

Catalog | August 2016

# Low voltage IE4 synchronous reluctance motors

With expertise, and a comprehensive portfolio of products and life-cycle services, we help value-minded industrial customers improve their energy efficiency and productivity.









# IE4 synchronous reluctance motors Sizes 132 to 315

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# General information Package benefits

# Lowest energy bill with maximum availability



Traditional IE2 induction motor



The heart of the synchronous reluctance motor and drive package is a magnet-free efficiency-optimized synchronous reluctance motor. The draft standard IEC 60034-30-1 Edition 1.0 specifying IE classes applies exclusively to motors rated for line operation, which is not the case for ABB synchronous reluctance motors. Therefore, the motor does not have an IE class marking on the rating plate.

So why call the package an IE4? Because its package efficiency at the nominal operating point is the same or higher than that of a motor and drive package utilizing a motor with line-operated IE4 classification. An additional benefit related to synchronous reluctance motors is their excellent partial load efficiency performance compared to induction motors.



### Verified package efficiency

For the first time, you don't have to guess the combined energy consumption of the motor and drive for a given output power. The SynRM motor and drive package is measured to verify efficiency. When comparing efficiencies between different alternatives, make sure you're looking at efficiency values for the whole package and all the speeds that will be run. Read more about package efficiency on page 8.

# Upgrade system efficiency without mechanical modifications

Unlike many other IE4 motors, most synchronous reluctance motors follow harmonized Cenelec size and output combinations. This means that upgrading to the highest efficiency level is easy and straightforward, and there is no need for mechanical modifications, which keeps the payback time of the total investment very short.

# Ultimate efficiency and reliability to optimize your cost of ownership



#### Innovation inside

The idea is simple. Take a conventional, proven stator technology and a totally new, innovative rotor design. Then combine them with a best-in-class industrial drive loaded with new, purpose-designed software.

### Magnet-free design - Easy service

Synchronous reluctance technology combines the performance of the permanent magnet motor with the simplicity and service-friendliness of an induction motor. The new rotor has neither magnets nor windings and suffers virtually no power losses. And because there are no magnetic forces in the rotor, maintenance is as straightforward as with induction motors.

# Superior reliability to minimize the cost of not running

IE4 synchronous reluctance motors have very low winding temperatures, which increases the reliability and lifetime of

the winding. More importantly, the cool synchronous reluctance rotor means significantly lower bearing temperatures - an important factor because bearing failures cause about 70 percent of unplanned motor outages.



# Winner of the 2011 Automation Award - The 'Automations Oscars'

The new motor and drive package won Germany's most important automation award at the SPS/IPC/DRIVES trade show in Nuremberg.



SynRM technology is also available in high output motor and drive packages with up to two frame sizes smaller motor. To learn more, visit www.abb.com.

# ACS880 drive highlights



# ACS880 drive highlights

- An all-compatible drives range for numerous industries and applications: paper machines, processing lines, pumps, fans, compressors, and conveyors, among others.
- Compact design for easy installation, commissioning, and maintenance.
- Enclosure classes IP21, IP22, IP42, IP54 and IP55 for various ambient conditions.
- Integrated safety, including the safe-torque-off (STO) feature as standard.

- A memory module stores drive settings and can be installed in a new drive by anyone on the site.
- Supports various motor types: induction, permanent magnet, and synchronous reluctance motors.
- Direct torque control (DTC) ABB's signature motor control technology provides precise speed and torque control also without any feedback devices like encoders or position sensors.

Other drives are also available. Consult ABB Drives for the latest SynRM-compatible frequency converter offering.





# ACS850 drive highlights



# ACS850 drive highlights

- Designed to meet the production and performance needs of machine builders, system integrators and end users in a broad range of applications.
- Modular structure with a wide range of options means that users need to purchase only the features they require.
- Can run induction, permanent magnet, and synchronous reluctance motors, so it can be deployed on other motors if needed.
- A compact and convenient memory module stores drive settings and can be installed in a new drive by anyone on the

- Slim design means the drive occupies the minimum cabinet space.
- Drive setup simply involves entering the parameters from the motor rating plate just as with an induction motor. No encoders, position sensors or other feedback devices are needed.
- Direct torque control (DTC) ABB's signature motor control technology provides precise speed and torque control also without feedback.

Other drives are also available. Consult ABB Drives for the latest SynRM-compatible frequency converter offering.



Removable control panel



Removable memory unit

# Why settle for high motor efficiency?

Using a motor with the highest efficiency class together with speed control is a good start when it comes to minimizing your energy bill.

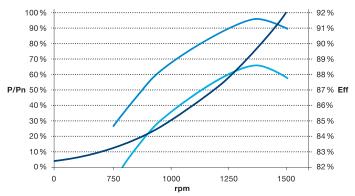
However, the IE class only indicates motor efficiency with a sinusoidal supply at nominal speed and power. This information is not relevant when calculating energy consumption in variable speed applications. Accurate calculations demand efficiency data for the whole motor-drive package and for the entire speed range.

Now – for the first time in the industry – ABB offers you the means to calculate actual energy consumption with a measured efficiency curve for the motor and drive package. Log the operating profile and energy consumption of your present system and calculate the energy consumption with the new IE4 SynRM package.

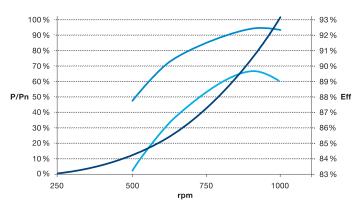
This time your calculations will be based on facts, not assumptions.

### Motor-drive package efficiency curves

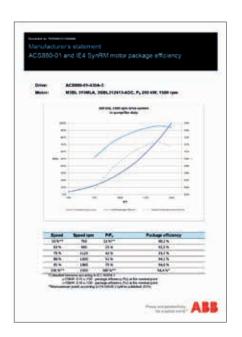
- Pump/fan power curve
- ABB IE4 SynRM & Drive
- IE2 Induction Motor & Drive

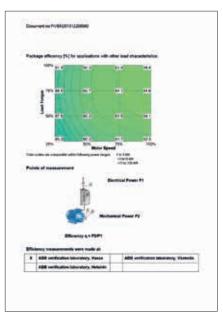


15 kW, 1500 rpm, drive system in pump/fan duty



37 kW, 1000 rpm, drive system in pump/fan duty

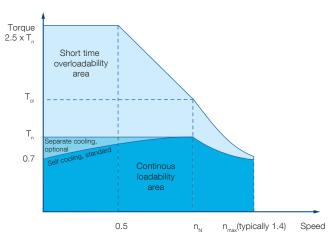




Motor-drive package efficiency data by ABB.

# IE4 synchronous reluctance motors

# Loadability



Torque characteristics of the SynRM motor

### Efficiency & MEPS

International minimum efficiency performance standards (MEPS) for measuring the efficiency of VSD-only types of motors - such as synchronous reluctance motors - are under development. No local MEPS efficiency requirements for VSDonly motors have been issued by November 2014.

#### Service

Servicing synchronous reluctance motors is as straightforward as with induction motors. The winding technology is identical to induction motors. The rotor does not include any magnetic materials, which means that the motor can be disassembled and serviced using the same procedure as for conventional induction motors. For test runs, SynRM capable frequency converter is needed.

# Why motor and drive package

New technology motors are more challenging from the control point of view than traditional induction motors. When selecting a new technology motor and drive package, it is important to ensure that the package is suitable for the application and that the drive has the right control software. The performance of synhronous reluctance motors is verified with an ABB drive. Performance and functionality with other drives cannot be guaranteed.

### Package selection

The technical data section lists matching motor and drive packages for easy package selection for pump and fan applications. Refer to ABB for package selection for other speeds or applications, or use the Drive-Size software.

#### Insulation protection

Synchronous reluctance motors motors have the same stator winding insulation as other ABB low voltage motors. The insulation is approved for 500 V VSD supply. For voltages above 500 V, follow ABB's instructions regarding the correct insulation system and the output filters of the drive.

#### Bearing currents

Synchronous reluctance motors rated above 100 kW are equipped with one insulated bearing as standard, which together with the correct cabling is sufficient to secure trouble-free operation up to 350 kW. Above 350 kW the drive should be equipped with a common-mode filter as an additional measure.

#### Cabling, grounding, and EMC

Synchronous reluctance motors are not equipped with EMC filters as standard. The variant code to order EMC cable glands is +704.

The use of a frequency converter sets higher demands on the cabling and grounding of the drive system. In other than exceptional circumstances, the motor must be cabled with shielded symmetrical cables and cable glands providing 360-degree bonding (EMC glands). For motors up to 30 kW, asymmetrical cables can be used, but shielded cables are always recommended, especially if there are sensitive components in the driven application.

For motors from frame size 280 upwards, additional potential equalization is needed between the motor frame and machinery, unless the motor and the driven machine are installed on a common steel base. When a steel base is used for potential equalization, the high frequency conductivity of the connection must be checked. For more information, see the ABB manual "Grounding and cabling of drive systems", 3AFY61201998 Rev C.

To meet EMC requirements, special EMC cables must be used in addition to the correct cable gland mounting, with additional special earthing pieces. For more information, refer to drive manuals.

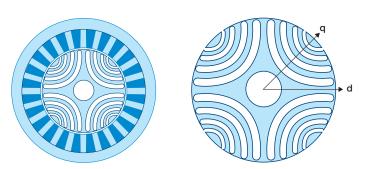
# Synchronous reluctance motor technology

#### Introduction

The synchronous reluctance motor is a three-phase electric motor with a magnetically anisotropic rotor structure. In the four-pole version, the rotor has four high- and four low-permeance axes. High permeance means high magnetic conductivity and higher inductance, while low permeance means lower inductance.

Reluctance is the inverse of permeance and is, in practical terms, magnetic resistance; high reluctance results in low inductance. The axes with high permeance can be referred to as the direct or d-axis, while the axes with high reluctance can be referred to as the quadrature or q-axis.

The figures below show cross-sectionals of a synchronous reluctance motor. The different axes in the rotor are identified in the figure on the right.



Cross-sectional illustration of a four-pole synchronous reluctance motor (left), and the definition of the magnetic d- and q-axes of its rotor (right).

# Functional principle

When a magnetic field is produced in the air gap by applying exciting currents to the stator windings, the rotor will strive to align its most magnetically conductive axis, the d-axis, with the applied field, in order to minimize the reluctance in the magnetic circuit. In other words, torque is produced in the air gap between the stator and rotor whenever the applied field vector and the d-axis of the rotor are not aligned.

The magnitude of the vector field and the speed of its rotation can be controlled by a frequency converter. The high saliency of the rotor means that its angular position can be simply detected by a sensorless control. Expensive absolute encoders, resolvers, and other rotational sensors are therefore not required.

The sensorless control system keeps track of the rotor's angular position in relation to the stator and creates a vector field with accurate magnitude and rotational speed in accordance with the control reference signals dictated by the load.

Since performance is dependent on the information about the rotor's position, the motor needs a frequency converter; it cannot be started with a direct-on-line supply. The rotor runs in synchronism with the applied vector field, striving to minimize reluctance in the magnetic circuit that is present. This functional principle has given its name to the technology - synchronous reluctance.

Synchronous reluctance motors run smoothly due to the sinusoidal air gap field distribution and operation with sinusoidal

# Rotor design

The rotor design of a synchronous reluctance motor comprises electric steel plates stacked together to form a rotor package. The electric steel plates have punched holes as flux barriers, as illustrated in the figures on the previous page.

The torque produced by the motor is proportional to the difference between the inductances on the d- and q-axes: the greater this difference, the greater the torque production. The synchronous reluctance motor is therefore designed with magnetically conductive material, iron, in the d-axis and magnetically insulating material, air, in the q-axis.

As the rotor has no windings and consequently no joule losses, it runs considerably cooler and with better efficiency than the rotor in an induction motor. The cool running of the rotor also means lower bearing temperatures, which in turn increase the reliability of the bearing system.

### **Further considerations**

Eliminating rotor joule losses in the synchronous reluctance motor has led to compact construction, good efficiency levels and cooler bearing temperatures. The main disadvantage of this technology is that the motor's power factor is generally not as good as with induction motors.

Since there is always a frequency converter between the motor and the grid, the lower power factor is not apparent on the grid side and consequently does not have an impact on the grid supply dimensioning. However, the lower power factor may sometimes mean that a frequency converter with a higher current rating is needed.

The stator and frame design are based on proven induction motor technology, and the rotor consists of only iron and air. The lack of windings and permanent magnets in the rotor eliminates potential faults associated with these components, resulting in robust motor technology optimized for industrial variable speed applications.

# Ordering information

When placing an order, specify motor type, size, and product code according to the following example.

