus. |
| 50.33 FBA B comm loss timeout | 300 ms. |
| Each change in paramet | er groups 50, 51, 52 and 53 must be validated using 51.27 FBA A par |
| refresh = Refresh or for l | -BA B configuration 54.27 FBA B par refresh = Refresh. |

Parameter Group 51/54

Depending on the selected fieldbus adapter parameters (FBA A or FBA B) the communication settings for PROFIBUS DP must be configured in parameter group 51 for FBA A or parameter group 54 for FBA B. The below example shows the settings for PROFIBUS DP configured as FBA A in combination with the F-Series adapter FPBA-01.

| Parameter | Setting |
|-------------------------|--|
| 51.01 FBA A type | FPBA; signal thus, read-only. |
| 51.02 Node address | Each device on the PROFIBUS network must have a unique node |
| | number. This parameter defines a node number for the thyristor power |
| | controller the module is connected to. |
| 51.03 Baud rate | Read-only . Indicates the detected communication speed in kbit/s. |
| | Default value is 0 if there is no connection. |
| 51.04 MSG type | 1: PPO1; |
| | 2 : PPO2; |
| | 3 : PPO3; |
| | 4: PPO4; |
| | 5 : PP05; |
| | 6 : PPO6; |
| | 7: ST1; not recommended. |
| | 8: ST2; not recommended. |
| | 9: PPO7; |
| | 10: PPO8; example. |
| | 20: ST20; not recommended. |
| 51.05 Profile | Available profiles for PROFIBUS: |
| | PROFIdrive; not supported. |
| | ABB DRIVES; not supported. |
| | Trans16; recommended. |
| | Trans32; not recommended. |
| | PROFIdrive P; NOT supported. |
| 51.06 T16 scale | 99: Defines the scaling for reference 1 and actual 1 only with 51.02 |
| | Protocol/Profile = Trans16 . |
| | Ref type = Transparent FBA_A/B_Ref1 = Ref1_from_PLC * (T16_Scale + 1) |
| | Here example 99 \rightarrow (99 + 1) * Ref_from_PLC. |
| 51.27 FBA A par refresh | Validates any changed adapter module configuration parameter |
| | settings. After refreshing, the value reverts automatically to 0 = Done. |
| | |
| | Note: This parameter cannot be changed while the thyristor power |
| | controller is running. |
| 51.32 FBA A comm SW ver | Read-only . Displays firmware patch and build number of the adapter |
| | module in the xxyy format, where: xx = patch number/yy = build number. |
| 51.33 FBA A appl SW ver | Read-only . Displays firmware version of the adapter module in xxyy |
| | format, where: xx = major revision number/yy = minor revision number. |

Communication profile for PROFIBUS

Communication profiles are ways of conveying control commands (control word, status word, references, and actual values) between the master station and the thyristor power controller.

For DCT880 and PROFIBUS the following Transparent 16 profile is available.



¹⁾ Native profile (e.g., DCU or FBA)

Note: The diagram is applicable only when PPO messaging is used. If Standard Telegrams (ST) are used, the communication profile is selected automatically.

Communication protocol for PROFIBUS

PROFIBUS DP-V0 and DP-V1 is supported with FPBA-01. The FPBA-01 adapter uses PPOs (parameter/process data objects) for cyclic communications.

The properties and services of a PROFIBUS device are described in a GSD file. The GSD file describes the vendor specific and PROFIdrive specific features of the adapter module.

The GSD file can be downloaded for FPBA-01 (Link to webpage) or via this direct download link FPBA-01 GSD file download link.

Cyclic message types

In this guide the cyclic communication of PROFIBUS will be used. For further information regarding the PROFIBUS protocol and profile types, please refer to the according manuals. The following picture shows the PPO-types and the process data mapping according to the selected type.



OUT area – Data sent from master to slave (control data) **IN area** – Data sent from slave to master (actual data)

Parameter identification: ID – Parameter identification IND – Index for arrays VALUE – Parameter value (Max. 4 bytes) PKW – Parameter ID/value

Process data: CW – Control word SW – Status word REF – Reference ACT – Actual value PZD – Process data (application-specific) DW – Data word

In this configuration example the PPO-type PPO - 08 (parameter 51.20: PPO - 08) is used in combination with the PROFIBUS Transparent16 profile (51.02 Trans16).

