Technical instruction ACS250 micro drives, 110-480 V Setting the motor nameplate details







Overview

ACS250 is typically configured by default to run a motor with the minimum of parameter settings required, however some basic setting of some motor parameters will always be required to provide best possible control performance and to provide suitable overload protection to the connected motor.

This technical instruction details the few basic motor parameters that are required to be set or checked when installing ACS250 in any application.

The parameters listed need to be set to the motor nameplate data values (taken from the rating plate of the motor) or to the motor manufacturer specified data (Technical specification) and entered into the ACS250 to ensure that the drive is accurately matched to the motor. Completion of this procedure will ensure best performance and avoid the risk of damage to the motor.

Rating plate parameters 9905 Motor rated voltage

The motor rated voltage in volts should be entered into this parameter.

Most industrial motors have a star/delta connection to allow operation at different voltages.

Ensure that the voltage value in this parameter corresponds to the motor terminal winding connection and the mains power supply voltage in use. An incorrect value in this parameter may reduce the motor performance or risk damaging the motor (see motor data plate examples shown in appendix).

When the correct value is entered, the ACS250 will adjust the output voltage to maintain the correct value where possible even with fluctuations in the incoming supply voltage. Setting this parameter to zero disables the voltage compensation function, meaning that the output voltage at motor rated speed/frequency will be at the same voltage as the incoming supply, with no compensation for fluctuations.

9906 Motor rated current

The motor rated current in amps should be entered into this parameter.

Care should be taken to ensure that the current rating taken from the ratings plate corresponds to the motor voltage rating in use, i.e. the star/delta connection configuration.

Typically, this will be displayed as: 220 V/400 V, 3.3 A/1.9 A. See motor data plate examples shown in appendix.

When this parameter has been set, the ACS250 will monitor the current and be able to determine whether or not the motor is in overload. Should the motor run in an overload condition for long periods of time (minutes), the ACS250 will trip. This provides one level of protection to prevent the motor from overheating.

The factory default value for this parameter is the rated current of the drive.

9907 Motor rated frequency

(

given for star

and delta

connection.

Ensure motor

configuration

matches the

ACS250 and

mains supply

in use.

The motor rated frequency in hertz should be entered into this parameter.

In general, this value will be 60 Hz so no change is required to the factory default setting.

Where high speed or special motors with alternative base frequencies are used, this parameter must be set correctly according to the motor in use, otherwise the motor may be damaged.

		ABB Motors (E **)														
		3 ~ motor M2AA 200 MLA 4														
		IEC 200 M/														
		No														
		In							s.cl.	.cl. F IP 55						
		V Hz		Hz	k۷	kW		r/min		Α		cos(φ)	IA/IN	tE/s		
		690 Y		50	30)	14	75		Ш	32.5	0.83				
		400 D	Ш	50	30)	14	75		Ш	56	0.83				
		660 Y	50		30	30		1470		34		0.83				
		380 D	50		30	30		1470		59		0.83				
		415 D	Ш	50	30)	14	1475		54		0.83				
		440 D	Ш	60	35		17	1770		Ш	59	0.83				
		Cat. no 3GAA 202 001 ADA														
6312/C3					6210/C3 180 kg) kg		
1					IEC 34-1 →											
		_	Ψ													
Dated valtages Dat					ad fue accessor					Datad anaadi				Data d accompany		
					ed frequency:					Rated speed:				Rated current:		
Enter into 9905				∟nte	ter into 9907					Enter into 9908				Enter into 9906		
Ratings are										E	Enter	value	Ш	Rating	s are	

to allow

parameters to

be displayed

and entered in

rpm. Leave at

0 for display/

programming

in hertz.

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given for star

and delta

connection.

9908 Motor rated speed in rpm

This parameter only needs to be set if the user requires the speed to be displayed in rpm, or slip compensation is required for the output frequency. Slip compensation provides a small degree of compensation for load changes meaning that the motor speed stays more constant with varying loads in comparison to when 9908=0 (display in Hz, compensation disabled).

When the rated speed has been set, all speed related parameters (e.g. maximum speed, minimum speed etc.) will be displayed in rpm rather than Hz.

The drive will also display the running speed in rpm in addition to the current in amps during normal operation.

Appendix

Below are two examples of typical motor data plates showing how the format data is typically presented and how this relates to parameters with the ACS250.

3 ~ Mot.	09413	371-	1001-B		Serial:	09	-07-162	29-	001			
kW	Hz		V	П	Α		rpm		cos (φ)			
0.37	50		220-240 D		1.85	П	1320		0.75			
0.37	50		380-415 Y		1.07	П	1320		0.75			
	7		1		1		1		'			
IEC 34-1 /	IFC 60	0034	-1	Ī	I.Class: F		IP: 55	1	Duty: S1			
		C 60034-1 I.Class: F IP: 55 Duty: S1 Weight: 6.15 kg OTOR COMPANY						'				
xxx	мото	R C	OMPANY				(ϵ			
Rated freque			ted voltage:	- 1	Rated o				Rated speed:			
Enter into 99	107	Ent	er into 9905	1	Enter in	ito	9906		Inter into 99			
		Rat	tings are		Ratings are given for star				Enter value to allow			
		giv	en for star									
		and	d delta		and delta connection.				parameters to			
		cor	nection.						be displayed			
			sure motor					11.	ınd entered i			
			nfiguration						pm. Leave a			
			tches the						for display/			
			S250 and						programming in hertz.			
	mains supply in use.							Ш	n nertz.			
Where voltage												
range is given												
			data plate									
		equal to										

drive supply voltage.

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