# Explanation of the product code

Motor type	Motor size	Product code			arrangement		Generation code	Variant codes
M3BL	160 MLA	3GBL	162	413	- A	S	С	445
		1 2 3 4	5 6 7	8 9 10	11 12	13	14	15

Position	s 1 to 4
3GAL:	Totally enclosed fan-cooled synchronous reluctance motor with aluminum frame, size 132
3GBL:	Totally enclosed fan-cooled synchronous reluctance motor with cast iro frame, sizes 160 - 315
Position	s 5 and 6
IEC-fran	ne
13:	132
16:	160
18:	180
20:	200
22:	225
25:	250
28:	280
31:	315
Position	17
Pole pai	rs
2:	4 poles
Position	s 8 to 10
Running	number
Position	11
_	(dash)
Position	12
Mountin	g arrangement
A:	Foot-mounted motor
B:	Flange-mounted motor. Large flange with clearance holes.
Use a va	riant code for ordering any other mounting arrangement.
Position	
Voltage	and frequency code
Position	114
Generat	ion code
 В	High output synchronous reluctance motors
C	IE4 synchronous reluctance motors
Position	

# Mounting arrangements

#### Foot- and flange-mounted motors Code I / code II Product code pos. 12 Foot-mounted motor foot-mounted, term.box top foot-mounted term box BHS foot-mounted, term.box LHS IM B3 IM V5 IM V6 IM B6 IM B7 IM B8 IM 1001 IM 1071 IM 1011 IM 1031 IM 1051 IM 1061 Flange-mounted motor, large flange B: flange mounted, large flange IM B5 IM V1 IM V3 IM 3001 IM 3061 IM 3071 IM 3011 IM 3031 IM 3051 Flange-mounted motor, small flange flange mounted, small flange IM B14 IM V18 IM V19 IM 3601 IM 3611 IM 3631 IM 3651 IM 3661 IM 3671 Foot- and flange-mounted motor with feet, large flange foot/flange-mounted, term. box top foot/flange-mounted, term. box RHS IM B35 IM V15 IM V35 IM 2001 IM 2011 IM 2031 IM 2051 IM 2061 IM 2071 Foot- and flange-mounted motor with feet, small flange foot/flangemounted, term. box RHS IM B34 IM 2101 IM 2111 IM 2131 IM 2151 IM 2161 IM 2171 Foot-mounted motor, shaft with free extensions foot/flangemounted, small flange IM 1002 IM 1012 IM 1032 IM 1052 IM 1062 IM 1072

Note: If the motor is mounted shaft upwards, take measures to prevent water or any other liquid from running down the shaft into the motor.

<sup>\*)</sup> Not stated in IEC 60034-7.

# Rating plates

The motor's main rating plate shows the motor's performance values at nominal speed. The lubrication plate specifies regreasing amount, regreasing interval in hours - depending on the mounting position and ambient temperature - and types of lubricant recommended.

								0		
	€									
3 ~ S	ΥN	CHRONO	US RELL	ICTANCE	MOTOR	}				
M3AL	132	SMD 4 II	MB3/IM1	001				4		
45038	491	55-10		2016	No. 3	G1F1603	31085	5		
					Ins.cl	. F	IP 5	5		
V Hz kW r/min A Eff. Duty										
380	Υ	100	15	3000	33.5	93.3%		S9		
Prod.	C	ode 3G	4L13224	7-ASC						
NETW	ORK	VOLTA	GE 400	V						
					1	Vmax	4200	- /		
6308-2Z/C3 6206-2Z/C3 47 kg										
IEC 60034-1										

Main rating plate



Lubrication plate

# Technical data IE4 synchronous reluctance motors, 3000 and 1500 r/min

This table presents technical performance data for the currently available IE4 motor and drive packages. Variant codes and construction details are based on the M3BP Process performance motors.

Output kW	t Motor type	Product code	Speed n <sub>N</sub> r/min	Motor Efficiency with VSD supply	Current I <sub>N</sub> A	Torque T <sub>N</sub> Nm	Torque T <sub>oL</sub> /T <sub>N</sub> Nm	Max speed n <sub>max</sub> r/min	Inertia J kgm²	Weight m kg	Suggested ACS880 SynRM package frequency converter for light duty (**no overload)	Package efficiency IE4 SynRM & ACS880 T <sub>N</sub> = 100%, n <sub>N</sub> =100%	Typical package efficiency IE2 IM & ACS880 T <sub>N</sub> = 100%, n <sub>N</sub> =100%
3000 r/	/min (100 Hz)		400 V r	network									
5,5	M3AL 132SMA 4	3GAL132217-●SC	3000	90.9 %	12.6	17.5	1.5	4200	0.0174	41	ACS880-01-14A3-3	90.0 %	84.5 %
7,5	M3AL 132SMB 4	3GAL132227-∙SC	3000	91.7 %	16.9	23.9	1.5	4200	0.0174	41	ACS880-01-17A7-3	90.1 %	85.5 %
11	M3AL 132SMC 4	3GAL132237-●SC	3000	92.6 %	25	35	1.5	4200	0.0211	47	ACS880-01-25A5-3	89.9 %	86.7 %
15	M3AL 132SMD 4	3GAL132247-●SC	3000	93.3 %	33.5	48	1.5	4200	0.0211	47	ACS880-01-035A-3	90.0 %	87.5 %
11	M3BL 160MLA 4	3GBL162417-●SC	3000	92.6 %	25	35	1.5	4200	0.0579	133	ACS880-01-25A5-3	90.1 %	86.7 %
15	M3BL 160MLB 4	3GBL162427-●SC	3000	93.3 %	34.8	48	1.5	4200	0.0579	133	ACS880-01-035A-3	90.9 %	87.5 %
18,5	M3BL 160MLC 4	3GBL162437-●SC	3000	93.7 %	42.8	59	1.5	4200	0.0579	133	ACS880-01-043A-3	91.6 %	88.1 %
22	M3BL 180MLA 4	3GBL182417-●SC	3000	94.0 %	50	70	1.5	4200	0.0702	160	ACS880-01-050A-3	91.8 %	88.5 %
30	M3BL 200MLA 4	3GBL202417-●SC	3000	94.5 %	68.8	95	1.5	4200	0.207	259	ACS880-01-069A-3	91.8 %	88.5 %
37	M3BL 200MLB 4	3GBL202427-●SC	3000	94.8 %	84.6	118	1.5	4200	0.207	259	ACS880-01-085A-3	92.4 %	89.2 %
45	M3BL 225SMA 4	3GBL222217-●SC	3000	95.0 %	103	143	1.5	4200	0.242	282	ACS880-01-103A-3	92.8 %	90.0 %
55	M3BL 225SMF 4	3GBL222267-●SC	3000	95.3 %	122	175	1.5	4200	0.242	282	ACS880-01-123A-3	92.9 %	89.9 %
1500 r/	min (50 Hz)		400 V r	network									
5,5	M3AL 132 SMA 4	3GAL132 213-●SC	1500	91.9 %	12.1	35	1.5	2100	0.0301	63	ACS880-01-14A3-3	90.0 %	85.1 %
7,5	M3AL 132 SMB 4	3GAL132 223-●SC	1500	92.6 %	16.2	48	1.5	2100	0.0301	63	ACS880-01-17A7-3	90.1 %	86.0 %
11	M3AL 132 SMC 4	3GAL132 233-●SC	1500	93.3 %	24.0	70	1.5	2100	0.0336	69	ACS880-01-25A5-3	90.0 %	87.1 %
11	M3BL 160MLA 4	3GBL162413-●SC	1500	93.3 %	24.9	70	1.5	2100	0.0702	160	ACS880-01-25A5-3	90.9 %	87.1 %
15	M3BL 160MLB 4	3GBL162423-●SC	1500	93.9 %	33.7	95	1.5	2100	0.0864	177	ACS880-01-035A-3	91.6 %	87.9 %
18,5	M3BL 180MLA 4	3GBL182413-●SC	1500	94.2 %	42.0	118	1.5	2100	0.0864	177	ACS880-01-043A-3	92.2 %	88.4 %
22	M3BL 200MLF 4	3GBL202463-●SC	1500	94.5 %	49.1	140	1.5	2100	0.287	304	ACS880-01-050A-3	92.4 %	88.8 %
30	M3BL 200MLA 4	3GBL202413-●SC	1500	94.9 %	66.7	191	1.5	2100	0.287	304	ACS880-01-069A-3	92.8 %	89.4 %
37	M3BL 250SMF 4	3GBL252263-●SC	1500	95.2 %	82.0	236	1.5	2100	0.575	428	ACS880-01-085A-3	93.1 %	89.8 %
45	M3BL 250SMG 4	3GBL252273-●SC	1500	95.4 %	99.5	286	1.5	2100	0.575	428	ACS880-01-103A-3	93.2 %	90.2 %
55	M3BL 250SMA 4	3GBL252213-●SC	1500	95.7 %	121	350	1.5	2100	0.633	454	ACS880-01-123A-3	93.4 %	90.1 %
75	M3BL 280SMA 4	3GBL282213-●DC	1500	96.0 %	173	478	2.0	2100	1.00	639	ACS880-01-173A-3	93.7 %	90.6 %
90	M3BL 280SMB 4	3GBL282223-●DC	1500	96.1 %	202	573	2.1	2100	1.00	639	ACS880-01-202A-3	93.9 %	90.8 %
110	M3BL 280SMC 4	3GBL282233-●DC	1500	96.3 %	245	702	2.1	2100	1.21	697	ACS880-01-245A-3	94.2 %	91.1 %
110	M3BL 315SMA 4	3GBL312213-●DC	1500	96.3 %	244	702	2.0	1800	1.64	873	ACS880-01-245A-3	94.2 %	91.1 %
132	M3BL 315SMB 4	3GBL312223-●DC	1500	96.4 %	290	842	2.0	1800	1.87	925	ACS880-01-290A-3	94.2 %	91.3 %
160	M3BL 315SMC 4	3GBL312233-●DC	1500	96.6 %	343	1018	1.9	1800	2.04	965	ASC880-01-343A-3	94.5 %	91.5 %
200	M3BL 315MLA 4	3GBL312413-●DC	1500	96.7 %	427	1272	1.9	1800	2.45	1116	ACS880-01-427A-3	94.4 %	91.7 %
250	M3BL 315LKA 4	3GBL312813-●DC	1500	96.7 %	542	1591	2.0	1800	3.04	1357	ACS880-04-585A-3*	94.4 %	91.8 %
315	M3BL 315LKC 4	3GBL312833-●DC	1500	96.7 %	650	2006	1.8	1800	3.77	1533	ACS880-04-650A-3*	94.3 %	92.0 %

<sup>\*</sup> ACS880-04 drive module, protection IP 21.

<sup>\*\*</sup> Consult ABB for motor and drive dimensioning for applications with other load characteristics.

# Technical data IE4 synchronous reluctance motors, 1000 r/min

This table presents technical performance data for the currently available IE4 motor and drive packages. Variant codes and construction details are based on the M3BP Process performance motors.

Output kW	Motor type nin (33 Hz)	Product code	n <sub>N</sub> r/min	Motor Efficiency with VSD supply	Current I <sub>N</sub> A	Torque T <sub>N</sub> Nm	Torque T <sub>oL</sub> /T <sub>N</sub> Nm	Max speed n <sub>max</sub> r/min	Inertia J kgm²	Weight m kg	Suggested ACS880 SynRM package frequency converter for light duty (**no overload)	Package efficiency IE4 SynRM & ACS880 T <sub>N</sub> =100%, n <sub>N</sub> =100%	Typical package efficiency IE2 IM & ACS880 T <sub>N</sub> =100%, n <sub>N</sub> =100%
7,5	M3BL 160MLA 4	3GBL162412-•SC	1000	91.3 %	17.3	72	1.5	1400	0.0702	160	ACS880-01-17A7-3	88.9 %	84.6 %
11	M3BL 160MLB 4	3GBL162422-●SC	1000	92.3 %	25.0	105	1.5	1400	0.0864	177	ACS880-01-25A5-3	89.9 %	86.0 %
15	M3BL 200MLF 4	3GBL202462-●SC	1000	92.9 %	34.0	143	1.5	1400	0.242	282	ACS880-01-035A-3	90.6 %	87.0 %
18,5	M3BL 200MLA 4	3GBL202412-●SC	1000	93.4 %	41.8	177	1.5	1400	0.287	304	ACS880-01-043A-3	91.4 %	87.6 %
22	M3BL 200MLB 4	3GBL202422-•SC	1000	93.7 %	49.5	210	1.5	1400	0.287	304	ACS880-01-050A-3	91.4 %	88.1 %
30	M3BL 250SMF 4	3GBL252262-•SC	1000	94.2 %	67.2	286	1.5	1400	0.499	391	ACS880-01-069A-3	92.1 %	88.9 %
37	M3BL 250SMA 4	3GBL252212-●SC	1000	94.5 %	82.6	353	1.5	1400	0.575	428	ACS880-01-085A-3	92.4 %	89.4 %
45	M3BL 280SMA 4	3GBL282212-●DC	1000	94.8 %	103	430	2.3	1400	1.00	639	ACS880-01-103A-3	92.6 %	89.8 %
55	M3BL 280SMB 4	3GBL282222-●DC	1000	95.1 %	123	526	2.0	1400	1.00	639	ACS880-01-123A-3	92.8 %	89.8 %
75	M3BL 280SMC 4	3GBL282232-•DC	1000	95.4 %	166	717	2.1	1400	1.21	697	ACS880-01-173A-3	93.4 %	90.3 %
75	M3BL 315SMA 4	3GBL312212-●DC	1000	95.4 %	166	717	2.0	1400	1.64	873	ACS880-01-173A-3	93.3 %	90.3 %
90	M3BL 315SMB 4	3GBL312222-•DC	1000	95.6 %	198	859	2.0	1400	1.87	925	ACS880-01-202A-3	93.4 %	90.6 %
110	M3BL 315SMC 4	3GBL312232-●DC	1000	95.8 %	241	1051	1.9	1400	2.04	965	ACS880-01-245A-3	93.7 %	90.9 %
132	M3BL 315MLA 4	3GBL312412-●DC	1000	96.0 %	279	1261	1.7	1400	2.45	1116	ACS880-01-290A-3	93.9 %	91.1 %
160	M3BL 315LKA 4	3GBL312812-●DC	1000	96.2 %	340	1527	1.9	1400	3.04	1357	ASC880-01-343A-3	94.1 %	91.3 %
200	M3BL 315LKC 4	3GBL312832-●DC	1000	96.3 %	418	1910	1.8	1400	3.77	1533	ACS880-01-427A-3	94.1 %	91.5 %

 <sup>\*</sup> ACS880-04 drive module, protection IP 21.
 \*\* Consult ABB for motor and drive dimensioning for applications with other load characteristics.