Data in configuration

Setting of parameters 52.01 is fixed by the PROFIBUS DP protocol, see above diagram. Do not use **Other...** for parameters 52.01. For parameters 52.02 ... 52.12 mapping Other... is valid. Different mappings like Act1 16bit or Act2 16bit are allowed.

| Defining | efining the actual values in group 52: PLC \leftarrow DCT880. | | | | | | | | |
|----------|---|--------------------|--|--|--|--|--|--|--|
| PZD | Pointer | Setting | Remarks | | | | | | |
| 1 | 52.01 | 4: SW 16bit; | 50.09 FBA A SW transparent source = Other = 06.13[16] , for e.g., | | | | | | |
| | | | 06.13 Global Status Word. | | | | | | |
| 2 | 52.02 | 5: ACT1 16bit; | 50.10 FBA A act1 transparent source = Other = 01.92[16], for e.g., | | | | | | |
| | | | 01.92 3ph Power Full Wave Fix Cycle actual relative. | | | | | | |
| | | | 51.19 T16 scale = 99 ; sets the divisor (divisor = 51.19 + 1). | | | | | | |
| 3 | 52.03 | 6: ACT2 16bit; | 50.11 FBA A act2 transparent source = Other = 01.57[16], for e.g., | | | | | | |
| | | | 01.57 3ph Power relative actual. | | | | | | |
| | | | 51.19 T16 scale = 99 ; sets the divisor (divisor = 51.19 + 1). | | | | | | |
| 4 | 52.04 | Other; | 52.04 FBA A data in4 = Other = 06.14[16] , for e.g., 06.14 Leg1 | | | | | | |
| | | | status word (actual value 3). | | | | | | |
| | | | Scaling depends on signal/parameter. | | | | | | |
| | | | | | | | | | |
| 12 | 52.12 | Other; | 52.12 FBA A data in12 (actual value 11). | | | | | | |
| | | | Scaling depends on signal/parameter. | | | | | | |
| Λ | Each chang | ge in parameter gr | oups 50, 51, 52 and 53 must be validated using 51.27 FBA A par | | | | | | |
| | refresh = R | efresh. | | | | | | | |

The following table shows the bytes send by the DCT880 to the PLC with the above example configuration:

| 01 | 02 | 03 | 04 | 05 | 06 | 07 | 08 | | 23 | 24 |
|-------------|----|---------------------|----|--------------------|----|----------|--------|------|--------|----------|
| Status Word | | 3ph Power Full Wave | | 3ph Power relative | | Actual v | alue 4 | | Actual | value 11 |

Data out configuration with one reference

| < | Setting of parameters 53.01 is fixed by the PROFIBUS DP protocol see above table. Do not use |
|---|---|
| | Other for parameters 53.01 CW/SW are fixed by the communication protocol. |
| | For parameters 53.02 53.12 only mapping Other is valid. |
| | Different mappings like Ref1 16bit or Ref2 16bit are allowed. |
| | |

| Defining | g the referer | nce values in group | $53:$ PLC \Rightarrow DCT880. |
|----------|---------------|---------------------|---|
| PZD | Pointer | Setting | Remarks |
| 1 | 53.01 | 1: CW 16bit; | Control Word, visible in 06.03 FBA A transparent control word. |
| | | | Select by 06.08 Main control word source = FBA A . |
| 2 | 53.02 | 2: Ref1 16bit; | Reference value 1, visible in 03.05 FBA A reference 1. |
| | | | Select e. g., by 22.15 Leg 1 Cha A Main Ref Selector = FBA A |
| | | | reference 1 (03.05). |
| | | | 51.19 T16 scale = 99 ; sets the multiplier (multiplier = 51.19 + 1). |
| 3 | 53.03 | 0: None ; | Reference value 2; not used. |
| 4 | 53.04 | Other; | 53.04 FBA A data out4 = Other = e. g. 21.11 Ext reference 1 |
| | | | Scaling depends on parameter. |
| | | | |
| 12 | 53.12 | Other; | 53.12 FBA A data out12 (reference value 11). |
| | | | Scaling depends on parameter. |



Each change in parameter groups 50, 51, 52 and 53 must be validated using 51.27 FBA A par refresh = Refresh.