# Variant codes IE4 synchronous reluctance motors

Variant codes specify additional options and features to the standard motor. The desired features are listed as three-digit variant codes in the motor order. Note also that there are variants that cannot be used together. In case of some variants, applicability depends not only on frame size but on package length (SM, ML, etc.).

		Frame size							
Code	Variant	132	160	180	200	225	250	280	315
dministra	ition								
30	Two-year extension on standard warranty	-	-	-	-	-	-	•	•
531	Sea freight packing	-	•	•	•	•	•	•	•
532	Packing of motor in vertical mounting position	-	-	-	-	-	-	•	•
533	Wooden sea freight packing	-	•	•	•	•	•	•	•
590	Mounting of customer supplied part other than coupling.	-	-	•	•	•	•	•	•
999	Case specific design requiring a quotation	•	•	•	•	•	•	•	•
Balancing		•	•		•	•	•	•	-
423	Balanced without key.	•	•	•	•	•	•	•	•
424	Full-key balancing	•	•	•	•	•	•	•	•
Bearings a	nd Lubrication	•							
036	Transport lock for bearings.	•	•	•	•	•	•	•	•
037	Roller bearing at D-end.	•	•	•	•	•	•	•	•
039	Cold-resistant grease	-	-	··· <del>·</del> -	-	-	-	•	•
040	Heat-resistant grease	-	-	-	-	-	-	•	•
D41	Bearings regreasable via grease nipples.	•	•	•	•	0	0	0	0
043	SPM compatible nipples for vibration measurement	•	•	•	•	0	0	0	0
057	2RS bearings at both ends.	•	•	•	•	•	•	-	-
058	Angular contact bearing at D-end, shaft force away from bearing.	•	•	•	•	•	•	•	•
)59	Angular contact bearing at N-end, shaft force towards bearing.	•	-	-	-	-	-	•	•
060	Angular contact bearing at D-end, shaft force towards bearing.		-	-	-	-	-	•	•
 061	Angular contact bearing at N-end, shaft force away from bearing.	-	-	-	-	-	-	•	•
107	Pt100 2-wire in bearings.	-	•	•	•	•	•	•	•
128	Double PT100, 2-wire in bearings	-	-	-	-	-	-	•	•
129	Double PT100, 3-wire in bearings	<del>-</del>	-	-	-	-	-	•	•
130	Pt100 3-wire in bearings.		-	-	-	-	-	•	•
194	2Z bearings greased for life at both ends.	0	0	0	0	•	•	-	-
420	Bearing mounted PTC thermistors.	-	-	-	-	-	-	•	•
433	Outlet grease collector	-	-	-	-	-	-	•	•
506	Nipples for vibration measurement : SKF Marlin Quick Connect stud CMSS-2600-3		•	•	•	•	•	•	•
654	Provision for vibration sensors (M8x1)		•	•	•	•	•	•	•
796	Grease nipples JIS B 1575 PT 1/8 Type A	-	•	•	•	•	•	•	•
797	Stainless steel SPM nipples	•	•	•	•	•	•	•	•
798	Stainless steel grease nipples	-	•	•	•	•	•	•	•
799	Grease nipples flat type DIN 3404, thread M10x1	<u>:</u> -	•	•	•	•	•	•	•
300	Grease nipples JIS B 1575 PT 1/8" pin type	···· <del>i</del> -	•	•	•	•	•	•	•
	andard designs			-		-		-	
178	Stainless steel / acid proof bolts.	•	•	•	•	•	•	•	•
204	Jacking bolts for foot mounted motors.	-	-	-	-	-	-	•	•
209	Non-standard voltage or frequency, (special winding).	•	•	•	•	•	•	•	•
217	Cast iron D-end shield (on aluminum motor).	•	-	-	-	-	-	-	-
125			-		-	-	-	•	•
Cooling sy	Corrosion protected stator and rotor core.		1			-			
	7	•	0	0	0	0	0	0	0
)53	Metal fan cover.								•

 $<sup>\</sup>circ$  = Included as standard

<sup>• =</sup> Available as option

<sup>- =</sup> Not applicable

Code	Variant	Frame 132	160	180	200	225	250	280	315
075	Cooling method IC418 (without fan).	•	-	-	-	-	-	-	-
83	Separate motor cooling (fan axial, N-end).	•	•	•	•	•	•	•	•
89	Separate motor cooling, IP44, 400V, 50Hz (fan axial, N-end).	-	•	•	•	•	•	-	-
206	Steel fan	-	-	-	-	-	-	•	•
422	Separate motor cooling (on top) with integrated fan motor	-	-	-	-	-	-	•	•
514	Separate motor cooling (an on top)	-	-	-	-	-	-	•	•
791	Stainless steel fan cover	-	-	-	-	-	-	•	•
Coupling	otamicas steer an oover				<u> </u>	<u> </u>	<u> </u>		
035	Assembly of customer supplied coupling-half.		: -	-	-	-		•	
Document					<u> </u>	<u> </u>			
141	Binding 2D main dimension drawing.		•	•		•	•		
374	· · · · · · · · · · · · · · · · · · ·	-	•	•	•	•	•	•	•
722	Binding 2D motor detailed drawing	_	•	•	•	•	•	•	
	Rotor dimension drawing (incl. torosional stiffness)								
Orain hole:	;	•		•		•	•		
065	Plugged existing drain holes.		•		•	-	-	•	
148	Draining holes with metal plugs.		-			Ĭ -		•	
Earthing B	7								1 -
067	External earthing bolt.	•	0	0	0	0	0	0	٥
Heating ele	· ·		1 _	1 -	1 _	1 _	1 -	1.	-
450	Heating element, 100-120 V	•	•	•	•	•	•	•	•
451	Heating element, 200 - 240 V	•	•	•	•	•	•	•	•
nsulation	system		,	,	,	,	,	,	,
105	Special winding insulation for frequency converter supply.	-	•	•	•	•	•	•	•
Mounting a	arrangements			,					
800	IM 2101 foot/flange mounted, IEC flange, from IM 1001 (B34 from B3).	•	-	-	-	-	-	-	-
009	IM 2001 foot/flange mounted, IEC flange, from IM 1001 (B35 from B3).	•	•	•	•	•	•	•	•
047	IM 3601 flange mounted, IEC flange, from IM 3001 (B14 from B5).	•	-	-	-	-	-	-	-
048	IM 3001 flange mounted, IEC flange, from IM 3601 (B5 from B14).	•	-	-	-	-	-	-	-
066	Modified for specified mounting position differing from IM B3 (1001), IM B5 (3001),	•	•	•	•	•	•	•	•
	B14 (3601), IM B35 (2001), IM B34 (2101)								
200	Flange ring holder.	•	-	-	-	-	-	-	-
236	Flange FT 165.	•	-	-	-	-	-	-	-
243	Flange ring FF 215.	•	-	-	-	-	-	-	-
244	Flange ring FT 215.	•	-	-	-	-	-	-	-
253	Flange ring FF 265.	•	-	-	-	-	-	-	-
254	Flange ring FT 265.	•	-	-	-	-	-	-	-
255	Flange FF 265.	•	-	-	-	-	-	-	-
305	Additional lifting lugs.	-	•	•	•	•	•	•	•
Noise redu		· ·					-		<del></del>
055	Noise reduction cover for foot mounted motor	-	-	-	-	-	-	•	•
Painting		<u>i</u>	:	<u>:</u>	<u>:</u>	<u>:</u>	<u>:</u>	-	
105	Paint thickness report.	-	•	•	•	•	•	•	•
114	Special paint color, standard grade	•	•	•	•	•	•	•	•
115	Painting system C4M acc. to ISO 12944-2: 1998.	-	•	•	•	•	•	•	•
168	Primer paint only.	-	•	•	•	•	•	•	•
710		_	•	•	•	•	•	•	•
	Thermally sprayed zink metallizing with acrylic top coat		•	•	•	•	•	•	
754	Painting system C5M acc. to ISO 12944-2:1998		<u> </u>		<u> </u>				
Protection	ř.		: .	1.	: _				1.
005	Protective roof, vertical motor, shaft down.	•	•	•	•	•	•	•	•
072	Radial seal at D-end. Not possible for 2-pole, 280 and 315 frames	•	•	•	•	•	•	•	•
073	Sealed against oil at D-end.	-	•	•	•	•	•	•	•
158	Degree of protection IP65.	•	•	•	•	•	•	•	•
101	Protective roof, horizontal motor.	-	•	•	•	•	•	•	•
103	Degree of protection IP56.	•	•	•	•	•	•	•	•
404	Degree of protection IP56, without fan and fan cover.	•	•	•	•	•	•	-	-

<sup>=</sup> Included as standard= Available as option= Not applicable

		Fram	e size						
Code	Variant	132	160	180	200	225	250	280	315
434	Degree of protection IP56, open deck.	-	-	-	-	-	-	•	•
783	Labyrinth sealing at D-end.	-	-	-	-	-	-	•	•
784	Gamma-seal at D-end.	•	•	•	•	0	0	-	-
Rating & ir	nstruction plates	•		•	•	•	•	•	-
002	Restamping voltage, frequency and output, continuous duty.	•	•	•	•	•	•	•	•
004	Additional text on std rating plate (max 12 digits on free text line).	•	•	•	•	•	•	•	•
098	Stainless rating plate.	0	0	0	0	0	0	0	0
126	Tag plate	<u>i</u> -	•	•	•	•	•	•	•
135	Mounting of additional identification plate, stainless.	•	•	•	•	•	•	•	•
138	Mounting of additional identification plate, aluminium.	•	-	-		-	-	-	-
139	Additional identification plate delivered loose.	•	•	•	•	•	•	•	•
159	Additional plate with text "Made in"		•	•	•	•	•	•	•
160		•	•	•	•	•	•	•	•
• • • • • • • • • • • • • • • • • • • •	Additional rating plate affixed.	•	•	•	•	•	•	•	
161	Additional rating plate delivered loose.	•	•	•	•	•	•	•	
163	Frequency converter rating plate. Rating data according to quotation.						·- <del> </del>		•
528	Rating plate sticker	- [-	•	•	•	•	•	•	•
Shaft & ro			1	1.	1				
069	Two shaft extensions according to catalog drawings.	•	•	•	•	•	•	•	•
070	Special shaft extension at D-End, standard shaft material	•	•	•	•	•	•	•	•
131	Motor delivered with half key (key not exceeding shaft diameter)	•	•	•	•	•	•	-	-
164	Shaft extension with closed keyway	٥	0	0	0	0	0	•	•
165	Shaft extension with open keyway	•	•	•	•	•	•	0	0
410	Shaft material stainless steel	-	<u>.</u> -	-	<u> </u>	-	-	•	•
591	Special shaft extension according to customer specification.	•	•	•	•	•	•	-	-
600	Special shaft extension at N-end, standard shaft material.		•	•	•	•	•	•	•
Standards	s and Regulations								
208	Fulfilling Underwriters Laboratories (UL), listed requirements	-	•	•	•	•	•	•	•
Stator win	ding temperature sensors								
120	KTY 84-130 (1 per phase) in stator winding.	-	•	•	•	•	•	•	•
121	Bimetal detectors, break type (NCC), (3 in series), 130 °C, in stator winding	•	•	•	•	•	•	•	•
122	Bimetal detectors, break type (NCC), (3 in series), 150 °C, in stator winding	•	•	•	•	•	•	•	•
123	Bimetal detectors, break type (NCC), (3 in series), 170 °C, in stator winding	•	•	•	•	•	•	•	•
124	Bimetal detectors, break type (NCC), (3 in series), 140 °C, in stator winding	-	•	•	•	•	•	•	•
125	Bimetal detectors, break type (NCC), (2x3 in series), 150 °C, in stator winding	•	•	•	•	•	•	•	•
127	Bimetal detectors, break type (NCC), (3 in series, 130 °C & 3 in series, 150 °C),	•	•	•	•	•	•	•	•
	in stator winding								
321	Bimetal detectors, closing type (NO), (3 in parallel), 130°C, in stator winding.	•	-	-	<del>.</del>	-	-	-	-
322	Bimetal detectors, closing type (NO), (3 in parallel), 150°C, in stator winding.	•	-	-	-	-	-	-	-
325	Bimetal detectors, closing type (NO), (2x3 in parallel), 150°C, in stator winding.	•	<u>.</u>	<u>.</u> 			-	-	-
327	Bimetal detectors, closing type (NO), (2x0 in parallel, 130°C & 3 in parallel, 150°C),	•					-		-
321									
	in stator winding.							•	
435	PTC - thermistors (3 in series), 130 °C, in stator winding	•	•	•	•	•	•	0	•
436	PTC - thermistors (3 in series), 150 °C, in stator winding					•		-	•
437	PTC - thermistors (3 in series), 170 °C, in stator winding	•	•	•	•	•	•	-	-
438	PTC - thermistors (3 in series), 190 °C, in stator winding				<u> </u>	-		•	•
439	PTC - thermistors (2x3 in series), 150 °C, in stator winding	•	•	•	•	•	•	•	•
440	PTC - thermistors (3 in series, 110°C & 3 in series, 130°C), in stator winding.	•	-	-	-	-	-	-	-
441	PTC - thermistors (3 in series, 130 °C & 3 in series, 150 °C), in stator winding	•	•	•	•	•	•	•	•
442	PTC - thermistors (3 in series, 150 °C & 3 in series, 170 °C), in stator winding	-	•	•	•	•	•	•	•
445	Pt100 2-wire in stator winding, 1 per phase	•	•	•	•	•	•	•	•
446	Pt100 2-wire in stator winding, 2 per phase	-	•	•	•	•	•	•	•
502	Pt100 3-wire in stator winding, 1 per phase	-	•	•	•	•	•	•	•
503	Pt100 3-wire in stator winding, 2 per phase	-	•	•	•	•	•	•	•
511	PTC thermistors (2 x 3 in series), 130 °C, in stator winding		•	•	•	•	•	•	•