The following table shows the bytes send by the DCT880 power controller to the PLC with the above example configuration:

| 01 | 02 | 03 | 04 | 05 | 06 | 07 | 08 | | 23 | 24 |
|--------------|----|-------------|----|----------|----|---------|------------|------|-----------|------------|
| Control Word | | Reference 1 | | Not used | | Referen | ce value 3 | | Reference | e value 11 |

Data out configuration with three references

Setting of parameters 53.01is fixed by the PROFIBUS DP protocol see above table. Do not use
Other... for parameters 53.01 CW/SW are fixed by the communication protocol.For parameters 53.02 ... 53.12 only mapping Other... is valid.
Different mappings like Ref1 16bit or Ref2 16bit are allowed.

| Definin | g the referer | nce values in group | $53:$ PLC \Rightarrow DCT880. | | | | | | | |
|---------|---------------|---------------------|---|--|--|--|--|--|--|--|
| PZD | Pointer | Setting | Remarks | | | | | | | |
| 1 | 53.01 | 1: CW 16bit; | Control Word, visible in 06.03 FBA A transparent control word. | | | | | | | |
| | | | Select by 06.08 Main control word source = FBA A . | | | | | | | |
| 2 | 53.02 | 0: None ; | Reference value 1; not used. | | | | | | | |
| 3 | 53.03 | 0: None ; | Reference value 2; not used. | | | | | | | |
| 4 | 53.04 | Other; | 53.04 FBA A data out4 = Other = 21.11 Ext reference 1. | | | | | | | |
| | | | Select e.g., by 22.15 Leg 1 Cha A Main Ref Selector = External | | | | | | | |
| | | | reference 1 (21.11). | | | | | | | |
| | | | Scaling depends on parameter. | | | | | | | |
| 5 | 53.05 | Other; | 53.05 FBA A data out5 = Other = 21.12 Ext reference 2. | | | | | | | |
| | | | Select e.g., by 24.15 Leg 2 Cha A Main Ref Selector = External | | | | | | | |
| | | | reference 2 (21.12). | | | | | | | |
| | | | Scaling depends on parameter. | | | | | | | |
| 5 | 53.06 | Other; | 53.06 FBA A data out6 = Other = 21.13 Ext reference 3. | | | | | | | |
| | | | Select e.g., by 26.15 Leg 3 Cha A Main Ref Selector = External | | | | | | | |
| | | | reference 3 (21.13). | | | | | | | |
| | | | Scaling depends on parameter. | | | | | | | |
| | | | | | | | | | | |
| 12 | 53.12 | Other; | 53.12 FBA A data out12 (reference value 11). | | | | | | | |
| | | | Scaling depends on parameter. | | | | | | | |
| | Each chan | ge in parameter gr | oups 50, 51, 52 and 53 must be validated using 51.27 FBA A par | | | | | | | |
| | refresh = F | Refresh. | | | | | | | | |

The following table shows the bytes send by the DCT880 power controller to the PLC with the above example configuration:

| 01 | 02 | 03 | 04 | 05 | 06 | 07 | 08 | 09 | 10 | 11 | 12 | | 23 | 24 |
|--------------|----|-------|------|-------|------|-----|-------|--------|------|--------|------|------|-----------|-------------|
| Control Word | | Not u | ised | Not u | used | Ext | ref 1 | Ext re | ef 2 | Ext re | ef 3 | | Reference | ce value 11 |

Status-, control word and reference handling

After configuration of the fieldbus adapter and setting the communication profile, the correct control mode and reference handling is required.

Control word

Therefore, the main control word (MCW) source should be linked to the receiving control word (CW):

| - | | 6. Control and status words | | | |
|---|---|-----------------------------|---------------|--------|------|
| | 6 | MCW Source | FBA A (06.03) | NoUnit | None |

To switch on the DCT880 via the control word from the PLC, the command location for each leg must be defined. This can be done via parameter group **19. Start/Stop Mode**:

Command location

With one reference

| • | 19. Start/Stop Mode | | |
|----|---------------------------------|--------------------|-------------|
| 10 | Leg 1 Command Location Selector | MCW (06.01) NoUnit | Hardware DI |
| 11 | Leg 2 Command Location Selector | Hardware DI NoUnit | Hardware DI |
| 12 | Leg 3 Command Location Selector | Hardware DI NoUnit | Hardware DI |