<sup>=</sup> Included as standard
= Available as option
= Not applicable

Variant	120	160	100	200	20F	250	200	215
Variant	132	160	180	200	225	250	280	315
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otamicss steel cable hange equipped with standard moter plated brass cable glands	<u> </u>	<u> </u>	<u> </u>			<u> </u>		
Routine test report.	•	•	•	•	•	•	•	•
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(L&L equivalent)								
	Larger than standard terminal box.  Detached terminal box.  Detached terminal box.  Terminal box LHS (seen from D-end).  Cable entry LHS (seen from D-end).  Terminal box BHS (seen from D-end).  Standard metal cable gland.  Cable entry with clamping device.  Cable sealing end unit, size small for C-opening  Cable sealing end unit, size small for C-opening  Cable sealing end unit, size medium for D-opening  Cable sealing end unit, size large for D-opening  Cable sealing end unit, size large for D-opening  Cable sealing end unit, size large for D-opening  Adapter C-C  Adapter D-D  Adapter E-D  Adapter E-D  Adapter E-S  Standard plastic cable gland  Two standard plastic cable gland  Two standard plastic cable gland  Extended cable connection, no terminal box.  Separate terminal box for femperature detectors, std. material  Extended cable connection, no terminal box.  Separate terminal box for sustiliaries, standard material.  Top mounted separate terminal box for monitoring equipment.  Terminal box at N-end.  Cable entry from D-end.  Cable entry from N-end.  Separate terminal box for heating elements, std. material  Separate terminal box for brakes  Aluminum non-drilled flange for cable glands  Prepared for NPT cable glands.  Prepared for NPT cable glands.  Prepared for PQ cable glands.  Prepared for PQ cable glands.  Prepared for PG cable glands.  Prepared for PG cable glands.  Printed steel flange equipped with nickel plated brass cable glands  Stainless steel non-drilled flange for cable glands  Stainless steel non-drilled flange for mable glands  Stainless steel cable flange equipped with nickel plated brass cable glands  Printed test report.  Vibration level test  Vibration spectrum test for one motor from specific delivery batch.  Noise level test for one motor from specific delivery batch.  Noise spectrum test for one motor from specific delivery batch.  Noise spectrum test for one motor from specific delivery batch.  Noise spectrum test for one motor from specific delivery batch.  Noise spectrum test for on	Larger than standard terminal box.  Detached terminal box.  Terminal box LHS (seen from D-end).  Cable entry LHS (seen from D-end).  Terminal box degree of protection IP65.  Terminal box BHS (seen from D-end).  Terminal box BHS (seen from D-end).  Standard metal cable gland.  Cable earling and unit, size small for C-opening  Cable sealing end unit, size medium for D-opening  Cable sealing end unit, size large for D-opening  Cable sealing end unit, size large for D-opening  Adapter C-C  Adapter C-D  Adapter E-D  Adapter E-D  Standard plastic cable gland  Two standard plastic cable gland  Separate terminal box for temperature detectors, sid. material  Extended cable connection, no terminal box.  Separate terminal box for auxiliaries, standard material.  Top mounted separate terminal box for monitoring equipment.  Terminal box at N-end.  Cable entry from N-end.  Separate terminal box for brakes  Aluminum non-drilled flange for cable glands  Two standard metal cable glands.  Prepared for NPT cable glands.  Tor Scaparate terminal box for brakes  Aluminum non-drilled flange for cable glands  Trop active cover for accessory terminal block in main terminal box.  Prainted seen for NPT cable glands.  Propared for NPT cable glands.  Prepared for NPT cable glands.  Prep	Larger than standard terminal box.	Larger than standard terminal box.  Detached terminal box.  1	Larger than standard terminal box.  Detached terminal box.  Detached terminal box.  Cable entry LHS (seen from D-end).  Cable setting that the standard metal cable gland.  Cable sealing end unit, size small for C-opening  Cable sealing end unit, size large for D-opening  Proparate terminal box to temperature defectors, std. material  Propared terminal box to resultaries, standard material.  Diarger terminal box for brakes  Aluminum non-drilled flange for cable glands  Preparad for Pi Cable glands.  Protective cover for accessory terminal block in main terminal box.  Painted non-drilled flange for cable glands.  Protective	Larger than standard terminal box.  Detached terminal box.  Detached terminal box.  Terminal box LHS (seen from D-end).  Cable entry LHS (seen from D-end).  Terminal box degree of protection IP85.  Terminal box degree of protection IP85.  Terminal box RHS (seen from D-end).  Standard metal cable gland.  Cable entry with clamping device.  Cable eating and unit, size small for C-opening  Cable eating and unit, size small for C-opening  Cable sealing end unit, size large for D-opening  Adapter C-C  Adapter C-D  Adapter E-D  Adapter E-D  Standard plastic cable gland  Two standard plastic cable gland  Latended cable connection, no terminal box.  Separate terminal box for monitoring equipment.  Terminal box at N-end.  Cable entry from N-end.  Separate terminal box for beating elements, stid. material.  Top mounted separate terminal box for brakes  Aurnimum end-dilled flange for cable glands.  Prepared for NPT cable glands.  Routine test report.  Wibration level test  Wibration spectrum test for one motor from specific delivery batch.  Noise spectrum test for one motor from specific delivery batch.  Noise spectrum test for one motor from specific delivery batch.  Noise spectrum test for one motor from specific delivery batch.  Noise spectrum test for one motor from specific delivery batch.  Noise spectrum test for one motor from specific delivery batch.  Noise spectrum test for one motor from specific delivery batch.  Noise spectrum test for one motor from	Larger than standard terminal box.  Detached terminal box.  Terminal box LHS (seen from D-end).  Cable entry LHS (seen from D-end).  Terminal box RHS (seen from D-end).  Cable early with clamping device.  Cable early with clamping device.  Cable sealing end unit, size medium for D-opening  Adapter E-D  Adapter E-D  Adapter E-D  Adapter E-D  Standard plastic cable gland  Description of D-opening  Standard plastic cable gland  Description of D-opening  Standard plastic cable glands  Separate terminal box for terminal box for monitoring equipment.  Top mounted separate terminal box for auxiliaries, standard material.  Top mounted separate terminal box for braining sequipment.  Top mounted separate terminal box for braining sequipment.  Top mounted separate terminal box for monitoring equipment.  Top mounted separate terminal box for braining sequipment.  Top mounted separate terminal box for braining sequipment.  Top mounted separate terminal box for monitoring equipment.  Top mounted separate terminal box for monitoring equipment sequipment.  Top mounted separate terminal box for monitoring equipment s	Larger than standard terminal box.  Detached terminal box.  Terminal box LHS (seen from D-end).  Cable entry LHS (seen from D-end).  Terminal box (seen from D-end).  Seen from D-end).  Cable entry LHS (seen from D-end).  Standard metal cable gland.  Standard metal cable gland.  Cable entry with clamping advise.  Cable sentry with clamping advise.  Cable sentry with clamping advise.  Cable sealing and unit, aze mail or C-opening  Adapter C-O  Adapter C-O

<sup>=</sup> Included as standard= Available as option= Not applicable

		Frame size								
Code	Variant	132	160	180	200	225	250	280	315	
477	Separate motor cooling (axial fan, N-end) and 2048 pulse tacho (L&L 861007455-2048)	-	•	•	•	•	•	•	•	
478	Separate motor cooling (fan on top, N-end) and prepared for hollow shaft tacho (L&L equivalent)	-	-	-	-	-	-	•	•	
479	Mounting of other type of pulse tacho with shaft extension, tacho not included.	-	-	-	-	-	-	•	•	
486	Separate motor cooling (fan top, N-end) and prepared for DC-tacho.	-	-	-	-	-	-	•	•	
510	Separate motor cooling (fan top, N-end) and 2048 pulse tacho (Leine & Linde 861) mounted.	-	-	-	-	-	-	•	•	
570	Prepared for hollow shaft pulse tacho (L&L 503).	-	•	•	•	•	•	-	-	
572	1024 pulse tacho (L&L 503).	-	•	•	•	•	•	-	-	
573	2048 pulse tacho (L&L 503).	-	•	•	•	•	•	-	-	
582	1024 pulse tacho, GHK912-GBR-1024, BEI IDEACOD	-	-	-	-	-	-	•	•	
583	2048 pulse tacho, GHK912-GBR-2048, BEI IDEACOD	-	-	-	-	-	-	•	•	
658	Special tacho mounted, price category 1	-	-	-	-	-	-	•	•	
659	Special tacho mounted, price category 2	-	-	-	-	-	-	•	•	
660	Special tacho mounted, price category 3	-	-	-	-	-	-	•	•	
661	1024 Pulse tacho mounted, Hohner series 59, 11-30V	•	-	-	-	-	-	-	-	
662	2048 Pulse tacho mounted, Hohner series 59, 11-30V	•	-	-	-	-	-	-	-	
701	Insulated bearing at N-end.	-	•	•	•	•	•	0	0	
704	EMC cable entry.	•	•	•	•	•	•	•	•	

 <sup>=</sup> Included as standard = Available as option = Not applicable

# Mechanical design Motor frame and drain holes

#### Motor frame

Motor size 132 have aluminum alloy stator frame with integrated aluminum feet and terminal box. Motor sizes 160 and above have cast iron frame and feet and a removable terminal box. Integrated feet provide rigid mounting and minimize vibration.

Motors can be supplied for foot mounting, flange mounting, and combinations of these.

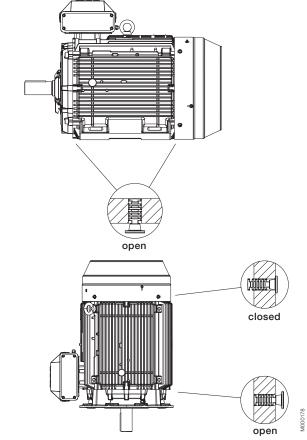
### Drain holes

Motors that will be operated in very humid or wet environments, and especially under intermittent duty, should be provided with drain holes. The IM designation, such as IM 3031, determines the intended mounting arrangement for the motor.

Motors are fitted with drain holes and closable plugs. The plugs are open on delivery. When mounting the motors, ensure that the drain holes face downwards.

In case of vertical mounting, the upper plug must be hammered home completely. In very dusty environments, both plugs should be hammered home.

When mounting differs from foot-mounted IM B3 arrangement, use variant code 066 when ordering. (See variant code 065 under Drain holes and variant code 066 under Mounting arrangements in the Variant codes section.)



As standard, the motor is delivered with drain holes and closable plugs.

# Heating elements

Heating elements are installed into windings to keep them free of corrosion in humid conditions. The required power of heating elements is shown in the table. You can order heating elements with variant code 450 or 451.

Motor size	132	160	180	200	225	250	280	315
Heating element power (W)	25	25	50	50	50	50	60	2x60

# Bearings

Synchronous reluctance motors are normally fitted with single-row deep-groove ball bearings, as shown in the table below.

If the bearing at the D-end is replaced with a roller bearing (NU- or NJ-), higher radial forces can be handled. Roller bearings are suitable for belt-drive applications.

When there are high axial forces, angular-contact ball bearings should be used. This option is available on request. When ordering a motor with an angular-contact ball bearing, specify also the method of mounting and the direction and magnitude of axial force. See Variant codes for special bearings.

#### Standard motor with deep-groove ball bearings

		Deep-groove ball bearings			
Motor size	n <sub>N</sub> r/min	D-end	N-end		
132	1500, 3000	6308-2Z/C3	6206-2Z/C3		
160	1000 - 3000	6309-2Z/C3	6209-2Z/C3		
180	1500 - 3000	6310-2Z/C3	6209-2Z/C3		
200	1000 - 3000	6312-2Z/C3	6210-2Z/C3		
225	3000	6313/C3	6210/C3		
250	1000 - 1500	6315/C3	6213/C3		
280	1000 - 1500	6316/C3	6316/C3*		
315	1000 - 1500	6319/C3	6316/C3*		

<sup>\*</sup> Insulated bearing at N-end as standard.

# Motor with roller bearings, variant code 037

Motor size	n <sub>n</sub> r/min	Roller bearings D-end
132	1500, 3000	NU 308
160	1000 - 3000	NU 309 ECP
180	1500 - 3000	NU 310 ECP
200	1000 - 3000	NU 312 ECP
225	3000	NU 313 ECP
250	1000 - 1500	NU 315 ECP
280	1000 - 1500	NU 316/C3
315	1000 - 1500	NU 319/C3

# **Axially locked bearings**

All motors are equipped as standard with an axially locked bearing at the D-end.

### **Transport locking**

Motors with roller bearings or an angular-contact ball bearing are fitted with a transport lock before dispatch to prevent damage to bearings during transport. A warning sign is attached to motors larger than 250 when transport locking is used.

Locking may also be fitted in other cases if severe transport conditions are expected.

### Bearing seals

These tables present the standard and alternative sizes and types of seals per motor size.

Standard designs						
		Standard design Axial seal				
Motor size	n <sub>N</sub> r/min	D-end	N-end			
132	1500, 3000	V-40A	Labyrinth seal			
160	1000 - 3000	V-45A	V-45A			
180	1500 - 3000	V-50A	V-45A			
200	1000 - 3000	V-60A	V-50A			
225	3000	RB65	V-50A			
250	1000 - 1500	RB75	V-65A			

Motor size		Standard design				
	n <sub>N</sub> r/min	D-end	N-end			
280	1000 - 1500	Axial seal VS80	Axial seal VS80			
315 SM, ML	1000 - 1500	Axial seal VS95	Axial seal VS80			
315 LK	1000 - 1500	Labyrinth seal	Axial seal VS80			

#### Alternative desings in motor sizes 132 – 250

Motor size	n <sub>N</sub> r/min	Alternative design, D-end Radial seal (DIN 3760), variant code 072
132	1500, 3000	40x62x7
160	1000 - 3000	45×62×8
180	1500 - 3000	50×68×8
200	1000 - 3000	60×80×8
225	3000	65×85×10
250	1000 - 1500	75×95×10

### Alternative desings in motor sizes 280 - 315

		Alternative design 1				
Motor size	n <sub>N</sub> r/min	D-end	N-end			
280	1000 - 1500	Labyrinth seal	Labyrinth seal			
315 SM, ML	1000 - 1500	Labyrinth seal	Labyrinth seal			
315 LK	1000 - 1500	(Labyrinth seal)	Labyrinth seal			

		Alternative design 2				
Motor size	n <sub>N</sub> r/min	D-end	N-end			
280	1000 - 1500	Radial seal 80×110×10	Radial seal 80×110×10			
315 SM, ML	1000 - 1500	Radial seal 95×125×10	Radial seal 80×110×10			
315 LK	1000 - 1500	(Labyrinth seal)	Radial seal 80×110×10			

# Bearing life and lubrication

#### Bearing life

The nominal life L<sub>10h</sub> of a bearing is defined according to ISO 281 as the number of operating hours achieved or exceeded by 90 % of identical bearings in a large test series under specified conditions. 50 % of bearings achieve at least five times this lifetime.

The calculated bearing life  $L_{10h}$  for power transmission by means of coupling is for horizontally mounted motors in sizes 280 to  $315 \ge 200,000$  hours.

#### Lubrication

On delivery, motors in frame size 225 and above are prelubricated with high-quality grease. Before first start-up, see instructions for relubricaton and recommended grease in the Manual for low voltage motors delivered together with the motor, or see the lubrication plate on the motor.

#### Lubrication intervals

ABB follows the L<sub>1</sub> principle in defining lubrication intervals. According to this principle, 99 % of motors will make the interval time. The synchronous reluctance motor sizes 250 to 315 have regreasable bearings as the standard solution. The lubrication intervals can also be calculated according to the  $L_{10}$  principle, which usually gives twice as long interval times. L<sub>10</sub> values are available from ABB at request.

# Motors with relubrication nipples

In frame sizes 280 – 315, the bearing system allows the use of a valve disc to ease lubrication. Motors are lubricated while running.

The grease outlet opening has closing valves at both ends. These should be opened before greasing and closed 1 - 2 hours after regreasing. This ensures that the construction is tight and bearings remain dust- and dirt-free. A grease-collection method can be used optionally.

The following tables show lubrication intervals according to the L1 principle for various nominal speeds in 25 °C ambient temperature. These values apply to horizontally mounted motors (B3) with 80 °C bearing temperature and high-quality grease containing lithium-complex soap and mineral or PAO-oil.

	Amount of grease,	Interval h at								
Frame size	g/bearing	3000 r/min	1500 r/min	1000 r/min						
Ball bearings										
132 - 200	greased for life									
225	50	6500	-	-						
250	60	-	11 500	15 000						
280	40	-	9600	14 000						
315	55	-	7600	11 800						

Lubrication intervals in duty hours for ball bearings

	Amount of grease,	Interval h at				
Frame size	g/bearing	3000 r/min	1500 r/min	1000 r/min		
Roller bearing	gs		,			
132	On request	-	-	-		
160	25	6000	10 500	12 000		
180	30	4500	9000	-		
200	40	4000	8500	11 500		
225	50	3000	-	-		
250	60	-	5500	7500		
280	40	-	5250	7000		
315	55	-	3800	5900		

Lubrication intervals in duty hours for roller bearings

#### Grease lifetime

Grease lifetime information is relevant for motors equipped with bearings greased for life, which means standard synchronous reluctance motors in frame sizes 160 - 200.

The standard bearing grease is high-quality grease intended for normal temperatures in dry or humid environments. The normal ambient temperature is 40 °C, in some cases even higher. Refer to the table below to see how temperature affects grease lifetime.

As an optional solution, grease nipples for regreasing can also be provided. See variant code 041.

The grease lifetime L<sub>10</sub>, applicable to permanently lubricated bearings, is defined as the number of operating hours after which 90 % of bearings are still adequately lubricated. 50 % of the bearings achieve twice the lifetime  $L_{10}$ .

40 000 hours should be regarded as the definitive maximum lifetime after which bearings should be replaced. Lifetime is subject to the load conditions of the application run by the motor.

Motor	Speed	Ambien	t tempera	ture and g	rease lifeti	me	
size	r/min	25 °C	40 °C	50 °C	60 °C	70 °C	80 °C
132	3000	40 000	31 000	20 000	12 000	6 000	3 000
132	1500	40 000	40 000	40 000	24 000	13 000	7 000
160	3000	40 000	40 000	40 000	26 000	14 000	8 000
160	1000 - 1500	40 000	40 000	40 000	40 000	40 000	37 000
180	3000	38 000	38 000	38 000	38 000	23 000	13 000
180	1500	40 000	40 000	40 000	32 000	28 000	15 000
200	3000	27 000	27 000	27 000	24 000	14 000	8 000
200	1000 - 1500	40 000	40 000	40 000	40 000	40 000	30 000

Grease lifetime L<sub>10</sub> in deep groove ball bearings of type 2Z, horizontally mounted motors in continuous duty

# Radial forces

# Permissible loading on the shaft

The following table shows permissible radial forces on the shaft in Newtons, assuming zero axial force, a 25 °C ambient temperature, and normal conditions. The values are given for a calculated bearing life of 20 000 and 40 000 hours per motor size.

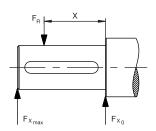
These calculated values further assume mounting position IM B3 (foot-mounted), with force directed sideways. In some cases, the strength of the shaft affects permissible forces.

Permissible loads of simultaneous radial and axial forces can be supplied on request.

If the radial force is applied between points X0 and Xmax, the permissible force FR can be calculated with the following

$$F_{R} = F_{X_{0}} - \frac{X}{E} (F_{X_{0}} - F_{X_{max}})$$

E = length of the shaft extension in the standard version.



Permissible radial forces, motor sizes 132 - 315

		1 16 6	Ball bearings			Roller bearings				
Motor	Speed	Length of shaft extension	20 000 hou	ırs	40 000 hou	ırs	20 000 ho	urs	40 000 hou	ırs
size	r/min	E (mm)	Fx <sub>0</sub> (N)	Fx <sub>max</sub> (N)	F <sub>x0</sub> (N)	Fx <sub>max</sub> (N)	Fx <sub>0</sub> (N)	Fx <sub>max</sub> (N)	Fx <sub>0</sub> (N)	Fx <sub>max</sub> (N
132	3000	80	2600	2100	2600	2100	-	-	-	-
132	1500	80	2600	2100	2600	2100	-	-	-	-
160	3000	110	5050	3900	4350	3350	6700	4300	5700	4300
160	1500	110	5400	4300	4600	3700	7550	4300	6400	4300
160	1000	110	5400	4300	4600	3700	7780	4300	6500	4300
180	3000	110	6060	4960	5280¹)	4305 <sup>1)</sup>	7600	5500	6560	5500
180	1500	110	4800	3940	4020	3300	7280	5500	6140	5500
200	3000	110	8300	6900	7200 <sup>2)</sup>	6000 <sup>2)</sup>	10 700	8900	9200	7650
200	1500	110	8900	7400	7600	6350	12 000	9550	10 150	8500
200	1000	110	8960	7480	7600	6340	12 480	9550	10 520	8780
225	3000	110	6100	5185	5155	4340	13 000	10 700	11 200	9455
250	3000	140	7700	6250	6500	5250	17 100	10 900	14 900	10 900
250	1500	140	8700	7000	7300	5900	19 800	13 800	17 000	13 800
250	1000	140	8900	7200	7355	5955	21 200	13 800	18 000	13 800
280	1500	140	9200	7800	7300	6200	25 100	9200	20 300	9200
280	1000	140	10 600	8900	8400	7000	28 300	9200	23 000	9200
315 SM_	1500	170	11 400	9400	9000	7450	32 500	9600	26 600	9600
315 SM_	1000	170	13 000	9600	10 300	8500	37 000	9600	30 000	9600
315 ML_	1500	170	11 500	9700	9100	7650	32 700	13 600	26 500	13 600
315 ML_	1000	170	13 200	11 100	10 400	8800	36 900	13 600	29 900	13 600
315 LK_	1500	170	11 500	10 000	9100	7850	33 100	13 300	26 800	13 300
315 LK_	1000	170	13 200	11 400	10 400	9000	37 300	13 300	30 300	13 300

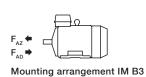
<sup>1)</sup> The maximum lifetime of the grease is 38 000 h, see Grease lifetime

<sup>2)</sup> The maximum lifetime of the grease is 27 000 h, see Grease lifetime

# Axial forces

The following tables present permissible axial forces on the shaft in Newton's, assuming zero radial force, a 25 °C ambient temperature, and normal conditions. The values are given for a calculated bearing life of 20 000 and 40 000 hours per motor size.

Permissible loads of simultaneous radial and axial forces can be supplied on request. For axial force FAD, it is assumed that the D-bearing is locked with a locking ring.





Mounting arrangement IM V1

# Permissible axial forces, motor sizes 132 - 315

			Mounting arrangement IM B3				Mounting a	Mounting arrangement IM V1			
		Length of	Ball bearin	gs			Ball bearin	gs			
Matau		shaft	20,000 h		40,000 h		20,000 h	20,000 h			
Motor size	Poles	extension E (mm)	F <sub>AD</sub> (N)	F <sub>AZ</sub> (N)	F <sub>AD</sub> (N)	F <sub>AZ</sub> (N)	F <sub>AD</sub> (N)	F <sub>AZ</sub> (N)	F <sub>AD</sub> (N)	F <sub>AZ</sub> (N)	
132	3000	80	2220	1620	1740	1140	2435	1480	1950	995	
132	1500	80	2840	2240	2205	1605	3150	2035	2515	1400	
160	3000	110	4650	4650	3850	3850	4950	4350	4200	3600	
160	1500	110	5000	5000	4200	4200	5450	4650	4600	3800	
160	1000	110	4840	4840	4000	4000	5400	4420	4540	3560	
180	3000	110	5480	5480	46001)	46001)	5920	5515	5060 <sup>1)</sup>	42551)	
180	1500	110	4360	4360	3540	3540	5080	3860	4240	3020	
200	3000	110	5000	7350	5000 <sup>2)</sup>	6150 <sup>2)</sup>	5000	7050	5000 <sup>2)</sup>	5800 <sup>2)</sup>	
200	1500	110	5000	8050	5000	6700	5000	7550	5000	6200	
200	1000	110	5000	8300	5000	6880	5000	7505	5000	6025	
225	3000	110	4860	4860	3960	3960	5000	4245	4780	3345	
250	3000	140	6000	6050	4900	4900	6000	5300	5800	4200	
250	1500	140	6000	7100	5800	5800	6000	6300	6000	4900	
250	1000	140	6000	7480	6000	6040	6000	6370	6000	4830	
280	1500	140	7900	5900	6100	4100	10 000	4500	8200	2700	
280	1000	140	9100	7100	7000	5000	11 600	5400	9500	3300	
315 SM_	1500	170	9300	7300	7100	5100	12 000	5500	9900	3300	
315 SM_	1000	170	10 700	8700	8200	6200	14 300	6300	11 800	3700	
315 ML_	1500	170	9200	7200	7000	5000	12 400	5000	10 300	2800	
315 ML_	1000	170	10 600	8600	8100	6100	14 900	5800	12 300	3200	
315 LK_	1500	170	9000	7000	6900	4900	13 600	3800	11 500	1650	
315 LK_	1000	170	10 300	8300	7800	5800	16 500	4100	14 000	1500	

<sup>1)</sup> The maximum lifetime of the grease is 38 000 h, see Grease lifetime.