With three references

| - | 19. Start/Stop Mode | | |
|----|---------------------------------|--------------------|-------------|
| 10 | Leg 1 Command Location Selector | MCW (06.01) NoUnit | Hardware DI |
| 11 | Leg 2 Command Location Selector | MCW (06.01) NoUnit | Hardware DI |
| 12 | Leg 3 Command Location Selector | MCW (06.01) NoUnit | Hardware DI |

Reference handling (one reference)

In this example leg 2 and leg 3 follow leg 1, see Leg 1/2/3 control mode 99.10/99.25/99.40. Thus, only one reference is required for all legs of the DCT880. Therefore, only data out2 [16] is used to send the reference from the PLC to the power controller:

| - | 53. FBA A data out | | | |
|---|--------------------|------------|--------|------|
| 1 | FBA data out1 | CW 16bit | NoUnit | None |
| 2 | FBA data out2 | Ref1 16bit | NoUnit | None |
| 3 | FBA data out3 | None | NoUnit | None |

In this example the input reference is **automatically** mapped to 03.05 FBA A reference 1. Via 22.15 Leg 1 Cha A Main Ref Selector the external reference can be mapped like this:

| • | 22. Leg 1 Reference Chain | | | |
|----|-------------------------------|---------------------------|--------|--------------------|
| 15 | Leg 1 Cha A Main Ref Selector | FBA A reference 1 (03.05) | NoUnit | Al1 scaled (12.12) |
| 16 | Leg 1 Cha A Main Ref Mux | Close | NoUnit | Close |

Reference handling (three references)

In this example leg 1, leg 2 and leg 3 are independent controlled, see Leg 1/2/3 control mode 99.10/99.25/99.40. Thus, three individual references are required for the legs of the DCT880. Therefore, data out2 [16], data out3 [16] and data out4 [16] are used to send the three references from the PLC to the power controller:

| - | 53. FBA A data out | | | |
|---|--------------------|-----------|--------|------|
| 1 | FBA data out1 | CW 16bit | NoUnit | None |
| 2 | FBA data out2 | 21.11[16] | NoUnit | None |
| 3 | FBA data out3 | 21.12[16] | NoUnit | None |
| 4 | FBA data out4 | 21.13[16] | NoUnit | None |

In this example all input references are **manually** mapped to parameters in reference parameter group 21:

- 53.02 FBA A data out2 to 21.11 Ext reference 1.
- 53.03 FBA A data out3 to 21.12 Ext reference 2.
- 53.04 FBA A data out4 to 21.13 Ext reference 3.

Via the individual Leg x Cha A Main Ref Selector the external references can be mapped like this:

| • | | 22. Leg 1 Reference Chain | | | |
|---|----|-------------------------------|------------------------------|--------|--------------------|
| | 15 | Leg 1 Cha A Main Ref Selector | External reference 1 (21.11) | NoUnit | Al1 scaled (12.12) |
| - | | 24. Leg 2 Reference Chain | | | |
| | 15 | Leg 2 Cha A Main Ref Selector | External reference 2 (21.12) | NoUnit | Al1 scaled (12.12) |
| - | | 26. Leg 3 Reference Chain | | | |
| | 15 | Leg 3 Cha A Main Ref Selector | External reference 3 (21.13) | NoUnit | Al1 scaled (12.12) |

Status word

The status word can be mapped directly to the communication profile via parameter 50.09 FBA A SW transparent source. Here as example the parameter 06.13 Global status word is transmitted to the PLC.

| • | 50. Fieldbus adapter (FBA) | | | |
|---|----------------------------|----------|--------|--------------|
| 9 | FBAA SW transparent sou | 6.13[16] | NoUnit | Not selected |

Actual values

Similar to the references, the values that are required for the PLC can be mapped directly via parameter group 52 FBA A data in:

| • | 52. FBA A data in | | | |
|---|-------------------|------------|--------|------|
| 1 | FBA A data in1 | SW 16bit | NoUnit | None |
| 2 | FBAA data in2 | Act1 16bit | NoUnit | None |
| 3 | FBA A data in3 | Act2 16bit | NoUnit | None |
| 4 | FBA A data in4 | 1.1[16] | NoUnit | None |
| 5 | FBA A data in5 | 1.2[16] | NoUnit | None |
| 6 | FBAA data in6 | 1.3[16] | NoUnit | None |

Example configuration PLC – ABB AC500

In this configuration example the following topology is used. The ABB AC500 PLC and the PC for PLC configuration, in this example shown here, are connected directly.



1) ABB AC500 PLC PROFIBUS interface

- 2) FPBA-01 connected to a DCT880
- 3) Commissioning PC

Network configuration for PROFIBUS DP

This example shows how to configure PROFIBUS DP communication between an ABB AC500 PLC and the adapter module FPBA-01 using Automation builder.

Before you start, make sure that you have downloaded the FPBA-01 GSD file from the Document library.

- 1. Start the Automation Builder software.
- 2. On the Tools menu, select Device Repository.
- 3. In the window that opens, click Install... and browse for the GSD-file.

| g Device Rep | pository | | | | × |
|----------------------|---|-------------------|----------------------|-----------------------|----------------------------|
| <u>L</u> ocation: | System Reposito (C:\ProgramDat | ory ta\Automat | onBuilder\AB_Devices | ▼ | Edit Locations |
| Installed de Name | e <u>v</u> ice descriptions liscellaneous rives ieldbusses | s: Vendor | Version | | Install |
| | LCS | | | | Renew device repository |
| | | | | | Details |
| | | | | | Close |

4. Open or create the PLC project that is used to control the thyristor power controller.

- 5. Add the CM572-DP PROFIBUS master device to the PLC project, if necessary.
- 6. Add the adapter module to the PROFIBUS network.
- 7. Add the I/O module, for example, PPO Type 8 to the adapter module to define cyclical communication between the module and the PLC.
- 8. Define the CM572-DP master properties, such as the station address, address settings for slaves and Baud rate.

| AB Test PROFIBUS.project* - Automation Builder 2.5 - Premium | | | | | - | | × |
|--|--|---------------------------------|--------------------------|-------------------|---------|---------|----|
| File Edit View Project Online Debug Tools Window Help | | | | | | | ₹ |
| 🛅 😅 🔛 🚳 い 🗠 🏘 🎼 則 🦄 🧌 App [PLC_AC500_V2: Application | n] - 😋 😋 🕞 😑 | | | | | | |
| | | | | | | | |
| Devices 👻 🗘 🗙 | Slot_1 PLC_AC500_V2 | () CM572_DP_1 () Profibus_Mas | ster_1 X | • | ToolBox | - | ąх |
| Test PROFIBUS | PPOETBUS marter | | | | | | |
| TO | PROFIBOS master | Identification | Mode | | | | |
| Application | I/O mapping list | Habat station address 120 | | | | | |
| IO_Bus | | rigilest station address. 120 💌 | | BIUISI | | | |
| - m Interfaces | | Bus parameters | | | | | |
| COM1_Online_Access (COM1 - Online Access) | | Baudrate: 1500 V kBit/s | | | | | |
| EBP Online_Access (COM2 - Online Access) | | Slot time: 300 tBi | Target rotation time: | 13382 tB i | | | |
| B 🔀 Ethernet | | Min. TSDR: 11 tBi | - | 8,9213 ms | | | |
| ETH1 (ETH1) | | Max. TSDR: 150 tBi | | | | | |
| Protocols (Protocols) | | Quiet time: 0 tBi | GAP update factor: | 10 | | | |
| Slot 1 (TA524) | | Setup time: 1 tBi | Max. retry limit: | 1 | | | |
| GM572_DP_1 (CM572-DP) | | | , | | | | |
| Profibus_Master_1 (Profibus-Master) | | Bus monitoring | Calculated timing | | | | |
| ABB_Drives_FPBA_01_DP_V0 (ABB Drives FPBA-01 DP-V0) | | Data control time: 120 ms | Tid 1: 37 tBi | values | | | |
| () PPO_08_0_PKW_12_P2D (PPO-08, 0 PKW + 12 P2D) | | Min slave interval: 2000 µs | Tid2: 150 tBi | | | | |
| | | Poll timeout: 10 ms | S | et default values | | | |
| | | | | | | | |
| | | | | | | | |
| | < | | | > | | | |
| | Messages - Total 0 error(s), 0 warning(s), : | message(s) | | * # X | | | |
| | All messages | - O error(s) 🕐 O warnin | ng(s) 🜖 0 message(s) 🗙 💥 | | | | |
| | Description | Project | Object | Position | | | |
| | | | | | | | |
| | | | | | | | |
| Paners Galactics | | | | | | | |
| U Pous a perices | | | | | | and a d | _ |