 $<sup>^{\</sup>mbox{\tiny 2)}}$  The maximum lifetime of the grease is 27 000 h, see Grease lifetime.

# Terminal box Standard terminal box

# Degree of protection and mounting options

The degree of protection for the standard terminal box is IP55. By default, terminal boxes are mounted on top of the motor at D-end and can be turned 4\*90°. The terminal box can also be mounted on the left or right side of the motor (see Mounting arrangements).

#### Cable entries

Motor sizes 160 to 250 come with connection flanges with tapped cable entries and can be provided with cable glands as an option. In sizes 280 to 315 SM and 315 ML the standard terminal box has a flange with cable glands, and 315 LK has cable sealing end units. The standard flange material is siluminum. See the table below for details on standard terminal boxes.

# Cable type and terminations

If no cable type is specified in the order, it will be a PVCinsulated non-armored cable, and its termination parts are determined as shown in the table below.

Terminations are suitable for copper and aluminum cables (Al-cables on request for motor sizes 160 to 250). Cables are connected to terminals by cable lugs, which are not included in the delivery.

# **Ordering**

To ensure the delivery of desired terminations for the motor, state the cable type, quantity, size and outer diameter when ordering. Non-standard designs of terminal boxes, such as non-standard size, or higher degree of protection, are available as options.

See Variant codes for all options available.

#### Standard terminal box connections

Motor size	Speed r/min	Terminal box type	Size of flange opening	Type of through holes	Size of through holes	Cable outer diameter mm	Max. connectable core cross-section mm²/phase	Number and size of terminal bolts	Method of connection
132	1500, 3000	Integrated	-	Knock-out	2x(M40+M32+M12)	2x(Ø19-27+Ø14-21)	1x35	6xM5, 6xM6	Terminal lugs
160	1000-3000	50	Α	Threaded	2xM40x1.5	2xØ19-27	1x35	6xM6	Terminal lugs
180	1500-3000	50	Α	Threaded	2xM40x1.5	2xØ19-27	1x35	6xM6	Terminal lugs
200	1500-3000	120	В	Threaded	2xM63x1.5	2xØ34-45	1x70	6xM10	Terminal lugs
225	3000	120	В	Threaded	2xM63x1.5	2xØ34-45	1x70	6xM10	Terminal lugs
250	1000-3000	120	В	Threaded	2xM63x1.5	2xØ34-45	1x70	6xM10	Terminal lugs
280	1000-1500	210	С	Threaded*	2xM63x1.5	2xØ32-49	2x150	6xM12	Terminal lugs
315 SM, ML	1000-1500	370	D	Threaded*	2xM63x1.5	2xØ32-49	2x240	6xM12	Terminal lugs
315 LKA, LKC	1000-1500	750**	E	End unit	Medium	2xØ48-60	4x240	6xM12	Terminal lugs
Auxiliary cable	entries								
132	1500, 3000				2xM12	Ø3-6			
160-250	1000-3000	•••••			1xM16x1.5	Ø5-9			
280-315	1000-1500	•••••	•••••		2xM20x1.5	Ø8-14			

<sup>\*</sup> With cable glands of the same size

<sup>\*\*</sup> With adapter E-D and medium size end unit

Motor size	Earthing on frame	Earthing in main terminal box
132	M5	M5
160 - 200	clamp	M6
250	clamp	M8
280 - 315	M10	2xM10

Standard delivery if no other information is provided

Note: For other network voltages and/or side-mounted motors, contact your ABB sales office.

# Terminal boxes and boards

The pictures below show standard terminal boxes and the corresponding terminal boards for various motor sizes.

# Motor size 132



Fig. 1. Integrated terminal box for motor size 132. Knock-out openings for cable entries.

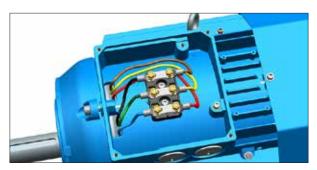


Fig. 2 Terminal board for 132.

# Motor sizes 160 - 250



Fig. 3. Terminal box for motor sizes 160 - 200. Tapped cable entries integrated in the terminal box.



Fig. 4. Terminal board for 160.

# Motor sizes 280 - 315



Fig. 5. Terminal box for motor sizes 280 - 315 SM-ML. Adapter and cable sealing end unit.

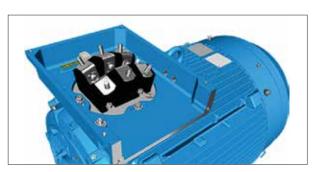


Fig. 6. Terminal board for 280 - 315 SM-ML.

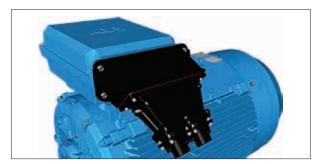


Fig. 7. Terminal box for motor size 315 LK. Adapter and cable sealing end unit.



Fig. 8. Terminal board for 315 LK.

# Terminal box Terminal box alternatives

# **Optional adapters**

There is a broad selection of cable termination accessories for the termination of one or several cables. The most common ones are presented below.







Flange with glands; cable sealing end units

# How to order

- Check first that the terminal box itself allows mounting of the desired cable and cable cores (see previous page).
- If very large cables are used, it may be necessary to use a larger terminal box than standard. Select the right cable gland(s) or cable sealing end unit(s) that match the outer diameter of the cable(s
- Select the appropriate adapter or flange.
- Note that turning the terminal box to a non-standard position may limit the use of some adapters.

# Ordering example for special cable entry and auxiliary terminal box

Motor	250 kW, 1500 rpm, 400 V 50 Hz
Cables	2 pieces, outer diameter 58 mm, single core cross
	section 185 mm <sup>2</sup> clamping device needed, cables
	coming from below

Needed one terminal box for anticondensation heaters and another for temperature detectors, material must be cast iron.

Motor	M3BL 315 MLA, 1500 rpm, B3
Adapter	D-D - variant code 293
Cable sealing end unit	Variant code 278
Clamping	Variant code 231
Auxiliaries	Variant codes 380, 567, 568

# Main terminal box and maximum single core cross-section

The terminal boxes are named according to their current-carrying capacity, from 160 to 1200. You can select one size larger than standard terminal box if a larger single cross-section is needed. The standard sizes of the main terminal box are listed in the following table. Check also the capacity of the cable entry to make sure that the cables fit. A larger terminal box can be ordered with variant code 019.

Standard terminal box	Size of opening	Max. single cross-section, mm²/phase
160	В	1×70
210	С	2×240
370	D	2×300
750	Е	4×500
1200	E	4×500

# **Optional adapters**

To allow easy termination of cables entering the terminal box from above or below, an angle adapter is recommended. These are available for motor sizes 280 - 315 and can also be used to allow the mounting of several cable sealing end units or gland plates.

Adapter	M000430	M000451	NOOM 42	MOOO4533
Variant code	292	293	294	295
Suited for motor sizes	280	315 SM, ML	315 LKA, LKC	315 LKA, LKC
Opening to terminal box	С	D	E	E
Flange or opening for end unit	С	D	D	2×D
Material	Steel	Steel	Steel	Steel
Notes			Included in type 750 terminal box when 750 is the standard size.	Only possible on type 1200 terminal box.

# Cable sealing end units

As an alternative to flanges and cable glands, cable sealing end units can be used. These allow more space for spreading the cores for easy termination. Cable sealing end units have rubber-sealed entries for one of the two main cables. In addition, there are two plugged M20 holes for auxiliary cables.

End unit	M000436	NO COO 33 T	MOOKISB
Variant code	277	278	279
Suited for motor sizes	280	315 SM, ML	315 SM, ML
Opening to terminal box	С	D	D
Cable outer diameter	1 - 2 cables, 48 - 60 mm	1 - 2 cables, 48 - 60 mm	1 - 2 cables, 60 - 80 mm
Cable entry for auxiliary cable	2×M20 plugged holes	2×M20 plugged holes	2×M20 plugged holes
Additional optional variants	EMC cable gland (704); Standard gland with clamping device (231)	EMC cable gland (704); Standard gland with clamping device (231)	EMC cable gland (704); Standard gland with clamping device (231)

# Auxiliary terminal box

You can equip motors from frame size 160 upward with one or several auxiliary terminal boxes for connection of auxiliaries like heaters or temperature detectors. The standard auxiliary terminal box material for motor sizes 280 - 315 is aluminum and for 160 - 250 cast iron. For frame sizes 280 - 315, cast iron as box material is also available as an option.

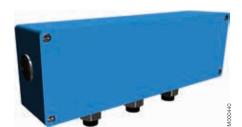
Connection terminals are of a spring-loaded type for quick and easy connection. These are suitable for up to 2.5 mm<sup>2</sup> wires. Auxiliary terminal boxes for frame sizes 280 - 315 are equipped with an earthing terminal. The first auxiliary terminal box is located on the right-hand side at D-end as standard. The standard cable entry size is M20 for both aluminum and cast iron, and the number of entries depends on the terminal box type and the number of selected auxiliaries.

Related v	ariant codes
380	Separate terminal box for temperature detectors, standard material
418	Separate terminal box for auxiliaries, standard material
567	Separate terminal box material: cast iron
568	Separate terminal box for heating elements, standard material
569	Separate terminal box for brake



Small auxiliary aluminum terminal box for motor sizes 280 - 315 (variant codes 418, 568, 380, 569)

The size of terminal box ordered with these codes depends on the number of accessories ordered. 80 x 125 mm, max 12 strips. Earthing size M4.



Large auxiliary aluminum terminal box for motor sizes 280 - 315.

The size of terminal box ordered with these codes depends on the number of accessories ordered. 80 x 250 mm, max 30 strips. Earthing size M4.



Auxiliary cast iron terminal box

Frame size for motor sizes 160 - 250 (variant code 418): 119 x 170 mm, max. 18 strips. No

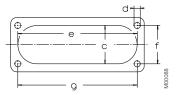
Frame size for motor sizes 280 - 315 (variant code 567): 211 x 188 mm, max 30 strips. Earthing size M6.

# Terminal box

# **Dimensions**

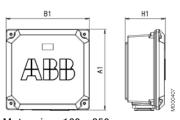
The terminal box dimensions presented on this page apply to cast-iron motors in sizes 160 - 315. For dimensions of integrated terminal boxes in aluminum motors, size 132, see the following Dimension drawings pages.

# Dimensions for terminal box inlets

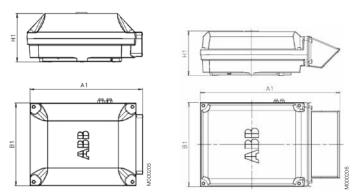


Flange opening	c mm	e mm	f mm	g mm	d thread type
В	71	194	62	193	M8
С	62	193	62	193	M8
D	100	300	80	292	M10
Е	115	370	100	360	M12

# Frame dimensions



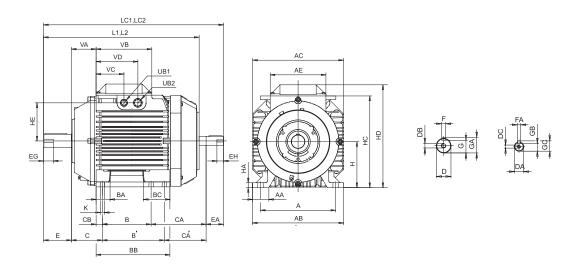
Motor sizes 160 - 250



Motor sizes 280 – 315. Top- and side-mounted terminal boxes.