9. Define the adapter module properties: On the FPBA identification tab, select the station address.

| eneral | Identification | Parameter | Watchdog |
|--------------------|----------------------------------|----------------------|-------------------------------|
| | Station address 2 | T_SDR (tBit) | 11 🗘 Watchdog control |
|) mapping list | Identication 0x0050 | المعادية بالمعار | |
| eck configuration | Ident humber 0x0959 | Lock/Unlock | (Look) V Time (ms) 400 Groups |
| icek configuration | User parameters | | |
| formation | Symbolic values | Length of user parar | neters (byte): 34 Defaults |
| | Parameter | Value | Allowed values |
| | DP Mode | DPV0 | Bit(7) 0 0-0 |
| | Process Alarm | Disabled | Bit(6) 0 0-0 |
| | Diagnostic Alarm | Disabled | Bit(5) 0 0-0 |
| | Update Alarm | Disabled | Bit(2) 0 0-0 |
| | Alarm Mode | Type mode | BitArea(0-2) 0 0-0 |
| | Prm Structure | Enabled | Bit(3) 1 1-1 |
| | Length of User Data | 30 | Unsigned8 30 30-30 |
| | Structure Type | 129 | Unsigned8 129 129-129 |
| | Slot | 0 | Unsigned8 0 0-0 |
| | Reserved | 0 | Unsigned8 0 0-0 |
| | Fail Safe mode | Stop | BitArea(0-1) 0 0-2 |
| | Control-zero mode | Use data | BitArea(2-3) 0 0-1 |
| | Failsafe Timeout(0 = No timeout) | 30 | Unsigned 16 30 0-65535 |
| | PZD1 Failsafe value | 1150 | Unsigned 16 1150 0-65535 |
| | PZD2 Failsafe value | 0 | Unsigned 16 0 0-65535 |
| | PZD3 Failsafe value | 0 | Unsigned 16 0 0-65535 |
| | PZD4 Failsafe value | 0 | Unsigned 16 0 0-65535 |
| | PZD5 Failsafe value | 0 | Unsigned 16 0 0-65535 |
| | PZD6 Failsafe value | 0 | Unsigned 16 0 0-65535 |
| | PZD7 Failsafe value | 0 | Unsigned 16 0 0-65535 |
| | PZD8 Failsafe value | 0 | Unsigned 16 0 0-65535 |
| | PZD9 Failsafe value | 0 | Unsigned 16 0 0-65535 |
| | PZD10 Failsafe value | 0 | Unsigned 16 0 0-65535 |
| | PZD11 Failsafe value | 0 | Unsigned 16 0 0-65535 |
| | PZD 12 Failsafe value | 0 | Unsigned 16 0 0-65535 |

10. Define the I/O module properties of the PPO-08 type:

| General | Find | Find Filter Show all | | | | | | Add FB for IO Channel | | |
|-----------------------|---|----------------------|---------|-----------|------|-------------|--------------|---|--|--|
| DD Madula I/O Mapping | Variable | Mapping | Channel | Address | Туре | Unit | Description | on | | |
| DP-Module I/O Mapping | 🖃 🍋 | | Input0 | %IW2.0 | | | | | | |
| I/O mapping list | 😐 🦘 SW | *** | Word0 | %IW2.0 | WORD | | | | | |
| | | ×. | Word1 | %IW2.1 | WORD | | | | | |
| Information | 🕀 🦘 ACT2 | × | Word2 | %IW2.2 | WORD | | | | | |
| | 😟 🗄 🦄 | | Word3 | %IW2.3 | WORD | | | | | |
| | 🕀 - 🍫 | | Word4 | %IW2.4 | WORD | | | | | |
| | | | Word5 | %IW2.5 | WORD | | | | | |
| | 😟 🍫 | | Word6 | %IW2.6 | WORD | | | | | |
| | ۰. ا | | Word7 | %IW2.7 | WORD | | | | | |
| | 😟 - 🦄 | | Word8 | %IW2.8 | WORD | | | | | |
| | 😟 👋 | | Word9 | %IW2.9 | WORD | | | | | |
| | 😑 - 🍫 | | Word10 | %IW2.10 | WORD | | | | | |
| | 😟 🧤 | | Word11 | %IW2.11 | WORD | | | | | |
| | 😑 ^K . | | Output0 | %QW2.0 | | | | | | |
| | 🗄 🧖 CW | *** | Word0 | %QW2.0 | WORD | | | | | |
| | 🗷 🧖 REF1 | *** | Word1 | %QW2.1 | WORD | | | | | |
| | E NeF2 | *** | Word2 | %QW2.2 | WORD | | | | | |
| | 😟 - ^K ø | | Word3 | %QW2.3 | WORD | | | | | |
| | <u>ن</u> الله الله الله الله الله الله الله الل | | Word4 | %QW2.4 | WORD | | | | | |
| | 😟 - 🍢 | | Word5 | %QW2.5 | WORD | | | | | |
| | 😟 🍢 | | Word6 | %QW2.6 | WORD | | | | | |
| | 🖽 🍢 | | Word7 | %QW2.7 | WORD | | | | | |
| | 😟 🍢 | | Word8 | %QW2.8 | WORD | | | | | |
| | 🕀 - 🍢 | | Word9 | %QW2.9 | WORD | | | | | |
| | 🚊 🍢 | | Word 10 | %QW2.10 | WORD | | | | | |
| | 🖮 - 🍢 | | Word11 | %QW2.11 | WORD | | | | | |
| | | | | Reset Map | ping | Always upda | te variables | Use parent device se | | |