Terminal box types acc. to current capacity	A1	B1	H1
Box types for 132			
Terminal box integrated in frame			
Box types for 160 - 250			
160	257	257	145
260	257	257	136
350	300	311	150
Box types for 280 - 315			
210	416	306	177
370	451	347	200
750, top-mounted	686	413	219
750, side-mounted	525	413	219

# Dimension drawings Foot-mounted motors, 132



# IM B3 (IM 1001), IM 1002

Motor size	Α	AA	AB	AC	AE	В	B'	ВА	ВВ	ВС	С	CA	CA'	СВ	D	DA	DB	DC	Е	EA	EG	EH
132 SMA-D*	216	47	262	261	160	140	178	40	212	76	89	198	160	18	38	24	M12	M8	80	50	28	19
132 SMA-B**	216	47	262	261	160	140	178	40	212	76	89	261	223	18	38	24	M12	M8	80	50	28	19
132 SMC**	216	47	262	261	160	140	178	40	212	76	89	301	263	18	38	24	M12	M8	80	50	28	19

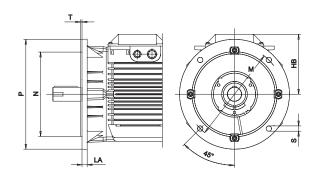
Motor size	F	FA	G	GA	GB	GC	Н	НА	НС	HD	HE	K	KA	L	LC	UB	UC	UD	VA	VB	VC	VD	VE
132 SMA-D*	10	8	33	41	20	27	132	14	263.5	295.5	109.5	12	15	487	557	M20	M25	-	71	160	80	120	-
132 SMA-B**	10	8	33	41	20	27	132	14	287	321	123.5	12	15	550	620	M40	M32	M12	71	160	42	102	136
132 SMC**	10	8	33	41	20	27	132	14	287	321	123.5	12	15	590	660	M40	M32	M12	71	160	42	102	136

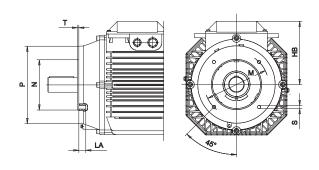
<sup>\* 3000</sup> RPM \*\* 1500 RPM

Tolerances							
A, B	± 0.8						
C, CA	± 0.8						
D, DA	ISO j6						
F, FA	ISO h9						
Н	+0 -0.5						
N	ISO j6						

# Dimension drawings

# Flange- and foot & flange-mounted motors, 132





# IM B5 (IM 3001), IM 3002

Motor size	НВ	LA	M	N	P	S	Т	
132 SMA-D*	163.5	14	265	230	300	14.5	4	
132 SMA-C**	189	14	265	230	300	14.5	4	

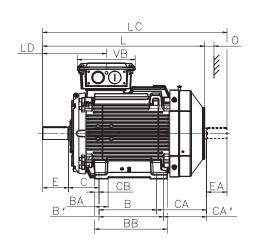
<sup>\* 3000</sup> RPM \*\* 1500 RPM

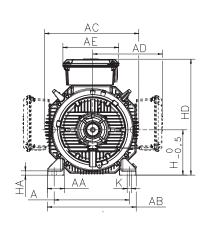
Tolerances						
A, B	± 0.8					
C, CA	± 0.8					
D, DA	ISO j6					
F, FA	ISO h9					
Н	+0 -0.5					
N	ISO j6					

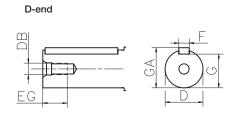
# IM B14 (IM 3601), IM 3602

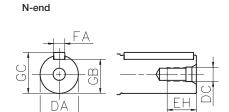
Motor size	НВ	LA	M	N	P	S	Т
132 SMA-D*	163.5	14.5	165	130	200	M10	3.5
132 SMA-C**	189	14.5	165	130	200	M10	3.5

# Dimension drawings Foot-mounted motors, 160 - 250









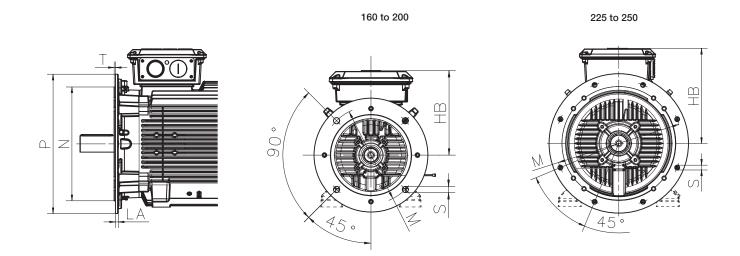
# Mounting options IM B3 (IM 1001), IM B6 (IM 1051), IM B7 (IM 1061), IM B8 (IM 1071), IM V5 (IM 1011), IM V6 (IM 1031)

Motor size	Speed r/min	Α	AA	AB	AC	AD	AE	В	B'	ВА	ВВ	С	CA	CA'	СВ	D	DA	DB	DC	E
160	3000	254	67	310	338	261	257	210	254	69	294	108	172	128	20	42	32	M16	M12	110
160	1000-1500	254	67	310	338	261	257	210	254	69	294	108	269	225	20	42	32	M16	M12	110
180	1500-3000	279	72	340	338	261	257	241	279	68	318	121	269	225	19	48	32	M16	M12	110
200	1000-3000	318	69	378	413	314	257	267	305	80	345	133	314	276	20	55	45	M20	M16	110
225	3000	356	90	435	413	328	300	286	311	69	351	149	316	291	20	55	45	M20	M16	110
250	1000-1500	406	92	480	508	376	300	311	349	69	392	168	281	243	23	65	55	M20	M20	140

Motor size	Speed r/min	EA	EG	EH	F	FA	G	GA	GB	GC	н	НА	HD	K	L	LC	LD	0	VB
160	3000	80	36	28	12	10	37	45	27	35	160	23	421	14.5	584	671.5	287.5	45	257
160	1000-1500	80	36	28	12	10	37	45	27	35	160	23	421	14.5	681	768.5	287.5	45	257
180	1500-3000	80	36	28	14	10	42.5	51.5	27	25	180	23	441	14.5	681	768.5	287.5	50	257
200	1000-3000	110	42	36	16	14	49	59	39.5	48.5	200	23	514	18.5	821	934	320.5	70	257
225	3000	110	42	42	16	16	49	59	49	59	225	23	553	18.5	821	934	320.5	80	311
250	1000-1500	110	42	42	18	16	58	69	49	59	250	23	626	24.0	884	1010	343.5	90	311

Tolerances							
A, B	ISO js14						
C, CA	± 0.8						
D, DA	ISO k6 < Ø 50 mm						
	ISO m6 > Ø 50 mm						
F, FA	ISO h9						
Н	+0 -0.5						

# Dimension drawings Flange- and foot & flange-mounted motors, 160 - 250

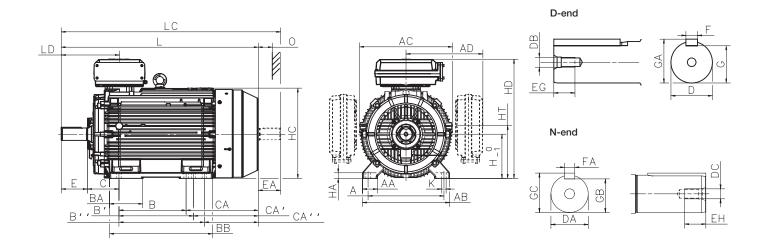


Mounting options IM B5 (IM 3001), V1 (IM 3011), V3 (IM 3031), IM B14 (IM 3601), V18 (IM 3611), V19 (IM 3631), IM B35 (IM 2001), IM V15 (IM 2011), IM V35 (IM 2031)

Flange								
Motor size	Speed r/min	НВ	LA	М	N	Р	S	т
160	1000-3000	261	20	300	250	350	19	5
180	1500-3000	261	18	300	250	350	19	5
200	1000-3000	314	20	350	300	400	19	5
225	3000	328	20	400	350	450	19	5
250	1000-1500	376	24	500	450	550	19	5

Tolerances							
A, B	ISO js14						
C, CA	± 0.8						
D, DA	ISO k6 < Ø 50 mm						
	ISO m6 > Ø 50 mm						
F, FA	ISO h9						
Н	+0 -0.5						
N	ISO j6						

# Dimension drawings Foot-mounted motors, 280 – 315



# Mounting options IM B3 (IM 1001), IM B6 (IM 1051), IM B7 (IM 1061), IM B8 (IM 1071), IM V5 (IM 1011), IM V6 (IM 1031)

Motor size	Speed r/min	Α	AA	AB	AC	AD¹)	AD <sup>2)</sup>	В	В'	В"	ВА	ВВ	С	CA	CA '	CA"	D	DA	DB	DC	E	EA
280 SM_	1000-1500	457	84	530	577	481	-	368	419	-	147	506	190	400	349	-	75	65	M20	M20	140	140
315 SM_	1000-1500	508	100	590	654	545	-	406	457	-	180	558	216	420	369	-	80	75	M20	M20	170	140
315 ML_	1000-1500	508	100	590	654	545	-	457	508	-	212	669	216	480	429	-	90	75	M24	M20	170	140
315 LK_	1000-1500	508	100	590	654	562	576	508	560	710	336	851	216	635	583	433	90	75	M24	M20	170	140

Motor size	Speed r/min	EG	EH	F	FA	G	GA	GB	GC	Н	НА	НС	HD¹) top-m.	HD <sup>2)</sup> top-m.	HT	K	L	LC	LD top-m.	LD side-m.	0
280 SM_	1000-1500	40	40	20	18	67.5	79.5	58	69	280	31	564	762	-	337.5		1088	1238		539	100
315 SM_	1000-1500	40	40	22	20	71	85	67.5	79.5		40	638	852	-	375	28	1204			615	115
315 ML_	1000-1500	48	40	25	20	81	95	67.5	79.5	315	40	638	852	-	375	28	1315	1463	386	670	115
315 LK_	1000-1500	48	40	25	20	81	95	67.5	79.5	315	40	638	852	880	359	28	1521	1669	386	751	115

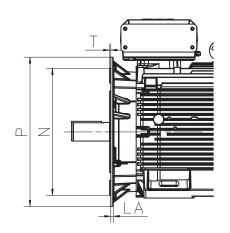
<sup>1)</sup> Terminal box 370

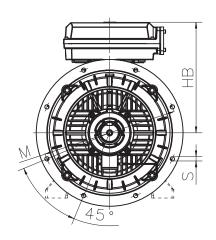
<sup>2)</sup> Terminal box 750

Tolerances								
A, B	± 0.8							
C, CA	± 0.8							
D	ISO k6 < Ø 50 mm							
	ISO m6 > Ø 50 mm							
F	ISO h9							
Н	+ 0 -0.5							
N	ISO j6							

## Dimension drawings

## Flange- and foot & flange-mounted motors, 280 - 315





Mounting options IM B5 (IM 3001)V1, (IM 3011), V3 (IM 3031), IM B14 (IM 3601), V18 (IM 3611), V19 (IM 3631), IM B35 (IM 2001), IM V15 (IM 2011), IM V35 (IM 2031)

Flange									
Motor size	Speed r/min	HB¹)	HB <sup>2)</sup>	LA	М	N	Р	s	т
280 SM_	1000-1500	482	-	23	500	450	550	18	5
315 SM_	1000-1500	537	-	25	600	550	660	23	6
315 ML_	1000-1500	537	-	25	600	550	660	23	6
315 LK_	1000-1500	537	565	25	600	550	660	23	6

<sup>1)</sup> Terminal box 370

<sup>2)</sup> Terminal box 750

Tolerand	Tolerances									
A, B	± 0.8									
D	ISO j6									
F	ISO h9									
Н	+0 - 0.1									
N	ISO j6 (280 SM_)									
	ISO js6 (315_)									
C ± 0.8										

## Accessories Separate cooling

#### Axial fan, N-end

Fan motors with an axial fan are available for motor sizes 160 - 315 and can be ordered with variant code 183. The values here are given for 400 V, but technical data for other voltages can be found in MotSize.

Axial fan	. N-end	(motor sizes	160 - 315	١

Main motor	Fan motor type (at 50 Hz)	Voltage V at 50 Hz		Current A
M3BL 160 - 250	M2VA 63 B 4 B14	400	0.18	0.61
M3BL 280 - 315 ML	M3BP 80 MD 4 B14	400	0.75	1.83
M3BL 315 LK	M3BP 90 SLD 4 B14	400	1.5	3.0

#### Fan on top, N-end

The non-axial fan available for motor sizes 280 - 315 is a Ziehl-Abegg fan with an integrated motor. This cooling option is suited for 400 V, 50 Hz networks and can be ordered with variant code 422.

#### Fan on top

Main motor	Fan motor type	Voltage V	Freq. Hz	Power kW	Current
M3BL 280	Ziehl-Abegg RH35	400 VY	50	0.35	0.83
		460 VY	60	0.5	0.9
M3BL 315	Ziehl-Abegg RH40	400 VY	50	0.50	1.0
		460 VY	60	0.8	1.4

#### Special motor and fan on top, N-end

A special ABB fan motor type is available for motor sizes 280 - 315. It is suited for environments where IP 65 is the required IP class or where the input voltage must be other than 360 -420 V (50 Hz).

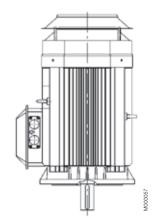
The values here are given for 400 V, but technical data for other voltages can be found in MotSize.

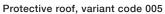
The centrifugal impeller used in the fan is a Ziehl-Abegg impeller. This type of cooling can be ordered with variant code 514.

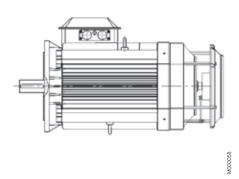
Special motor and	I fan on top			
Main motor	Fan motor type	Voltage V at 50 Hz	Power kW	Current A
M3BL 280 - 315	M3BP 80 MD 4 B34	400	0.75	1.83

## Accessories

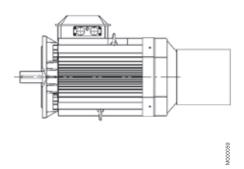
## Protective roof and tachometer







Tachometer, variant codes 472, 473, 572, and 573

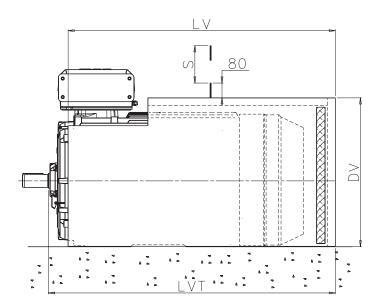


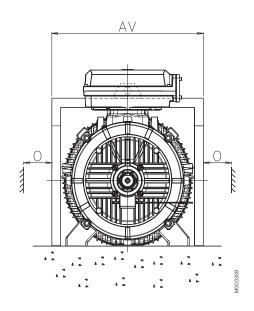
Separate cooling without tacho: 183 and 189 With tacho: 474, 476, 477, 574, 576, and 577

## Accessories Silencer for motor sizes 280 - 315

Both foot-mounted and flange-mounted motors can be fitted with a silencer to reduce noise level by about 5 - 6 dB(A). The silencer is painted blue and made of 2 mm steel sheet. The sound absorbing material is 40 mm thick polyurethane foam. On the rim there is a rubber strip for sealing on the floor. The silencer fits loosely over the motor.

The variant code for ordering a silencer is 055.





Motor size	AV	LV	LVT	DV	O 1)	S 2)	Weight kg	
280 SM_	681	1010	1090	616	50	762	38	
315 SM_	760	1094	1191	697	60	852	47	
315 ML_	760	1205	1302	697	60	852	51	
315 LK_	760	1411	1508	697	60	852	58	

<sup>1)</sup> Clearance for motor cooling

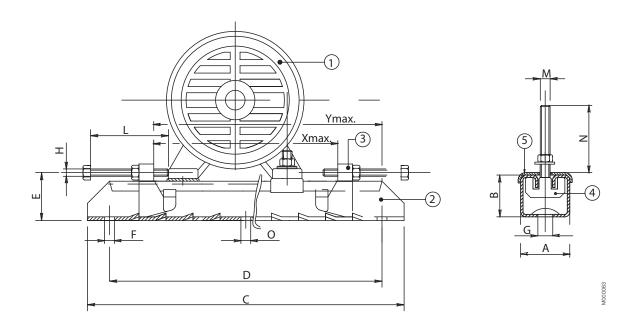
Note: The dimensions are only valid for standard foot-mounted motors.

<sup>2)</sup> Clearance for removing the silencer

### Accessories Slide rails for motor sizes 160 - 250

A set of slide rails includes two complete rails with screws for mounting the motor on the rails. Screws for mounting the rails on the foundation are not included. Slide rails have unmachined lower surfaces and should, before tightening down, be supported in a suitable manner.

Slide rails can be ordered with article numbers shown in the table.

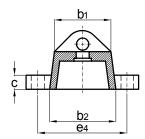


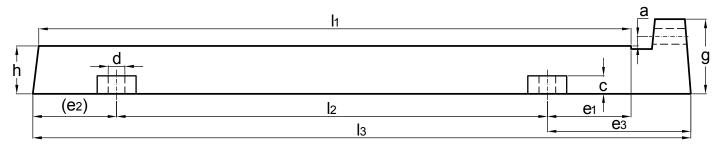
Motor size	Туре	Article no. 3GZV103001-	Α	В	С	D	Е	F	G	н	L	М	N	0	Xmax	Ymax	Weight/ rail kg
160-180	TT180/12	-14	75	42	700	630	57	17	26	M12	120	M12	50	-	520	580	12.0
200-225	TT225/16	-15	82	50	864	800	68	17	27	M16	140	M16	65	17	670	740	20.4
250	TT280/20	-16	116	70	1072	1000	90	20	27	M18	150	M20	80	20	870	940	43.0

## Accessories Slide rails for motor sizes 280 - 315

A set of slide rails includes two complete rails with screws for mounting the motor on the rails. Screws for mounting the rails on the foundation are not included. Slide rails have unmachined lower surfaces and should be supported in a suitable manner before tightening down.

Slide rails can be ordered with article numbers shown in the table.

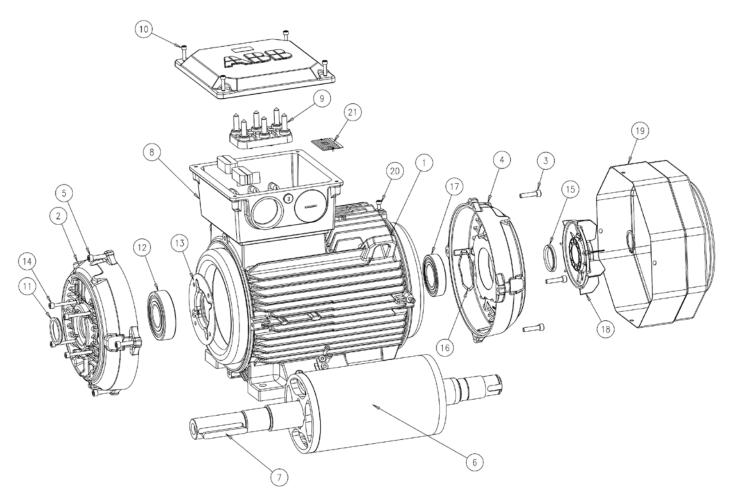




Note: The drawings are suggestive and do not give all details.

Motor															Bolts	Horizontal	Weight
size	Article no.	I,	l <sub>2</sub>	l <sub>3</sub>	a	h	b <sub>1</sub>	$b_2$	С	d	e,	$\mathbf{e}_{_{2}}$	e <sub>3</sub>	$e_4$	to feet	bolts	kg/2 pcs
280	3GZF334730-55	800	600	900	16	75	100	120	35	28	100	100	200	165	M20×90	M24×300	50
315	3GZF334730-56	1000	720	1100	16	80	120	140	40	28	140	140	240	190	M24×100	M24×300	80

## Motor construction Exploded view, frame size 160



1	Stator frame	8	Terminal box	15	Seal, N-end	
2	End shield, D-end	9	Terminal board	16	Wave spring	
3	Screws for end shield, N-end	10	Screws for terminal box cover	17	Bearing, N-end	
4	End shield, N-end	11	Seal, D-end	18	Fan	
5	Screws for end shield, D-end	12	Bearing, D-end	19	Fan cover	
6	Rotor with shaft	13	Inner bearing cover, D-end	20	Screws for fan cover	
7	Key, D-end	14	Screws for bearing cover	21	Rating plate	

## Motors in brief IE4 synchronous reluctance motors

Motor size		132	160	180	200	225	250	280	315					
Stator and	Material	Die-cast aluminum alloy	Cast iron	•	•	•	•	•	•					
end shields	Paint color shade	Munsell blue 8B 4.5/3.25		•••••	. •••••••••	•								
	Corrosion class	Polyester powder paint	C3 (medium)	according to I	SO/EN 12944-	5	•							
Bearings	D-end	6308-2Z/C3	6309-2Z/C3	6310-2Z/C3	6312-2Z/C3	6313/C3	6315/C3	6316/C3	6319/C3					
	N-end	6206-2Z/C3	6209-2Z/C3 6209-2Z/C3 6210-2Z/C3 6210/C3 6					6316/C3*	6316/C3*					
Axially locked bear	ings	Locked at D-end	D-end											
Bearing seals		D-end: V-ring	V-ring or gan	nma seal as sta	andard, radial	seal on reque	st. See the	V-ring or lal	oyrinth seal as					
		N-end: Labyrinth seal	Bearing seal	s page for opti	ons.			standard. S	ee the Bearing					
								seals page	for options.					
Lubrication		Permanently lubricated sh	nielded bearing	s,		Regreasabl	e bearings,	Regreasabl	e bearings,					
		wide-temperature-range of	grease			regreasing	nipples M6×1	regreasing	nipples M10×1					
Measuring nipples		Not included	SPM as an o	ption			SPM as star	ndard						
Rating plate	Material	Aluminum	Stainless ste	el	•									
Terminal box	Frame material	Die-cast aluminum alloy,	Cast iron											
		integrated in stator												
	Corrosion class	Polyester powder paint	C3 (medium)	according to I	SO/EN 12944-	5								
	Cover screws		Zinc-electro	olated steel										
Connections	Cable entries	2x(M40+M32+M12)	2xM40x1,5, 1	IxM16x1,5**	2×M63×1.5,	1×M16×1.5**		2×M63×1.5, 2×M20×1.5**						
	Terminals	6 terminals with lugs	6 terminals**	*										
	Cable glands	Integrated knock-out	Flange as standard, cable glands as option Cable flange and glands											
		openings; no cable							as standard					
		glands												
Fan	Material	Glass-fiber-reinforced pol	ypropylene											
Fan cover	Material	Polypropylene	Hot-dip-galv	anized steel										
	Paint color shade	Munsell blue 8B 4.5/3.25	_											
	Corrosion class	-	C3 (medium)	according to I	SO/EN 12944-	5								
Stator winding	Material	Copper												
	Insulation	Class F	_											
	Winding protection	Optional	3 PTC thermistors, 150 °C					3 PTC therr	nistors, 155 °C					
Balancing method		Half-key balancing												
Keyway		Closed keyway						Open keyw	ay					
Drain holes		Standard, open on deliver	У											
Enclosure		IP 55, higher protection	IP 55											
		on request												
Cooling method		IC 411												

<sup>\*</sup> Insulated bearing at N-end as standard

<sup>\*\*</sup> For detailed information on connections, see Terminal box alternatives section.

<sup>\*\*\*</sup> Terminals for connection with cable lugs (lugs not included in the delivery).

## For your notes

## Total product offering

# Motors, generators and mechanical power transmission products with a complete portfolio of services

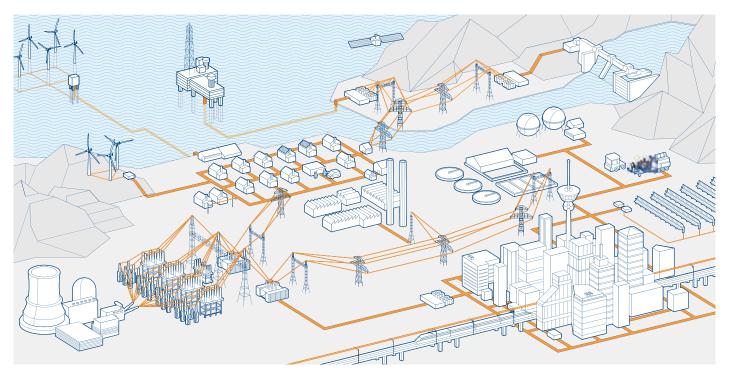


ABB is the leading manufacturer of low, medium and high voltage motors and generators, and mechanical power transmission products. ABB products are backed by a complete portfolio of services. Our in-depth knowledge of virtually every type of industrial process ensures we always specify the best solution for your needs.

#### Low and high voltage IEC induction motors

- Process performance motors
- General performance motors
- High voltage cast iron motors
- Induction modular motors
- Slip-ring modular motors
- Synchronous reluctance motors

#### Low and medium voltage NEMA motors

- Steel frame open drip proof (ODP) motors
- Weather protected, water cooled, fan ventilated
- Cast iron frame (TEFC)
- Air to air cooled (TEAAC) motors

#### Motors and generators for explosive atmospheres

- IEC and NEMA motors and generators, for all protection types
- > Synchronous motors

#### > Synchronous generators

- Synchronous generators for diesel and gas engines
- Synchronous generators for steam and gas turbines

#### > Wind power generators

#### > Generators for small hydro

#### > Other motors and generators

- Brake motors
- DC motors and generators
- Gear motors
- Marine motors and generators
- Single phase motors
- Motors for high ambient temperatures
- Permanent magnet motors and generators
- High speed motors
- Smoke extraction motors

- Wash down motors
- Water cooled motors
- Generator sets
- Roller table motors
- Low inertia motors
- Traction motors and generators

#### > Life cycle services

- Installation and commissioning
- Spares and consumables
- Preventive maintenance
- Predictive maintenance
- Condition monitoring
- On-site and workshop
- Remote troubleshooting
- Technical support
- Engineering and consulting
- Extensions, upgrades and retrofits
- Replacements
- Training
- Service agreements
- Mechanical power transmission components, bearings, gearings

## Life cycle services and support From pre-purchase to migration and upgrades

ABB offers a complete portfolio of services to ensure trouble-free operation and long product lifetimes. These services cover the entire life cycle. Local support is provided through a global network of ABB service centers and certified partners.

#### Pre-purchase

ABB's front-end sales organization can help customers to quickly and efficiently select, configure and optimize the right motor or generator for their application.

#### Installation and commissioning

Professional installation and commissioning by ABB's certified engineers represent an investment in availability and reliability over the entire life cycle.

#### Engineering and consulting

ABB's experts provide energy efficiency and reliability appraisals, advanced condition and performance assessments and technical studies.

#### Condition monitoring and diagnosis

Unique services collect and analyze data to provide early warnings of problems before failures can occur. All critical areas of the equipment are covered.

#### Maintenance and field services

ABB offers life cycle management plans and preventive maintenance products. The recommended four-level maintenance program covers the entire product lifetime.

#### Spare parts

Spare parts and support are offered throughout the life cycle of ABB products. In addition to individual spares, tailored spare part packages are also available.

#### Repair and refurbishment

Support for all ABB motors and generators and other brands is provided by ABB's global service organization. Specialist teams can also deliver emergency support.

#### Migration and upgrades

Life cycle audits determine the optimum upgrades and migration paths. Upgrades range from individual components to direct replacement motors and generators.

#### **Training**

Product and service training courses take a practical approach. The training ranges from standard courses to specially tailored programs to suit customer requirements.

#### Specialized support

Specialized support is offered through ABB's global service organization. Local units provide major and minor repairs as well as overhauls and reconditioning.

#### Service contracts

Service contracts are tailored to the customer's needs. The contracts combine ABB's entire service portfolio and 120 years of experience to deploy the optimal service practices.



### Contact us

www.abb.com/motors&generators

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