 On the **DP-Module I/O Mapping** tab, type names for the variables that refer to the device signals in the PLC program.

- 11. Open the PLC program and create a program that controls the thyristor power controller.
- 12. Compile the project and download it to the PLC.
- 13. **Note:** Make sure that the variable names defined for the device signals are used in the PLC program, too. Otherwise, the communication will not work.

| Resources | PPO_08_0_PKW_12_PZD_Module_Mapping |
|--|--|
| 다 | 0001 SW (%IW2.0) = 12 0002 ACT1 (%IW2.1) = 1197 |
| È···· 중 CM572_DP_1 È··· 중 Profibus_Master_1 | 0003 ACT2 (%IW2.2) = 1195 0004 ACT3 (%IW2.3) = 0 0005 CW (%QW2.0) = 1087 |
| PP0_08_0_PKW_12_PZD_Module_Mapping <r></r> | 0006 REF1 (%QW2.1) = 5555 0007 REF2 (%QW2.2) = 8888 |
| Variable_Configuration (VAR_CONFIG) | 0008 REF3 (%QW2.3) = 6666 |

DCS Family



DCS550-S modules The compact drive for machinery application

| 20 | | 1,000 A _{DC} |
|------|---|-----------------------|
| 0 | | $610 V_{_{DC}}$ |
| 230 | | 525 V_{AC} |
| IP00 |) | |



DCS880 modules For safe productivity

| 20 | 5,200 A _{dc} |
|------|---------------------------|
| 0 | 1,500 V _{DC} |
| 230 | 1,200 V _{AC} |
| IP00 | |



DCS880-A enclosed converters **Complete drive** solutions

20,000 A_{DC} 20 ... 0 1,500 V_{DC} 1,200 V_{AC} 230 ... IP21 – IP54



DCT880 modules Thyristor power controller

20

4,200 A_{AC} ... 990 V_{AC} 110 ... IP00

- Compact
- Robust design
- Adaptive and winder program
- · High field exciter current
- Safe torque off (STO) built in as standard
- Compact and robust
- + Single drives, 20 $\rm A_{\rm \tiny DC}$ to 5,200 $\rm A_{\rm \tiny DC}$, up to 1,500 $\rm V_{\rm \tiny DC}$
- IEC 61131 programmable
- Intuitive control panel and PC tool with USB connection and start up assistant
- Wide range of options to serve any DC motor application
- Suitable for motoric and non motoric applications (e.g. electrolysis & hydrogen production)
- Individually adaptable to customer requirements
- User-defined accessories like external PLC or automation systems can be included
- High power solutions in 6- and 12-pulse up to 20,000 A_{DC}, 1,500 V_{DC}
- In accordance to usual standards
- Individually factory load tested
- Detailed documentation
- Precise power control in industrial heating applications
- Two or three phase devices
- Power optimizer for peak load reduction
- Built on ABB's all-compatible drives architecture
- Intuitive control panel and PC tool with USB connection and start up assistant
- · Application control programs and drive application programming with IEC 61131 programming



Wallstadter-Straße 59 68526 Ladenburg • Germany Tel: +49 (0) 6203-71-0 Mail: dc-drives@de.abb.com Web: new.abb.com/drives/dc